# Polymorphic Types in Functional Logic Programming* 

J.C. González-Moreno<br>M.T. Hortalá-González<br>M. Rodríguez-Artalejo<br>Dpto. Sistemas Informáticos y Programación<br>UCM, Madrid<br>jcmoreno@ei.uvigo.es<br>\{teresa,mario\}@sip.ucm.es

13 July 2001


#### Abstract

The rewriting logic CRWL has been proposed as a semantic framework for higher-order functional logic programming, using applicative rewriting systems as programs and lazy narrowing as the goal solving procedure. We present an extension of CRWL with a polymorphic type system, and we investigate the consequences of type discipline both at the semantic level and at the operational level. Semantically, models must be extended to incorporate a type universe. Operationally, lazy narrowing must maintain suitable type information in goals, in order to guarantee well-typed computed answers.


[^0]
## 1 Introduction

Research on functional logic programming (FLP, for short) has been pursued for longer than ten years, aiming at the integration of the best features of functional programming (FP) and logic programming (LP). In this paper, we investigate the integration of two fundamental characteristics: logical semantics, mainly developed in the LP field, and type discipline, best understood in FP languages. Regarding the FP side, we restrict our attention to nonstrict languages such as Haskell [43], whose advantages from the viewpoint of declarative programming are widely recognized. Thanks to lazy evaluation, functions in a non-strict language can sometimes return a result even if the values of some arguments are not known, or known only partially, and the semantic values intended for some expressions can be infinite objects. In the rest of the paper, "FP" must be understood as "non-strict FP".

Logical semantics characterizes the meaning of a pure logic program $\mathcal{P}$ (a set of definite Horn clauses) as its least Herbrand model, represented by the set of all the atomic formulas that are logical consequences of $\mathcal{P}$ in Horn logic [2, 14, 3]. Disregarding those proposals without a clear semantic basis, most early approaches to the integration of FP and LP, as e.g. [28, $16,26]$ were based on the idea of adding equations to LP languages. This approach is appealing because equational logic is simple, well-known and widely applicable. Equational logic captures LP by representing Horn clauses as a particular kind of conditional equations, and it seems to capture also FP by viewing functional programs as sets of oriented equations, also known as term rewriting systems (shortly, TRSs) [10, 30, 6]. Certainly, term rewriting serves as an operational model for FP, but in spite of this equational logic does not provide a logical semantics for FP programs. In general, the set of all equations that are logical consequences of a functional program in equational logic do not characterize the meaning of the program. As a simple example, let $\mathcal{P}$ be the FP program consisting of the following two equations:

```
repeat1(X) \approx [X|repeat1(X)]
repeat2(X) }\approx[X,X|repeat2(X)
```

Here $[\mathrm{X} \mid \mathrm{Xs}$ ] represents a list with head X and tail Xs , and the notation [X,X|repeat2(X)] abbreviates [X|[X|repeat2(X)]]. In a non-strict FP language, it is understood that the expressions repeat1 ( 0 ) and repeat2 ( 0 ) have the same meaning, namely an infinite list formed by repeated occurrences of 0 . If equational logic would characterize the meaning of $\mathcal{P}$, both
expressions should be interchangeable for the purposes of equational deduction, which is not the case. In particular, repeat1 ( 0 ) $\approx$ repeat2 ( 0 ) cannot be deduced from $\mathcal{P}$ in equational logic.

In contrast to the failure of equational logic, denotational semantics [21] is able to characterize the meaning of functional programs. In our example, the common meaning of repeat1 ( 0 ) and repeat2( 0 ) is the limit of a sequence of partially defined lists with increasing information, built with the help of a special symbol $\perp$ which represents an undefined value:

$$
\perp \sqsupseteq[0 \mid \perp] \sqsupseteq[0,0 \mid \perp] \sqsupseteq[0,0,0 \mid \perp] \sqsupseteq \cdots
$$

Borrowing ideas from denotational semantics, [19] proposed a rewriting logic CRWL to characterize the logical meaning of higher-order FP and FLP programs. The main results in [19] are existence of least Herbrand models for all programs, in analogy to the LP case, as well as soundness and completeness of a lazy narrowing calculus CLNC for goal solving. No type discipline was considered.

Regarding type discipline, most functional languages use Milner's type system [35, 9], which helps to avoid errors and to write more readable programs. This system has two crucial properties. Firstly, "well-typed programs don't go wrong", i.e., it is guaranteed that no type errors will occur during program execution, without any need of dynamic type checking at run time. Secondly, types are polymorphic, because they include type variables with a universal reading, standing for any type. For instance, a function to compute the length of a list admits the polymorphic type $[\alpha] \rightarrow$ int, meaning that it will work for a list of values of any type $\alpha$. Polymorphism promotes genericity of programs.

Type discipline in LP $[12,34]$ is not as well understood as in FP. Often one finds a distinction between the so-called descriptive and prescriptive views of types. The descriptive approach is applied to originally untyped programs, and views types a posteriori as approximations (usually regular supersets) of the success sets of predicates. On the contrary, the prescriptive approach views types a priori as imposing a restriction to the semantics of a program, so that predicates only accept arguments of the prescribed types. Usually, the prescriptive view leads to explicit type annotations in programs.

In our opinion, polymorphic type systems in Milner's style are also a good choice for LP and FLP languages. Types in Milner's type system have both a prescriptive and a descriptive rôle. More precisely, a type $\tau_{1} \rightarrow \tau$ for a
function $f$ prescribes an argument of type $\tau_{1}$ and describes a result of type $\tau$, which is guaranteed as long as the prescription for the argument is obeyed. The prescriptive part is in fact imposed, since an expression $f(e)$ is rejected at compile time if $e$ has not type $\tau_{1}$, in spite of the fact that $f(e)$ might happen to have a well defined value of type $\tau$ for some $e$ that has not type $\tau_{1}$. Mixing the prescriptive and descriptive views is also useful to understand some type systems for LP, where different types can be assigned to different modes of use of the same predicate. For each particular mode of use, one can think of a type prescription for the input arguments and a type description for the output arguments.

In the past, polymorphic type systems have been proposed for Prolog programs [39, 23, 22], for equational logic programs [24] and for higher-order logic programs in the language $\lambda$-Prolog [40, 41, 31]. Exactly as in Milner's original system, the aim of [39] was to guarantee that "well-typed programs don't go wrong" without any type checking at run time. On the contrary, the type systems in $[23,22,24,41,31]$ can accept a wider class of well-typed programs, but type computations at run time are needed.

Currently, polymorphic type systems are supported by existing FLP languages such as Curry [13] and $\mathcal{T O Y}$ [32]. In the case of $\mathcal{T O} \mathcal{Y}$, no dynamic type checking is performed by the current implementation. As a consequence, absence of type errors at run time is guaranteed for purely functional computations, but not for more complicated computations involving higher-order logic variables.

The present paper is a thoroughly revised, corrected and extended version of [20]. It is intended as a contribution to a better understanding of polymorphic type discipline in FLP languages with a logical semantics. Starting from the results in [19], we extend the rewriting logic CRWL and the narrowing calculus CLNC with a polymorphic type system, and we investigate the consequences of type discipline both at the semantic level and at the operational level. At the semantic level, we modify the models from [19] to incorporate a type universe. However, we do not require programs to be well-typed in order to be regarded as meaningful. Every program $\mathcal{P}$ has a logical meaning given by a least Herbrand model, which is well-behaved w.r.t. types in the case that $\mathcal{P}$ is well-typed. At the operational level, we modify CLNC to include some type information in goals. More precisely, a type environment assigning types to variables is maintained within each goal. The modified narrowing calculus is designed to be sound and complete in a reasonable sense w.r.t. the computation of well-typed solutions. Moreover, dynamic type checking
takes place only at those computation steps where some logic variable which is acting as a function becomes bound.

The rest of the paper is organized as follows. In Section 2 we introduce Higher-Order (shortly, HO) FLP programs as a special kind of applicative TRSs, as well as a polymorphic type system. In Section 3 we give all the constructions and results concerning the logical semantics of well-typed programs, including all the proofs that were omitted in [20], as well as new examples. In Section 4 we present the lazy narrowing calculus CLNC, showing by means of detailed examples that all the type checking mechanisms embodied in the calculus are really needed. The soundness and completeness of CLNC are presented in a revised formulation w.r.t. [20], and the proofs which were missing in [20] are now provided. All along the paper we include some succint comparison to related work. We summarize our conclusions in the final Section 5 and we collect most of the technical proofs in an Appendix.

## 2 Programming with Applicative Rewrite Systems

### 2.1 Types and Expressions

Since we are interested in HO FLP languages with a type discipline, we need a suitable syntax to represent types and expressions of any type. To introduce types, we assume a countable set TVar of type variables $\alpha, \beta, \ldots$ and a countable ranked alphabet $T C=\bigcup_{n \in \mathbb{N}} T C^{n}$ of type constructors $C$. Types $\tau \in$ Type are built as

$$
\tau::=\alpha(\alpha \in T V a r)\left|\left(C \tau_{1} \ldots \tau_{n}\right) \quad\left(C \in T C^{n}\right)\right|\left(\tau \rightarrow \tau^{\prime}\right)
$$

Types without any occurrence of $\rightarrow$ are called datatypes. By convention, $C \bar{\tau}_{n}$ abbreviates $\left(C \tau_{1} \ldots \tau_{n}\right)$, " $\rightarrow$ " associates to the right, and $\bar{\tau}_{n} \rightarrow \tau$ abbreviates $\tau_{1} \rightarrow \cdots \rightarrow \tau_{n} \rightarrow \tau$. The set of type variables occurring in $\tau$ is written $\operatorname{tvar}(\tau)$. A type $\tau$ is called monomorphic iff $\operatorname{tvar}(\tau)=\emptyset$, and polymorphic otherwise.

A polymorphic signature over $T C$ is a triple $\Sigma=\langle T C, D C, F S\rangle$, where $D C=\bigcup_{n \in \mathbb{N}} D C^{n}$ resp. $F S=\bigcup_{n \in \mathbb{N}} F S^{n}$ are ranked sets of data constructors resp. defined function symbols. Moreover, each $c \in D C^{n}$ comes with a type declaration $c:: \bar{\tau}_{n} \rightarrow C \bar{\alpha}_{k}$, where $n, k \geq 0, \alpha_{1}, \ldots, \alpha_{k}$ are pairwise different,
$\tau_{i}$ are datatypes, and $\operatorname{tvar}\left(\tau_{i}\right) \subseteq\left\{\alpha_{1}, \ldots, \alpha_{k}\right\}$ for all $1 \leq i \leq n$ (so-called transparency property). Also, every $f \in F S^{n}$ comes with a type declaration $f:: \bar{\tau}_{n} \rightarrow \tau$, where $\tau_{i}, \tau$ are arbitrary types.

As we will see later on, functions $f \in F S^{n}$ must be defined by means of rewrite rules with $n$ formal parameters. Moreover, the types declared in a signature for data constructors and defined functions are the principal or most general ones, which can be instantiated to more particular types (possibly involving " $\rightarrow$ ") for different uses of the constructor or function. Note that the principal types of data constructors must respect the transparency property and the additional restriction requiring the principal types of arguments to be datatypes. As we will see, transparency is essential for our results. The additional restriction is not imposed by current FP [43] or FLP $[13,32]$ languages, and we have not checked whether our results remain valid when dropping it. However, we believe that this restriction is not a severe limitation for practical programming; see Example 1 below.

In the sequel, we use the notation $(h:: \tau) \in_{\text {var }} \Sigma$ to indicate that $\Sigma$ includes the type declaration $h:: \tau$ up to a renaming of type variables. For any signature $\Sigma$, we write $\Sigma_{\perp}$ for the result of extending $\Sigma$ with a new data constructor $\perp:: \alpha$, intended to represent an undefined value that belongs to every type. As notational conventions, we use $c, d \in D C, f, g \in F S$ and $h \in D C \cup F S$, and we define the arity of $h \in D C^{n} \cup F S^{n}$ as $\operatorname{ar}(h)=n$. In the sequel, we always suppose a given signature $\Sigma$, which will not always appear explicitly in our notation. Assuming a countable set DVar of data variables $X, Y, \ldots$ (disjoint with TVar), partial expressions $e \in E x p_{\perp}$ are defined as follows:

$$
e::=X \quad(X \in D V a r)|\perp| h(h \in D C \cup F S) \mid\left(e e_{1}\right)
$$

These expressions are usually called applicative, because ( $e e_{1}$ ) stands for the application operation (represented as juxtaposition) which applies the function denoted by $e$ to the argument denoted by $e_{1}$. First-order (shortly, FO) expressions can be translated to applicative expressions by means of so-called curried notation. For instance, $f(X, g(Y))$ becomes $(f X(g Y))$. The set of data variables occurring in $e$ is written $\operatorname{var}(e)$. An expression $e$ is called closed iff $\operatorname{var}(e)=\emptyset$, and open otherwise. An expression $e$ is called linear iff every $X \in \operatorname{var}(e)$ has one single occurrence in $e$. Following a usual convention, we assume that application associates to the left, and we use the notation $e \bar{e}_{n}$ to abbreviate $e e_{1} \ldots e_{n}$. Expressions $e \in \operatorname{Exp}$ without
occurrences of $\perp$ are called total. Two important subclasses of expressions are partial data terms $t \in \operatorname{Term}_{\perp}$, defined as

$$
t::=X \quad(X \in D \operatorname{Var})|\perp|\left(c \bar{t}_{n}\right) \quad\left(c \in D C^{n}\right)
$$

and partial patterns $t \in P a t_{\perp}$, defined as:

$$
\begin{aligned}
t::= & X(X \in D V a r)|\perp|\left(c \bar{t}_{m}\right) \quad\left(c \in D C^{n}, m \leq n\right) \mid \\
& \left(f \bar{t}_{m}\right)\left(f \in F S^{n}, m<n\right)
\end{aligned}
$$

Note that expressions ( $f \bar{t}_{m}$ ) with $f \in F S^{n}$ and $m \geq n$ are not allowed as patterns, because they are potentially reducible using rewrite rules for $f$. Total data terms $t \in$ Term and total patterns $t \in$ Pat are defined analogously, but omitting $\perp$. Note that $T e r m_{\perp} \subset P a t_{\perp} \subset E x p_{\perp}$. As usual in FP, data terms are used to represent data values. Patterns generalize data terms and can be used as an intensional representation of functions, as we will see in Subsection 2.3.

Most functional languages allow also $\lambda$-abstractions of the form $\lambda X$.e to represent functions. Some approaches to HO FLP also permit $\lambda$-abstractions, see e.g. [25, 46, 48, 33]. In spite of some known decidability results for particular cases, in general $\lambda$-abstractions can give rise to undecidable unification problems [17]. We restrict ourselves to $\lambda$-free applicative expressions, which are expressive enough for most programming purposes.

The next example illustrates some of the notions introduced so far.

## Example 1 (Polymorphic Signature)

Let us consider a polymorphic signature with $T C^{0}=\{$ bool, nat $\}, T C^{1}=$ $\{$ list $\}, T C^{2}=\{\mathrm{sum}\}, D C^{0}=\{$ true, false, $\mathrm{z}, \mathrm{nil}\}, D C^{1}=\{\mathrm{s}, \mathrm{l}, \mathrm{rs}\}$, $D C^{2}=\{$ cons $\}, F S^{0}=\{$ one $\}, F S^{1}=\{$ not, negate, head, tail, unpack, wild, extend, pp, p\}, $F S^{2}=\{$ and, or, plus, map, snd, twice, $(++)\}, F S^{3}=$ \{third, split\} and with the following type declarations:

```
true, false :: bool
cons :: \alpha -> list \alpha -> list }
negate :: list bool }->\mathrm{ list bool
tail, extend :: list }\alpha->\mathrm{ list }
and, or :: bool }->\mathrm{ bool }->\mathrm{ bool
plus :: nat }->\mathrm{ nat }->\mathrm{ nat
map :: (\alpha }->\beta)->\mathrm{ list }\alpha->\mathrm{ list }
```

```
z, one :: nat
nil :: list }
s :: nat }->\mathrm{ nat
not :: bool }->\mathrm{ bool
head :: list }\alpha->
p, pp :: nat }->\mathrm{ bool
wild :: \alpha }->
```

```
(++) :: list }\alpha->\mathrm{ list }\alpha->\mathrm{ list }\alpha\quad\mathrm{ snd :: }\alpha->\beta->
twice :: ( }\alpha->\alpha)->\alpha->\alpha ls ::\alpha 偣 sum \alpha
```



```
split :: list }\alpha->\mathrm{ list }\alpha->\mathrm{ list }\alpha->\mathrm{ bool
unpack :: ( }\beta->\beta)->
```

Then, we can build data terms such as (s X), (cons (s X) (cons Ynil)); patterns such as (plus z), ( snd X), (twice twice), (twice (plus X)); and expressions, like (map (plus X) (cons (s X) nil)), (twice (plus X) Y). And we can also build the type list (sum ( $\alpha \rightarrow$ bool) $\alpha$ ), for lists whose elements can represent either values of type $\alpha$ or boolean functions over such values.

In the sequel, we use Prolog notation for the list constructors, writing [] for nil and [X|Xs] for cons XXs. We also write $[\alpha]$ for the type list $\alpha$. In concrete examples, we sometimes use infix notation for other constructors and function symbols, writing e.g. Xs ++ Ys instead of (++) Xs Ys.

The following classification of expressions is useful: $X \bar{e}_{m}$, with $X \in D V a r$ and $m \geq 0$, is called a flexible expression, while $h \bar{e}_{m}$ with $h \in D C \cup F S$ is called a rigid expression. Moreover, a rigid expression is called active iff $h \in F S$ and $m \geq \operatorname{ar}(h)$, and passive otherwise. Note that any pattern is either a variable or a passive rigid expression. As we will see in Subsection 3.1, outermost reduction makes sense only for active rigid expressions.

Following the spirit of denotational semantics [21], we view $P a t_{\perp}$ as the set of finite elements of a semantic domain, and we define the approximation ordering $\sqsupseteq$ as the least partial ordering over $P a t_{\perp}$ satisfying the following properties: $\perp \sqsupseteq t$, for all $t \in P a t_{\perp} ; X \sqsupseteq X$, for all $X \in D \operatorname{Var}$; and $h \bar{t}_{m} \sqsupseteq h \bar{s}_{m}$ whenever these two expressions are patterns and $t_{i} \sqsupseteq s_{i}$ for all $1 \leq i \leq$ $m$. $P a t_{\perp}$, and more generally any partially ordered set (shortly, poset), can be converted into a semantic domain by means of a technique called ideal completion; see e.g. [37]. Our semantics in Section 3 will be based on posets.

As usual, we define type substitutions $\sigma_{t} \in T S u b$ as mappings $\sigma_{t}: T V a r \rightarrow$ Type extended to $\sigma_{t}:$ Type $\rightarrow$ Type in the natural way. Similarly, we consider partial data substitutions $\sigma_{d} \in D S u b_{\perp}$ given by mappings $\sigma_{d}: D V a r \rightarrow P a t_{\perp}$, total data substitutions $\sigma_{d} \in D S u b$ given by mappings $\sigma_{d}: D V a r \rightarrow P a t$, and substitutions given as pairs $\sigma=\left(\sigma_{t}, \sigma_{d}\right)$. By convention, we write $\tau \sigma_{t}$ instead of $\sigma_{t}(\tau)$, and $\theta_{t} \sigma_{t}$ for the composition of $\theta_{t}$ and $\sigma_{t}$, such that $\tau\left(\theta_{t} \sigma_{t}\right)=\left(\tau \theta_{t}\right) \sigma_{t}$ for any $\tau$. We define the domain $\operatorname{dom}\left(\sigma_{t}\right)$ as the set of all type variables $\alpha$ such that $\sigma_{t}(\alpha) \neq \alpha$, and the range $\operatorname{ran}\left(\sigma_{t}\right)$ as $\bigcup_{\alpha \in \operatorname{dom}\left(\sigma_{t}\right)} \operatorname{tvar}\left(\sigma_{t}(\alpha)\right)$. For any
subset $A \subseteq \operatorname{dom}\left(\sigma_{t}\right)$ we define the restriction $\sigma_{t} \upharpoonright A$ as the type substitution $\sigma_{t}^{\prime}$ such that $\operatorname{dom}\left(\sigma_{t}^{\prime}\right)=A$ and $\sigma_{t}^{\prime}(\alpha)=\sigma_{t}(\alpha)$ for all $\alpha \in A$. Similar notions can be defined for data substitutions. the identity substitution $i d=\left(i d_{t}, i d_{d}\right)$ is such that $i d_{t}(\alpha)=\alpha$ for all $\alpha \in T \operatorname{Var}$ and $i d_{d}(X)=X$ for all $X \in D \operatorname{Var}$.

The subsumption ordering over Type is defined by the condition $\tau \leq \tau^{\prime}$ iff $\tau^{\prime}=\tau \sigma_{t}$ for some $\sigma_{t} \in T S u b$. A similar ordering can be defined over $E x p_{\perp}$, and extended to work over $D S u b_{\perp}$ by defining $\theta_{d} \leq \theta_{d}^{\prime}$ iff $\theta_{d}^{\prime}=\theta_{d} \sigma_{d}$ for some $\sigma_{d} \in D S u b_{\perp}$. For any set of data variables $\mathcal{X}$, we use the notations $\theta_{d} \leq \theta_{d}^{\prime}[\mathcal{X}]$ (resp. $\left.\theta_{d} \leq \theta_{d}^{\prime}[\backslash \mathcal{X}]\right)$ to indicate that $X \theta_{d}^{\prime}=X \theta_{d} \sigma_{d}$ holds for some $\sigma_{d} \in D S u b_{\perp}$ and all $X \in \mathcal{X}$ (resp. all $X \notin \mathcal{X}$ ). The subsumption ordering over Type also induces a subsumption ordering over TSub. Finally, let us mention the approximation ordering over $D S u b_{\perp}$, defined by the condition $\sigma_{d} \sqsupseteq \sigma_{d}^{\prime}$ iff $\sigma_{d}(X) \sqsupseteq \sigma_{d}^{\prime}(X)$, for all $X \in D V a r$.

### 2.2 Well-typed Expressions

Inspired by Milner's type system [35, 9] and by various approaches to type systems for LP [12, 34], we now introduce the notion of well-typed expression. We define a type environment as any set $T$ of type assumptions $X:: \tau$ for data variables, such that $T$ does not include two different assumptions for the same variable. The domain $\operatorname{dom}(T)$ and the range $\operatorname{ran}(T)$ of a type environment are the set of all data variables resp. type variables that occur in $T$. For any variable $X \in \operatorname{dom}(T)$, the unique type $\tau$ such that $(X:: \tau) \in T$ is noted as $T(X)$. Given $\sigma_{t} \in T S u b$, we define $T \sigma_{t}$ as the type environment $T^{\prime}$ such that $\operatorname{dom}\left(T^{\prime}\right)=\operatorname{dom}(T)$ and $T^{\prime}(X)=T(X) \sigma_{t}$ for all $X \in \operatorname{dom}(T)$. We write $T \leq T^{\prime}$ iff $T^{\prime}=T \sigma_{t}$ for some $\sigma_{t} \in$ TSub. Type judgements $T \vdash_{W T} e ~:: \tau$ are derived by means of the following type inference rules:

VR $T \vdash_{W T} X:: \tau$, if $T(X)=\tau$.
ID $T \vdash_{W T} h:: \tau \sigma_{t}$, if $(h:: \tau) \in_{v a r} \Sigma_{\perp}$ and $\sigma_{t} \in T S u b$.
AP $T \vdash_{W T}\left(e e_{1}\right):: \tau$, if $T \vdash_{W T} e::\left(\tau_{1} \rightarrow \tau\right)$ and $T \vdash_{W T} e_{1}:: \tau_{1}$, for some $\tau_{1}$.

Note that the rule ID reflects the implicit universal quantification of type variables in the types of data constructors and defined functions. On the contrary, the rule VR treats the types of data variables as fixed by the
current type environment. This corresponds to the distinction between letbound and $\lambda$-bound identifiers in the classical presentation of polymorphic type inference [35, 9].

An expression $e \in E x p_{\perp}$ is called well-typed in a type environment $T$ iff there exists some type $\tau$ such that $T \vdash_{W T} e:: \tau$. Expressions that admit more than one type in $T$ are called polymorphic. A well-typed expression always admits a so-called principal type that is more general than any other. Adapting ideas from [35, 9], we define a type reconstruction algorithm $T R$ to compute principal types. Assume an expression $e$ and a type environment $T$ such that $\operatorname{var}(e) \subseteq \operatorname{dom}(T)$. Then $T R(T, e)$ returns a pair of the form $\left(e^{\tau}, E\right)$ where $e^{\tau}$ is a type annotation of $e$ and $E$ is a system of equations between types, expressing most general conditions for $\tau$ to be a valid type of $e$. The algorithm $T R$ works by structural recursion on $e$ :

VR $\operatorname{TR}(T, X)=\left(X^{\tau}, \emptyset\right)$, if $T(X)=\tau$.
ID $\quad T R(T, h)=\left(h^{\tau}, \emptyset\right)$, if $(h:: \tau) \in_{\text {var }} \Sigma_{\perp}$ is a fresh variant of $h$ 's type declaration.

AP $\quad T R\left(T,\left(e e_{1}\right)\right)=\left(\left(e^{\tau_{1} \rightarrow \gamma} e_{1}^{\tau_{1}}\right)^{\gamma}, E \cup E_{1} \cup\left\{\tau \approx \tau_{1} \rightarrow \gamma\right\}\right)$, if $T R(T, e)=$ $\left(e^{\tau}, E\right), \quad T R\left(T, e_{1}\right)=\left(e_{1}^{\tau_{1}}, E_{1}\right), \operatorname{tvar}(E) \cap \operatorname{tvar}\left(E_{1}\right) \subseteq \operatorname{ran}(T), \gamma \notin$ $\operatorname{tvar}(E) \cup \operatorname{tvar}\left(E_{1}\right)$ is a fresh type variable.

Type-annotated expressions, as those returned by $T R$, have the following syntax:

$$
\begin{aligned}
e^{\tau}::= & X^{\tau} \quad(X \in D \operatorname{Var}, \tau \in \text { Type }) \mid \\
& h^{\tau \sigma_{t}}\left(h:: \tau \in_{\text {var }} \Sigma_{\perp}, \sigma_{t} \in T S u b\right) \mid\left(e^{\tau_{1} \rightarrow \tau} e_{1}^{\tau_{1}}\right)^{\tau}
\end{aligned}
$$

Implicitly, we are assuming that a type-annotated expression never includes two different annotations for the same variable. In the sequel we often abbreviate type annotations by omitting some intermediate types. In particular, we write $\left(e^{\bar{\tau}_{n} \rightarrow \tau} \bar{e}_{n}^{\bar{\tau}_{n}}\right)^{\tau}$, or even more simply ( $e^{\bar{\tau}_{n} \rightarrow \tau} \bar{e}_{n}^{\bar{\tau}_{n}}$ ), to abbreviate a full type annotation of an expression of the form $\left(e \bar{e}_{n}\right)$. The following lemma says that type-annotated expressions correspond to the derivation of type judgements in a natural way. The straightforward proof is omitted.

## Lemma 1 (Type Annotation vs. Type Derivation)

Given a type-annotated expression $e^{\tau}$, let $e$ be the expression obtained from $e^{\tau}$ by erasing all type annotations, and let $T$ be the implicit type environment
of $e^{\tau}$, which consists of all the type assumptions $X:: \tau$ such that $X^{\tau}$ occurs as a part of $e^{\tau}$. Then $T \vdash_{W T} e:: \tau$. Reciprocally, whenever $T \vdash_{W T} e:: \tau$, there is some type annotation $e^{\tau}$ of e whose implicit type environment is $T$.

The algorithm $T R$ also returns a system $E$ of equations between types. By definition, its set of solutions $\operatorname{TSol}(E)$ consists of all $\sigma_{t} \in T S u b$ such that $\tau \sigma_{t}=\tau^{\prime} \sigma_{t}$ for all $\tau \approx \tau^{\prime} \in E$. If $E$ is solvable (i.e., $T S o l(E) \neq \emptyset$ ), a most general solution $\operatorname{mgu}(E)=\sigma_{t} \in \operatorname{TSol}(E)$ can be computed by means of Robinson's unification algorithm (see e.g. [2]). The key properties of the type reconstruction algorithm are given by the next theorem, whose proof can be found in the Appendix.

## Theorem 1 (Type Reconstruction)

Assume $\operatorname{TR}(T, e)=\left(e^{\tau}, E\right)$. Then:

1. For every $\sigma_{t} \in T S o l(E): T \sigma_{t} \vdash_{W T} e:: \tau \sigma_{t}$.
2. Reciprocally: if $T \leq T^{\prime}$ and $\tau^{\prime} \in T y p e$ are such that $T^{\prime} \vdash_{W T} e:: \tau^{\prime}$, then there exists $\sigma_{t} \in \operatorname{TSol}(E)$ such that $T \sigma_{t}=T^{\prime}$ and $e^{\tau} \sigma_{t}=e^{\tau^{\prime}}$.

Assuming $T R(T, e)=\left(e^{\tau}, E\right)$ with solvable $E$, and $\sigma_{t}=m g u(E)$, we write $P T(T, e)=\tau \sigma_{t}$ for the principal type of $e$ w.r.t. $T$, and $P A(T, e)=e^{\tau} \sigma_{t}$ for the principal type annotation of $e$ w.r.t. $T$. Here, $e^{\tau} \sigma_{t}$ is meant as the result of applying $\sigma_{t}$ to all the type annotations occurring within $e^{\tau}$. In particular, the outermost type annotation in $e^{\tau} \sigma_{t}$ is $\tau \sigma_{t}$.

In order to compute a principal type for an expression $e$ with $\operatorname{var}(e)=$ $\left\{X_{1}, \ldots, X_{n}\right\}$ one can invoke $T R(T, e)$ with $T=\left\{X_{1}:: \alpha_{1}, \ldots, X_{n}:: \alpha_{n}\right\}$, where $\alpha_{i}$ are $n$ pairwise different type variables. All the expressions from Example 1 are well-typed in suitable environments, and some of them have a polymorphic principal type. For instance, twice twice is well-typed in the empty environment. Moreover, $P A(\emptyset$, twice twice) can be computed as
(twice ${ }^{((\alpha \rightarrow \alpha) \rightarrow \alpha \rightarrow \alpha) \rightarrow(\alpha \rightarrow \alpha) \rightarrow \alpha \rightarrow \alpha}$ twice $\left.{ }^{(\alpha \rightarrow \alpha) \rightarrow \alpha \rightarrow \alpha}\right)^{(\alpha \rightarrow \alpha) \rightarrow \alpha \rightarrow \alpha}$
The following three lemmata state some technically useful properties of type inference. Proofs are given in the Appendix.

## Lemma 2 (Typing Monotonicity)

 Then $T \vdash_{W T} t^{\prime}:: \tau$ holds also for every pattern $t^{\prime} \sqsupseteq t$.

## Lemma 3 (Well-typed Substitution)

Assume two type environments $T_{0}, T_{1}$, a partial expression e such that $T_{0} \vdash_{W T}$ $e:: \tau$, and a substitution $\sigma=\left(\sigma_{t}, \sigma_{d}\right)$ which is well-typed in the sense that $T_{1} \vdash_{W T} X \sigma_{d}:: T_{0}(X) \sigma_{t}$ for all $X \in \operatorname{var}(e)$. Then, it is also true that $T_{1} \vdash_{W T} e \sigma_{d}:: \tau \sigma_{t}$.

## Lemma 4 (Type Instantiation)

Assume $T \vdash_{W T} e:: \tau$. Then $T \sigma_{t} \vdash_{W T} e:: \tau \sigma_{t}$ holds for any substitution $\sigma_{t} \in T S u b$.

In fact, Lemma 4 is a particular case of Lemma 3. Moreover, Lemma 3 admits the following reformulation, which is helpful when working type annotations. A proof is also given in the Appendix.

## Lemma 5 (Well-typed Substitution in a Type-annotated Expression)

Assume a type-annotated expression $e^{\tau}$ and a substitution $\sigma=\left(\sigma_{t}, \sigma_{d}\right)$ which is well-typed in the sense that $X \sigma_{d}$ can be annotated with type $\tau_{0} \sigma_{t}$ for every type-annotated variable $X^{\tau_{0}}$ occurring in $e^{\tau}$. Then, $e^{\tau} \sigma$ is a type-annotated expression.

When applying Lemma 5 in the sequel, we often assume that $e^{\tau} \sigma$ has been built as a principal type annotation.

As part of the definition of polymorphic signatures we have required a transparency property for the principal types of data constructors. Due to transparency, the types of the variables occurring in a data term $t$ can be deduced from the type of $t$. It is useful to isolate those patterns that have a similar property. To this purpose, we define transparent patterns as

$$
\begin{aligned}
t::= & X(X \in D V a r)|\perp|\left(c \bar{t}_{m}\right)\left(c \in D C^{n}, m \leq n\right) \mid \\
& \left(f \bar{t}_{m}\right)\left(f \in F S^{n}, m<n\right)
\end{aligned}
$$

where the subpatterns $t_{i}$ in $\left(c \bar{t}_{m}\right)$ and $\left(f \bar{t}_{m}\right)$ must be recursively transparent, and the principal type of the defined function $f$ in $\left(f \bar{t}_{m}\right)$ must be of the form $\bar{\tau}_{m} \rightarrow \tau$ with $\operatorname{tvar}\left(\bar{\tau}_{m}\right) \subseteq \operatorname{tvar}(\tau)$.

In the sequel, we say that a type which can be written as $\bar{\tau}_{m} \rightarrow \tau$ fulfilling $\operatorname{tvar}\left(\bar{\tau}_{m}\right) \subseteq \operatorname{tvar}(\tau)$ is $m$-transparent, and a function symbol $f$ will be called $m$-transparent iff its principal type is $m$-transparent. Note that a data constructor $c$ is always $m$-transparent for all $m \leq \operatorname{ar}(c)$.

Types and patterns that are not transparent are called opaque. As a typical example of an opaque pattern, consider (snd X), whose principal type $(\beta \rightarrow \beta$ ) reveals no information on the type of X. Different instances of (snd $X$ ) actually keep the principal type ( $\beta \rightarrow \beta$ ), independently of the type of the expression substituted for X . The following transparency lemmata (proved in the Appendix) show that such a behaviour is not possible for transparent patterns.

## Lemma 6 (Transparency)

Assume a transparent pattern $t$ and two type environments $T_{1}, T_{2}$ such that $T_{1} \vdash_{W T} t:: \tau$ and $T_{2} \vdash_{W T} t:: \tau$, for a common type $\tau$. Then $T_{1}(X)=T_{2}(X)$ holds for every $X \in \operatorname{var}(t)$.

In the sequel, we sometimes use the notation $T \vdash_{W T} a:: \tau:: b$ to indicate that the expressions $a$ and $b$ have a common type $\tau$ in the type environment $T$.

## Lemma 7 (Transparent Decomposition)

Assume a m-transparent $h \in D C \cup F S$ such that $T \vdash_{W T} h \bar{a}_{m}:: \tau:: h \bar{b}_{m}$ holds for a common type $\tau$. Then, there exists types $\tau_{i}$ such that $T \vdash_{W T} a_{i}:: \tau_{i}:: b_{i}$ holds for all $1 \leq i \leq m$.

### 2.3 Programs

Following [19], we define CRWL programs as a special kind of applicative TRSs, but now requiring well-typedness. More precisely, assuming $f \in F S^{n}$ whose declared type (up to renaming of type variables) is of the form $f:$ : $\bar{\tau}_{n} \rightarrow \tau$, a well-typed defining rule for $f$ must have the following form:

where $l$ must be linear, $t_{i}$ must be transparent patterns, $r$ must be an expression such that $\operatorname{var}(r) \subseteq \operatorname{var}(l)$, the condition $C$ must consist of finitely many (possibly zero) so-called joinability statements $a \bowtie b$ where $a, b$ are expressions, and $T$ must be a type environment whose domain is the set of all data variables occurring in the rewrite rule, and such that: $T \vdash_{W T} t_{i}:: \tau_{i}$ for $1 \leq i \leq n, T \vdash_{W T} r:: \tau$ and $T \vdash_{W T} C::$ bool. The symbol $\perp$ never occurs in a defining rule. A well-typed CRWL program can be any set of well-typed
defining rules for different symbols $f \in F S$. Neither termination nor confluence is required. In particular, the lack of confluence means that CRWL programs can define non-deterministic functions, whose usefulness for FLP languages has been advocated in [18]. Hence, the restriction $\operatorname{var}(r) \subseteq \operatorname{var}(l)$ is not motivated by confluence, but needed for a type preservation result presented as Theorem 2 in Subsection 3.1.

The meaning of joinability statements will be explained in the next section. An additional explanation is needed to understand the previous definitions. In $T \vdash_{W T} C$ :: bool, we view $C$ as an "expression" built from symbols in the current signature $\Sigma$, plus the two additional "operations" $(\bowtie):: \alpha \rightarrow \alpha \rightarrow$ bool and $():,:$ bool $\rightarrow$ bool $\rightarrow$ bool, used in infix notation to build conditions.

Note that defining rules in a well-typed program are type-general and transparent, because they match exactly the principal type declared for the corresponding function and they use transparent patterns in their left-hand sides. The transparency of function definitions made no sense in [19], but it is important in a typed setting. We consider also untyped programs, which are sets of untyped defining rules where the type environment $T$ is missing. The restriction $\operatorname{var}(r) \subseteq \operatorname{var}(l)$ is not needed for untyped programs.

In practice, users of FP languages such as Haskell [43] or FLP languages such as $\mathcal{T O Y}$ [32] provide type declarations only for data constructors. In most practical cases, this allows an automatic inference of the principal types of defined function symbols, using a type reconstruction algorithm embedded into the language's implementation. Note, however, that our class of CRWL programs allows so-called polymorphic recursion. The typability problem is known to be undecidable for programs which use polymorphic recursion [29], and any implemented type reconstruction algorithm is bound to fail sometimes for such programs.

The next program, based on the signature from Example 1, will be useful as a basis for other examples in the rest of the paper. It consists of obviously well-typed definitions, except for the following three exceptions: the rewrite rule defining the function wild, which has extra variables in its right-hand side; the first rewrite rule defining the function extend, which is not typegeneral; and the rewrite rule defining the function unpack, which has an opaque pattern in its left-hand side.

## Example 2 (CRWL Program)

not :: bool $\rightarrow$ bool

```
not false }->\mathrm{ true }\Leftarrow\emptyset\square
not true }->\mathrm{ false }\Leftarrow\emptyset\square
or :: bool }->\mathrm{ bool }->\mathrm{ bool
or true X }->\mathrm{ true }\Leftarrow\emptyset\square{X :: bool
orfalse X }->\textrm{X}\Leftarrow\emptyset\square\square{X :: bool
negate :: [bool] -> [bool]
negate [] }->\mathrm{ [] & \ व Ø
negate [X|Xs] -> [not X|negate Xs] \Leftarrow\emptyset ם {X :: bool, Xs :: [bool]}
extend :: [\alpha] -> [\alpha]
extend [] }->\mathrm{ [z] & \ व Ø
extend [X|Xs] -> [X,X|Xs] \Leftarrow\emptyset 口 {X :: \alpha, Xs :: [\alpha]}
and :: bool }->\mathrm{ bool }->\mathrm{ bool
and true X }->\textrm{X}\Leftarrow\emptyset\square\square{\textrm{X}:: bool
and false X }->\mathrm{ false }\Leftarrow\emptyset 口 {X :: bool
head :: [\alpha] -> <
head [X|Xs] }->\textrm{X}\Leftarrow\emptyset\square{\textrm{X}:: \alpha,\textrm{Xs}:: [\alpha]
one :: nat
one }->\mathrm{ sz
tail :: [\alpha] -> [\alpha]
tail [X|Xs] }->\mathrm{ Xs }\Leftarrow\emptyset\square{\textrm{X}::\alpha,\textrm{Xs}::[\alpha]
plus :: nat }->\mathrm{ nat }->\mathrm{ nat
pluszY }->\textrm{Y}\Leftarrow\emptyset\square{Y :: nat
plus (sX) Y }->\mathrm{ s (plus XY) }\Leftarrow\emptyset\square\square{X,Y :: nat
unpack :: ( }\beta->\beta)->
unpack (snd X) }->\textrm{X}\Leftarrow\emptyset\square\square{\textrm{X}:: \alpha
wild :: \alpha -> \beta
wild X }->\textrm{Y}\Leftarrow\emptyset\square{\textrm{X}::\alpha,\textrm{Y}::\beta
```

```
p :: nat \(\rightarrow\) bool
\(\mathrm{p}(\mathrm{s} Y) \rightarrow\) true \(\Leftarrow \emptyset \square\{\mathrm{Y}::\) nat \(\}\)
pp :: nat \(\rightarrow\) bool
\(\mathrm{pp}(\mathrm{sX}) \rightarrow \mathrm{pX} \Leftarrow \emptyset \square\{\mathrm{X}::\) nat \(\}\)
map \(::(\alpha \rightarrow \beta) \rightarrow[\alpha] \rightarrow[\beta]\)
\(\operatorname{map} F[] \rightarrow[] \Leftarrow \emptyset \square\{F::(\alpha \rightarrow \beta)\}\)
\(\operatorname{map} F[X \mid X s] \rightarrow[F X \mid m a p ~ F s] \Leftarrow \emptyset\)
\(\{\mathrm{F}::(\alpha \rightarrow \beta), \mathrm{X}:: \alpha\), Xs :: [ \(\alpha]\}\)
snd \(:: \alpha \rightarrow \beta \rightarrow \beta\)
\(\operatorname{snd} \mathrm{X} \mathrm{Y} \rightarrow \mathrm{Y} \Leftarrow \emptyset \square\{\mathrm{X}:: \alpha, \mathrm{Y}:: \beta\}\)
twice :: \((\alpha \rightarrow \alpha) \rightarrow \alpha \rightarrow \alpha\)
twice \(\mathrm{FX} \rightarrow \mathrm{F}(\mathrm{FX}) \Leftarrow \emptyset \quad\) ■ \(\{\mathrm{F}::(\alpha \rightarrow \alpha), \mathrm{X}:: \alpha\}\)
\((++)::[\alpha] \rightarrow[\alpha] \rightarrow[\alpha]\)
[]\(++\) Ys \(\rightarrow\) Ys \(\Leftarrow \emptyset\) 口 \(\{\) Ys :: \([\alpha]\}\)
\([\mathrm{X} \mid \mathrm{Xs}]++\mathrm{Ys} \rightarrow[\mathrm{X} \mid \mathrm{Xs}++\mathrm{Ys}] \Leftarrow \emptyset \square\{\mathrm{X}:: \alpha\), Xs, Ys :: \([\alpha]\}\)
third \(:: \alpha \rightarrow \beta \rightarrow \gamma \rightarrow \gamma\)
third \(\mathrm{XYZ} \rightarrow \mathrm{Z} \Leftarrow \emptyset \square\{\mathrm{X}:: \alpha, \mathrm{Y}:: \beta, \mathrm{Z}:: \gamma\}\)
split :: \([\alpha] \rightarrow[\alpha] \rightarrow[\alpha] \rightarrow\) bool
split Xs Ys Zs \(\rightarrow\) true \(\Leftarrow\) Xs \(\bowtie\) Ys ++ Zs \(\square\{\) Xs, Ys, Zs :: \([\alpha]\}\)
```

In the previous program, most patterns in the left-hand sides are data terms of FO type, except for the HO pattern (snd X) in function unpack and the HO variable F in functions map and twice. The usefulness of HO patterns as intensional representations of functions is better illustrated in the next example, where circuit is used as an alias for the type bool $\rightarrow$ bool $\rightarrow$ bool $\rightarrow$ bool. Functions of this type are intended to represent simple circuits which receive three boolean inputs and return a boolean output.

## Example 3 (Use of HO Patterns: Simple Circuits)

```
x1, x2, x3 :: circuit
x1 X1 X2 X3 }->\mathrm{ X1 }\Leftarrow\emptyset \square {X1, X2, X3 :: bool}
x2 X1 X2 X3 }->\mathrm{ X2 }\Leftarrow\emptyset \square {X1, X2, X3 :: bool
```

```
x3 X1 X2 X3 }->\mathrm{ X3 }\Leftarrow\emptyset\square { {X1, X2, X3 :: bool} 
notGate :: circuit -> circuit
notGate C X1 X2 X3 }->\mathrm{ not (C X1 X2 X3) }\Leftarrow\emptyset
                                    {C :: circuit, X1, X2, X3 :: bool}
andGate :: circuit }->\mathrm{ circuit }->\mathrm{ circuit
andGate C1 C2 X1 X2 X3 }->\mathrm{ and (C1 X1 X2 X3) (C2 X1 X2 X3) }\Leftarrow\emptyset\square
                            {C1, C2 :: circuit, X1, X2, X3 :: bool}
orGate :: circuit }->\mathrm{ circuit }->\mathrm{ circuit
orGate C1 C2 X1 X2 X3 }->\mathrm{ or (C1 X1 X2 X3) (C2 X1 X2 X3) }\Leftarrow
                                    {C1, C2 :: circuit, X1, X2, X3 :: bool}
size :: circuit -> nat
size x1 }->\textrm{z
size x2 }->
size x3 }->\mathrm{ z
size (notGate C) }->\mathrm{ s (size C) }\Leftarrow\emptyset\square {C :: circuit 
size (andGate C1 C2) }->\mathrm{ plus (size C1) (size C2) }\Leftarrow
                                    {C1, C2 :: circuit}
size (orGate C1 C2) }->\mathrm{ plus (size C1) (size C2) }\Leftarrow
                                    {C1, C2 :: circuit}
```

This obviously well-typed program should be completed with the definition of function plus, as in Example 2. Functions x1, x2 and x3 represent the basic circuits which just copy one of the inputs to the output. More interestingly, the HO functions notGate, andGate and orGate take circuits as parameters and build new circuits, corresponding to the logical gates NOT, AND and OR. The function size, whose definition uses HO patterns for circuits, computes the number of gates of a given circuit. Imagine that we are interested in a circuit whose output coincides with the majority of its three inputs. Using $\lambda$-notation, a circuit with this desired behaviour can be written as follows:

```
\lambdaX1.\lambdaX2.\lambdaX3.(and (or (and X1 X3) X2) (or X1 X3))
```

In our $\lambda$-free setting, an intensionally different circuit with the same behaviour can be represented as a pattern:
(andGate (orGate (andGate x 1 x 3 ) x2) (orGate x 1 x 3 ))
More generally, many patterns in the signature of this example are useful representations of circuits. The problem of finding a pattern that realizes a
circuit with a given logical behaviour has been discussed in detail in [47]. The solution can be easily written as a $\mathcal{T} \mathcal{O} \mathcal{Y}$ program [32], using a lazy generate-and-test method that exploits the combination of lazy evaluation and nondeterministic functions. The use of HO patterns as formal parameters and/or computed results is not possible in Haskell [43].

## 3 A Rewriting Logic for Program Semantics

### 3.1 Rewriting Calculi

In [19], a rewriting logic was proposed to deduce from an untyped CRWL program $\mathcal{P}$ certain statements that characterize the meaning of $\mathcal{P}$. More precisely, two kinds of statements must be considered: approximation statements $e \rightarrow t$, meaning that $t \in P a t_{\perp}$ approximates the value of $e \in E x p_{\perp}$; and joinability statements $a \bowtie b$, meaning that $a \rightarrow t, b \rightarrow t$ holds for some total $t \in$ Pat. The collection of all $t$ such that $e \rightarrow t$ can be deduced from $\mathcal{P}$ leads to a logical characterization of $e$ 's meaning, as we will see in Subsection 3.2. On the other hand, joinability statements are needed for conditions in rewrite rules, as well as for goals (see Section 4). They do not behave as equations in equational logic, for two reasons: $t$ is required to be a total pattern rather than an arbitrary expression, and it is not required to be unique. Requiring unicity of $t$ would lead to a deterministic version of joinability, which has been used under the name strict equality in several FLP languages, as e.g. [15, 38].

Roughly, a deduction of $e \rightarrow t$ in CRWL corresponds to a finite sequence of rewrite steps going from $e$ to $t$ in the $\operatorname{TRS} \mathcal{P} \cup\{X \rightarrow \perp\}$. Unfortunately, this simple idea does not work directly, because it leads to an inconvenient treatment of non-determinism (see [18, 47] for details). Therefore, two special rewriting calculi were proposed in [19] to formalize CRWL deducibility in a HO setting. The first one, called Basic Rewriting Calculus (BRC for short) expresses reflexivity, monotonicity and transitivity of CRWL-reductions in a natural way. Its definition is as follows.

## Definition 1 (The Basic Rewriting Calculus BRC)

$$
\begin{array}{ll}
\text { BT: } & e \rightarrow \perp \quad \mathbf{R F}: \quad e \rightarrow e \\
\text { TR: } & \frac{e \rightarrow e^{\prime} e^{\prime} \rightarrow e^{\prime \prime}}{e \rightarrow e^{\prime \prime}} \quad \mathbf{M N}: \frac{e \rightarrow e^{\prime} e_{1} \rightarrow e_{1}^{\prime}}{\left(e e_{1}\right) \rightarrow\left(e^{\prime} e_{1}^{\prime}\right)} \\
\mathbf{R}: \quad \frac{C}{l \rightarrow r} \quad \text { if }(l \rightarrow r \Leftarrow C) \in[\mathcal{P}]_{\perp} \\
\mathbf{J}: & \frac{a \rightarrow t \quad b \rightarrow t}{a \bowtie b} \quad \text { if } t \text { is a total pattern } \\
\hline
\end{array}
$$

The inference rule $\mathbf{R}$ above uses the set of (possibly partial) instances of rewrite rules from $\mathcal{P}$, that is defined as follows, ignoring the type environments:

$$
[\mathcal{P}]_{\perp}=\left\{(l \rightarrow r \Leftarrow C) \sigma_{d} \mid(l \rightarrow r \Leftarrow C \square T) \in \mathcal{P}, \sigma_{d} \in D S u b_{\perp}\right\}
$$

Due to the rules $\mathbf{B T}$ and $\mathbf{R}, \mathrm{BRC}$ is not equivalent to classical rewriting. The alternative Goal Oriented Rewriting Calculus (shortly GORC), given below, looks still more unnatural from the classical rewriting viewpoint. The motivation to introduce GORC is the top-down, goal-oriented format of GORC proofs. As we will see in Section 4, this feature provides a useful basis for the design of goal-solving calculi.

## Definition 2 (The Goal-Oriented Rewriting Calculus GORC)

BT: $\quad e \rightarrow \perp \quad$ RR: $\quad X \rightarrow X \quad$ if $X \in D$ Var
OR: $\frac{e_{1} \rightarrow t_{1} \cdots e_{n} \rightarrow t_{n} \quad C \quad r a_{1} \ldots a_{m} \rightarrow t}{f e_{1} \ldots e_{n} a_{1} \ldots a_{m} \rightarrow t}$
if $t \not \equiv \perp$ is a pattern, $m \geq 0$, and $f t_{1} \ldots t_{n} \rightarrow r \Leftarrow C \in[\mathcal{P}]_{\perp}$
$\mathbf{D C}: \quad \frac{e_{1} \rightarrow t_{1} \cdots e_{m} \rightarrow t_{m}}{h e_{1} \ldots e_{m} \rightarrow h t_{1} \ldots t_{m}} \quad$ if $h t_{1} \ldots t_{m}$ is a rigid pattern
J: $\quad \frac{a \rightarrow t \quad b \rightarrow t}{a \bowtie b} \quad$ if $t$ is a total pattern
BRC and GORC are essentially equivalent, as shown by the following result.

## Proposition 1 (Rewriting Calculi Equivalence)

For any CRWL program $\mathcal{P}, B R C$ and $G O R C$ derive the same approximation and joinability statements.

Proof idea: Reasoning by induction on the structure of proofs, it is possible to show that BRC proofs can be converted into GORC proofs and viceversa. We omit a detailed reasoning because it would be very similar to the proof of Proposition 4.1 in [18], which deals with the FO fragment of CRWL in an untyped setting. This reference includes also more motivation for the introduction of both rewriting calculi.

In the sequel we refer mainly to the GORC calculus. We use the notation $\mathcal{P} \vdash_{G O R C} \varphi$ to assert that the statement $\varphi$ can be deduced from the program $\mathcal{P}$ using GORC. Next we show a simple example of a GORC proof, based on the program from Example 2 and deriving snd (tail [X]) $\bowtie$ snd (tail [Y]).

## Example 4 (A Simple GORC Proof)

1. snd (tail [X]) ฝ snd (tail [Y])
by JN, 2,3
2. snd (tail [X]) $\rightarrow$ snd [] by DC, 4
3. snd (tail [Y]) $\rightarrow$ snd []
by $\mathrm{DC}, 5$
4. tail [X] $\rightarrow$ []
by OR, 6,8
5. tail [Y] $\rightarrow$ [] by OR, 7, 8
6. $[\mathrm{X}] \rightarrow$ [XI[]] by DC, 8,9
7. $[\mathrm{Y}] \rightarrow[\mathrm{Y} \mid[]] \quad$ by $\mathrm{DC}, 8,10$
8. [] $\rightarrow$ []
by DC
9. $\mathrm{X} \rightarrow \mathrm{X}$ by RR
10. $\mathrm{Y} \rightarrow \mathrm{Y}$ by RR

The next definition will be useful later on.

## Definition 3 (Structured GORC Proofs)

The structure of a GORC proof $\Pi$ for statement $\varphi$ (in symbols, $\Pi \leadsto \varphi$ ) obeys
to the following abstract syntax:

$$
\begin{aligned}
(\Pi \leadsto \varphi): & = \\
& \mathbf{B T} \leadsto e \rightarrow \perp \\
& \mathbf{R R} \leadsto X \rightarrow X \\
& \mid\left(\Pi_{1} \leadsto e_{1} \rightarrow t_{1} \& \cdots \& \Pi_{n} \leadsto e_{n} \rightarrow t_{n} \& \Pi^{\prime} \leadsto C \&\right. \\
& \left.\Pi^{\prime \prime} \leadsto r \bar{a}_{m} \rightarrow t\right)+(\mathbf{O R}) \leadsto f \bar{e}_{n} \bar{a}_{m} \rightarrow t \\
\text { if }\left(f \bar{t}_{n} \rightarrow\right. & r \Leftarrow C) \in[\mathcal{P}]_{\perp} \\
\mid & \left(\Pi_{1} \leadsto e_{1} \rightarrow t_{1} \& \cdots \& \Pi_{m} \leadsto e_{m} \rightarrow t_{m}\right)+(\mathbf{D C}) \\
& \leadsto h \bar{e}_{m} \rightarrow h \bar{t}_{m} \\
\mid & \left(\Pi_{1} \leadsto a \rightarrow t \& \Pi_{2} \leadsto b \rightarrow t\right)+(\mathbf{J N}) \leadsto a \bowtie b
\end{aligned}
$$

When writing structured GORC proofs in the rest of the paper, we sometimes abbreviate them by omitting some parts which are unneeded or can be deduced from the context.

There is a natural relation between GORC deducibility and the approximation ordering $\sqsupseteq$ over $P a t_{\perp}$, as shown by the following lemma. We omit the straightforward proof, which proceeds by induction over the size of GORC proofs. A proof of item 3 for the FO fragment of CRWL can be found in [18], Lemma 4.1.

## Lemma 8 (Basic Properties of GORC)

Assume a (not necessarily well-typed) CRWL program $\mathcal{P}$. The following properties hold:

1. For any $t, t^{\prime} \in$ Pat $_{\perp}: \mathcal{P} \vdash_{G O R C} t^{\prime} \rightarrow t \Longleftrightarrow t \sqsupseteq t^{\prime}$.
2. For any $e \in E x p_{\perp}, t, t^{\prime} \in$ Pat $_{\perp}: \mathcal{P} \vdash_{G O R C} e \rightarrow t^{\prime}$ and $t \sqsupseteq t^{\prime} \Longrightarrow$ $\mathcal{P} \vdash_{G O R C} e \rightarrow t$.
3. For any $e \in E x p_{\perp}, t \in P a t_{\perp}$ and $\sigma_{d}, \sigma_{d}^{\prime} \in D S u b_{\perp}$ such that $\sigma_{d} \sqsupseteq \sigma_{d}^{\prime}$ : $\mathcal{P} \vdash_{G O R C} e \sigma_{d} \rightarrow t \Longrightarrow \mathcal{P} \vdash_{G O R C} e \sigma_{d}^{\prime} \rightarrow t$ with a proof of the same size and structure.

Let us now consider the relationship between GORC provability and the polymorphic type system introduced in Subsection 2.2. Note that $\mathcal{P} \vdash_{\text {GORC }}$ $e \rightarrow t$ corresponds to a purely functional computation reducing $e$ to $t$. Although GORC derivations do not perform any kind of type checking, they
do always preserve types in the case of a well-typed program. The following subject reduction lemma, proved in the Appendix, guarantees that a single OR step is type-preserving.

## Lemma 9 (One Step Subject Reduction for GORC)

Assume that a well-typed program $\mathcal{P}$ includes a defining rule $f \bar{t}_{n} \rightarrow r \Leftarrow$ $C \square T_{0}$ for a defined symbol with principal type $f:: \bar{\tau}_{n} \rightarrow \tau_{0}$. Suppose also a type environment $T$ and a substitution $\sigma=\left(\sigma_{t}, \sigma_{d}\right)$ which verifies $T \vdash_{W T} t_{i} \sigma_{d}:: \tau_{i} \sigma_{t}$ for all $1 \leq i \leq n$. Then $T \vdash_{W T} r \sigma_{d}:: \tau_{0} \sigma_{t}$.

The proof of Lemma 9 relies on the Lemmata 3, 4, and 6. Type-preservation for arbitrary GORC derivations is ensured by the next result, whose full proof is given in the Appendix.

## Theorem 2 (Subject Reduction for GORC)

Consider a well-typed program $\mathcal{P}$. Assume $e \in \operatorname{Exp}_{\perp}, \tau \in$ Type and a type environment $T$ such that $T \vdash_{W T} e:: \tau$. Then, for every $t \in P a t_{\perp}$ :

$$
\mathcal{P} \vdash_{G O R C} e \rightarrow t \Longrightarrow T \vdash_{W T} t:: \tau .
$$

Proof idea: Induction on the size of a given GORC proof for $\mathcal{P} \vdash_{G O R C} e \rightarrow$ $t$. A case distinction is needed according to the GORC inference rule applied at the last step. The OR case is the most interesting one; it is proved with the help of Lemma 9.

When defining well-typed program rules in Subsection 2.3, we have required absence of extra variables in the right-hand sides, as well as type generality and transparency of the left-hand sides. All these requirements are needed for the subject reduction property to hold. This is shown by the next example, based on the program from Example 2.

## Example 5 (Subject Reduction Failure)

1. $\{\mathrm{X}:: \alpha\} \vdash_{W T}$ wild $\mathrm{X}::$ bool and $\mathcal{P} \vdash_{G O R C}$ wild $\mathrm{X} \rightarrow \mathrm{z}$, but $\{\mathrm{X}:: \alpha\} \nvdash_{W T}$ z :: bool.
2. $\emptyset \vdash_{W T}$ extend [] :: [bool] and $\mathcal{P} \vdash_{G O R C}$ extend [] $\rightarrow$ [z], but $\emptyset$ $\forall_{W T}[z]::$ [bool].
3. $\emptyset \vdash_{W T}$ unpack (snd z) :: bool and $\mathcal{P} \vdash_{G O R C}$ unpack (snd z) $\rightarrow \mathrm{z}$, but $\emptyset \vdash_{W T} \mathbf{z}$ :: bool.

Our result on the existence of well-typed least Herbrand models for welltyped programs (see Lemma 11 and Theorem 3 in Subsection 3.2) crucially depend on the subject reduction property, and thus on the absence of extra variables in right-hand sides. Both the GORC calculus and the construction of least Herbrand models are concerned only with the behaviour of rewriting computations. Goal solving in the logic programming sense is the task of the lazy narrowing calculus CLNC presented in Section 4. In contrast to GORC, computations in CLNC do not instantiate extra variables in an arbitrary way. Therefore, it might be the case that extra variables on right-hand sides are no obstacle for the well-typed behaviour of lazy narrowing. We have not investigated this problem.

Independently of the extra variables issue, the possible occurrence of HO logic variables in goals implies that no analogon of the subject reduction property can be found for goal solving in CLNC. As we will see, dynamic type checking is needed in order to face this difficulty. In Section 4 we also use GORC proofs to witness the correctness of solutions computed by CLNC. For this reason, the following notion is useful to investigate the construction of well-typed CLNC computations.

## Definition 4 (Type-annotated GORC Proofs)

Type-annotated GORC proofs are built by extending GORC proofs with consistent type information. More precisely, we use the following abstract syntax to describe the structure of type-annotated GORC proofs:

$$
\begin{aligned}
& (\Pi \sim \varphi)::=\mathbf{B T} \leadsto e^{\tau} \rightarrow \perp^{\tau} \\
& \quad \mid \quad \mathbf{R R} \leadsto X^{\tau} \rightarrow X^{\tau} \\
& \quad \mid \quad\left(\Pi_{1} \leadsto e_{1}^{\tau_{1}} \rightarrow t_{1}^{\tau_{1}} \& \cdots \& \Pi_{n} \leadsto e_{n}^{\tau_{n}} \rightarrow t_{n}^{\tau_{n}} \& \Pi^{\prime} \leadsto C^{b o o l} \&\right. \\
& \left.\quad \Pi^{\prime \prime} \leadsto\left(r^{\bar{\mu}_{m} \rightarrow \tau} \bar{a}_{m}^{\bar{\mu}_{m}}\right)^{\tau} \rightarrow t^{\tau}\right)+(\mathbf{O R}) \leadsto\left(f^{\tau_{n} \rightarrow \bar{\mu}_{m} \rightarrow \tau} \bar{e}_{n}^{\bar{\tau}_{n}} \bar{a}_{m}^{\bar{\mu}_{m}}\right)^{\tau} \rightarrow t^{\tau} \\
& \quad \text { if }\left(f^{\bar{\tau}_{n} \rightarrow \bar{\mu}_{m} \rightarrow \tau} \bar{t}_{n}^{\bar{\tau}_{n}}\right)^{\bar{\mu}_{m} \rightarrow \tau} \rightarrow r^{\bar{\mu}_{m} \rightarrow \tau} \Leftarrow C^{b o o l} \in[\mathcal{P}]_{\perp}^{T A} \\
& \quad \mid \quad\left(\Pi_{1} \leadsto e_{1}^{\tau_{1}} \rightarrow t_{1}^{\tau_{1}} \& \cdots \& \Pi_{m} \leadsto e_{m}^{\tau_{m}} \rightarrow t_{m}^{\tau_{m}}\right)+(\mathbf{D C}) \\
& \quad \leadsto\left(h^{\bar{\tau}_{m} \rightarrow \tau} \bar{e}_{m}^{\tau_{m}}\right)^{\tau} \rightarrow\left(h^{\bar{\tau}_{m} \rightarrow \tau} \bar{t}_{m}^{\bar{\tau}_{m}}\right)^{\tau} \\
& \mid\left(\Pi_{1} \leadsto a^{\tau} \rightarrow t^{\tau} \& \Pi_{2} \leadsto b^{\tau} \rightarrow t^{\tau}\right)+(\mathbf{J N}) \leadsto a^{\tau} \bowtie b^{\tau}
\end{aligned}
$$

The notation $[\mathcal{P}]_{\perp}^{T A}$ refers to the set of type-annotated (and possibly partial) instances of defining rules from the well-typed program $\mathcal{P}$. It can be defined in two stages:

- Due to Lemma 1, each rule $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C \square T\right) \in \mathcal{P}$ for a function with principal type $f:: \bar{\tau}_{n} \rightarrow \tau$ can be type-annotated to become $\left(f^{\bar{\tau}_{n} \rightarrow \tau} \bar{t}_{n}^{\bar{\tau}_{n}}\right)^{\tau} \rightarrow r^{\tau} \Leftarrow C^{\text {bool }}$ (with implicit type environment $T$ ). Let $\mathcal{P}^{T A}$ be the set of all possible, principal type annotations of rules from $\mathcal{P}$, built in this way.
- Define $[\mathcal{P}]_{\perp}^{T A}$ as the set of all the type-annotated rule instances $\left(l^{\tau} \rightarrow\right.$ $\left.r^{\tau} \Leftarrow C^{b o o l}\right) \theta$, such that $\left(l^{\tau} \rightarrow r^{\tau} \Leftarrow C^{b o o l}\right) \in \mathcal{P}^{T A}$ and $\theta=\left(\theta_{t}, \theta_{d}\right)$ is well-typed in the sense of Lemma 5.

All the expressions occurring within a type-annotated GORC proof are supposed to be fully type-annotated in the way explained in Subsection 2.2. Obviously, type-annotated GORC proofs always represent a well-typed computation. Some GORC proofs, however, cannot be type-annotated. Considering again the well-typed program $\mathcal{P}$ from Example 2, we get:

## Example 6 (Type Annotation of GORC Proofs)

(a) The GORC proof from Example 4 can be type-annotated. The typeannotated version of the first line of the proof (somewhat abbreviated) would look as follows:

$$
\begin{gathered}
\text { (snd } \left.^{[\alpha] \rightarrow \beta \rightarrow \beta}\left(\operatorname{tail}^{[\alpha] \rightarrow[\alpha]}\left[\mathrm{X}^{\alpha}\right]^{[\alpha]}\right)^{[\alpha]}\right)^{\beta \rightarrow \beta} \\
\bowtie \\
\text { (snd } \left.^{[\alpha] \rightarrow \beta \rightarrow \beta}\left(\operatorname{tail}^{[\alpha] \rightarrow[\alpha]}\left[\mathrm{Y}^{\alpha}\right]^{[\alpha]}\right)^{[\alpha]}\right)^{\beta \rightarrow \beta}
\end{gathered}
$$

This is an instance of the principal type-annotation, chosen to enable a consistent type-annotation of all the other statements occurring in the proof. The principal type annotation, namely

$$
\begin{gathered}
\operatorname{sid}^{\left[\alpha_{1}\right] \rightarrow \beta \rightarrow \beta}\left(\operatorname{tail}^{\left[\alpha_{1}\right]} \rightarrow\left[\alpha_{1}\right]\right. \\
\left.\left.\left.\bowtie \mathrm{X}^{\alpha_{1}}\right]^{\left[\alpha_{1}\right]}\right)^{\left[\alpha_{1}\right]}\right)^{\beta \rightarrow \beta} \\
\left.\operatorname{snd}^{\left[\alpha_{2}\right] \rightarrow \beta \rightarrow \beta}\left(\operatorname{tail}^{\left[\alpha_{2}\right] \rightarrow\left[\alpha_{2}\right]} \quad\left[\mathrm{Y}^{\alpha_{2}}\right]^{\left[\alpha_{2}\right]}\right)^{\left[\alpha_{2}\right]}\right)^{\beta \rightarrow \beta}
\end{gathered}
$$

would not allow a consistent type annotation of the second and third lines of the proof. This is because the $\mathbf{J N}$ case in Definition 4 requires $t^{\tau}$ be the same type-annotated pattern in the two premises $a^{\tau} \rightarrow t^{\tau}$ and $b^{\tau} \rightarrow t^{\tau}$.
(b) On the other hand, the following GORC proof cannot be type-annotated, because the only possible type-annotations of the lines 1,2 and 3 are not consistent with the requirements of Definition 4 in the $\mathbf{J N}$ case.

```
1. snd (tail [z]) \bowtie snd (tail [true])
2. snd (tail [z]) }->\mathrm{ snd []
3. snd (tail [true]) }->\mathrm{ snd []
4. tail [z] }->\mathrm{ []
5. tail [true] }->\mathrm{ []
6. [z] }->\mathrm{ [z|[]]
7. [true] -> [true|[]]
8. [] }->\mathrm{ []
9. z }->\textrm{z
10. true }->\mathrm{ true
```

by $\mathbf{J N}, 2,3$
by DC, 4
by DC, 5
by OR, 6,8
by OR, 7, 8
by DC, 9,8
by DC, 10,8
by DC
by DC
by DC

### 3.2 Models

A logical semantics for CRWL programs has been presented in [19] for an untyped HO language, and in [5] for a typed FO language with algebraic datatypes. Here we combine both approaches, using models with a data universe and a type universe. Let us recall some notions about posets, that are needed for our data domains.

A poset with bottom $\perp$ is any set $S$ partially ordered by $\sqsubseteq$, with least element $\perp$. $\operatorname{Def}(S)$ denotes the set of all maximal elements $u \in S$, also called totally defined. Assume $X \subseteq S . X$ is a directed set iff for all $u, v \in X$ there exists $w \in X$ such that $u, v \sqsubseteq w$. $X$ is a cone iff $\perp \in X$ and $X$ is downwards closed w.r.t. $\sqsubseteq . ~ X ~ i s ~ a n ~ i d e a l ~ i f f ~ X ~ i s ~ a ~ d i r e c t e d ~ c o n e . ~ W e ~ w r i t e ~ \mathcal{C}(S)$ (resp. $\mathcal{I}(S)$ ) for the set consisting of all the subsets $X \subseteq S$ which are cones (resp. ideals) of $S . \mathcal{I}(S)$ ordered by set inclusion $\subseteq$ is a poset with bottom $\{\perp\}$, called the ideal completion of $S$. Mapping each $u \in S$ into the principal ideal $\langle u\rangle=\{v \in S \mid v \sqsubseteq u\}$ gives an order preserving embedding. There is a natural correspondence between the ideal completions of posets and a popular class of semantic domains, called algebraic cpos [21]; more details are given in [37, 18]. For our needs in this paper, the following intuitions will suffice: the elements of a poset $S$ represent finite approximations of data values; defined elements in $\operatorname{Def}(S)$ represent totally computed finite values of deterministic expressions; ideals in $\mathcal{I}(S)$ represent possibly infinite
values of deterministic expressions; and cones in $\mathcal{C}(S)$ represent values of non-deterministic expressions.

In the sequel we overload the symbol $\perp$ to stand for the bottom element of any poset, as well as for the syntactic $\perp$ used in partial expressions. Assume two posets with bottom $D$ and $E$. To model deterministic resp. non-deterministic functions, we define:

$$
\begin{aligned}
& {\left[D \rightarrow_{n} E\right]=\left\{f: D \rightarrow \mathcal{C}(E) \mid \forall u, u^{\prime} \in D:\left(u \sqsupseteq u^{\prime} \Rightarrow f(u) \subseteq f\left(u^{\prime}\right)\right)\right\}} \\
& {\left[D \rightarrow_{d} E\right]=\left\{f \in\left[D \rightarrow_{n} E\right] \mid \forall u \in D: f(u) \in \mathcal{I}(E)\right\}}
\end{aligned}
$$

Given $f \in\left[D \rightarrow_{n} E\right]$ and $X \in \mathcal{C}(D)$, we write $f(X)$ to abbreviate $\bigcup_{u \in X} f(u)$. It is easily checked that $f(X) \in \mathcal{C}(E)$. This fact will be implicitly used in the sequel. As models for CRWL programs we use algebras of the following kind.

## Definition 5 (Algebras)

For any signature $\Sigma$ we consider algebras of the form

$$
\mathcal{A}=\left\langle D^{\mathcal{A}}, T^{\mathcal{A}}, @^{\mathcal{A}}, \Rightarrow^{\mathcal{A}},::^{\mathcal{A}},\left\{C^{\mathcal{A}}\right\}_{C \in T C},\left\{c^{\mathcal{A}}\right\}_{c:: \tau \in D C},\left\{f^{\mathcal{A}}\right\}_{f:: \tau \in F S}\right\rangle
$$

such that the following conditions hold:

1. The data universe $D^{\mathcal{A}}$ is a poset, whose elements are called data intensions.
2. The type universe $T^{\mathcal{A}}$ is a set, whose elements are called type intensions.
3. The apply operation @ ${ }^{\mathcal{A}}$, that will be used in infix notation, belongs to $\left[D^{\mathcal{A}} \times D^{\mathcal{A}} \rightarrow_{n} D^{\mathcal{A}}\right]$ and satisfies $\perp @^{\mathcal{A}} v=\langle\perp\rangle$ for all $v \in D^{\mathcal{A}}$. For given elements $u_{i} \in D^{\mathcal{A}}$, the notation " $u_{0} @^{\mathcal{A}} u_{1} @^{\mathcal{A}} \ldots @^{\mathcal{A}} u_{k}$ " represents a cone defined as $\left\langle u_{0}\right\rangle$, if $k=0$, and $\left(u_{0} @^{\mathcal{A}} \ldots @^{\mathcal{A}} u_{k-1}\right) @^{\mathcal{A}} u_{k}$, if $k>0$.
4. $\Rightarrow^{\mathcal{A}}: T^{\mathcal{A}} \times T^{\mathcal{A}} \rightarrow T^{\mathcal{A}}$, that will be used in infix notation, interprets the type constructor " $\rightarrow$ ".
5. :: ${ }^{\mathcal{A}} \subseteq D^{\mathcal{A}} \times T^{\mathcal{A}}$ interprets type membership. For each $l \in T^{\mathcal{A}}$, the extension of $l$, defined as $\mathcal{E}^{\mathcal{A}}(l)=\left\{u \in D^{\mathcal{A}} \mid u::{ }^{\mathcal{A}} l\right\}$, must be a cone in $D^{\mathcal{A}}$.
6. For each $C \in T C^{n}, C^{\mathcal{A}}:\left(T^{\mathcal{A}}\right)^{n} \rightarrow T^{\mathcal{A}}\left(\right.$ simply $C^{\mathcal{A}} \in T^{\mathcal{A}}$ if $\left.n=0\right)$, interprets the type constructor $C$.
7. For each $c \in D C^{n}, c^{\mathcal{A}} \in D^{\mathcal{A}}$.
8. For each $f \in F S^{n}, f^{\mathcal{A}} \in D^{\mathcal{A}}$ if $n>0$, and $f^{\mathcal{A}} \in \mathcal{C}\left(D^{\mathcal{A}}\right)$, if $n=0$.
9. For all $h, k$ such that $h \in D C^{n}, 0 \leq k \leq n$ or $h \in F S^{n}, 0 \leq k<n$, and for all $u_{1}, \ldots, u_{k} \in D^{\mathcal{A}}$ there is $v \in D^{\mathcal{A}}$ such that $h^{\mathcal{A}} @^{\mathcal{A}} u_{1} @^{\mathcal{A}} \ldots @^{\mathcal{A}} u_{k}$ $=\langle v\rangle$. Moreover, if all the $u_{i}$ are maximal then $v$ is also maximal.

The elements of $D^{\mathcal{A}}$ are called data intensions because they can be interpreted as functions by means of the apply operation @ ${ }^{\mathcal{A}}$, but they are not "true functions". Analogously, the type intensions belonging to $T^{\mathcal{A}}$ are interpreted as cones of data intensions by means of the membership relation $:: \mathcal{A}$, but they are not "true sets". Thanks to intensional semantics, one can work in a HO language while avoiding undecidability problems, especially undecidability of HO unification [17]. Variants of this idea have occurred previously in some LP and equational LP languages, as e.g. in [7, 23, 22, 24]. The paper [7] presents an untyped HO LP language called HiLog, with intensional semantics. In $[23,22,24]$ one finds models and polymorphic type systems for FO LP and equational LP, as well as a suggestion to simulate HO programming by means of data intensions and user-defined apply predicates. This goes back to a technique proposed by Warren [49]. In order to well-type the apply predicates, type-generality of predicate definitions has to be abandoned. Moreover, [23, 22, 24] require explicit type annotations in terms, so that untyped expressions and programs have no semantic meaning.

To explain item 9 in Definition 5, let us abbreviate $h^{\mathcal{A}} @^{\mathcal{A}} u_{1} @{ }^{\mathcal{A}} \ldots @^{\mathcal{A}} u_{k}$ as $h^{\mathcal{A}} u_{1} \ldots u_{k}$. This stands for the result of applying $h^{\mathcal{A}}$ to $k$ arguments. Therefore, item 9 requires that the application of a data constructors and the partial application of a defined function to a number of arguments less than its arity, must return a deterministic result, totally defined if the arguments are. Given $h \in D C^{n} \cup F S^{n}$, we say that $h^{\mathcal{A}}$ is deterministic iff $h^{\mathcal{A}} u_{1} \ldots u_{n}$ is an ideal for all $u_{1}, \ldots, u_{n} \in D^{\mathcal{A}}$. According to item 9 , this is always the case for $c^{\mathcal{A}}$, for any $c \in D C^{n}$.

The technical requirements of Definition 5 are motivated by the properties of a particular class of algebras, called Herbrand Algebras.

## Definition 6 (Herbrand Algebras)

Assume a type environment $T$ with $\operatorname{dom}(T)=D$ Var. An algebra $\mathcal{A}$ is called a Herbrand algebra over $T$ iff the following conditions are satisfied:

1. $D^{\mathcal{A}}=P a t_{\perp}$, and $T^{\mathcal{A}}=$ Type.
2. $\tau_{1} \Rightarrow^{\mathcal{A}} \tau=\tau_{1} \rightarrow \tau$, and $C^{\mathcal{A}}\left(\tau_{1}, \ldots, \tau_{n}\right)=C \tau_{1} \ldots \tau_{n}$, for all $C \in T C^{n}$.
3. $t:: \mathcal{A} \tau$ iff $T \vdash_{W T} t:: \tau$, for all $t \in$ Pat $_{\perp}, \tau \in$ Type.
4. $\perp @^{\mathcal{A}} t=X @^{\mathcal{A}} t=\langle\perp\rangle$, for all $t \in$ Pat $_{\perp}, X \in D V a r$.
5. $t @^{\mathcal{A}} t_{1}=\left\langle\left(t t_{1}\right)\right\rangle$, whenever $\left(t t_{1}\right) \in$ Pat $_{\perp}$.
6. $c^{\mathcal{A}}=c$, for all $c \in D C$.
7. $f^{\mathcal{A}}=f$, for all $f \in F S$ such that $\operatorname{ar}(f)>0$.
$A$ valuation $\eta=\left(\eta_{t}, \eta_{d}\right)$ over $\mathcal{A}$ is given by two mappings $\eta_{t}: T \operatorname{Var} \rightarrow T^{\mathcal{A}}$ (the type valuation) and $\eta_{d}: D \operatorname{Var} \rightarrow D^{\mathcal{A}}$ (the data valuation). A valuation $\eta$ is totally defined iff $\eta_{d}(X) \in \operatorname{Def}\left(D^{\mathcal{A}}\right)$ for all $X \in D V a r$. We write $\operatorname{Val}(A)$ resp. $\operatorname{DefVal}(\mathcal{A})$ for the set of all valuations resp. totally defined valuations over $\mathcal{A}$. The values of types and expressions in $\mathcal{A}$ under $\eta$ are computed recursively:

- $\llbracket \alpha \rrbracket^{\mathcal{A}} \eta=\eta_{t}(\alpha)$, for $\alpha \in$ Type.
- $\llbracket\left(C \tau_{1} \ldots \tau_{n}\right) \rrbracket^{\mathcal{A}} \eta=C^{\mathcal{A}}\left(\llbracket \tau_{1} \rrbracket^{\mathcal{A}} \eta, \ldots, \llbracket \tau_{n} \rrbracket^{\mathcal{A}} \eta\right)$, for $C \in T C^{n}$.
- $\llbracket \tau_{1} \rightarrow \tau \rrbracket^{\mathcal{A}} \eta=\llbracket \tau_{1} \rrbracket^{\mathcal{A}} \eta \Rightarrow^{\mathcal{A}} \llbracket \tau \rrbracket^{\mathcal{A}} \eta$.
- $\llbracket \perp \rrbracket^{\mathcal{A}} \eta=\langle\perp\rangle$.
- $\llbracket X \rrbracket^{\mathcal{A}} \eta=\left\langle\eta_{d}(X)\right\rangle$, for $X \in D V a r$.
- $\llbracket c \rrbracket^{\mathcal{A}} \eta=\left\langle c^{\mathcal{A}}\right\rangle$, for $c \in D C$.
- $\llbracket f \rrbracket^{\mathcal{A}} \eta=\left\langle f^{\mathcal{A}}\right\rangle$ if $\operatorname{ar}(f)>0$ and $f^{\mathcal{A}}$ otherwise, for $f \in F S$.
- $\llbracket\left(e e_{1}\right) \rrbracket^{\mathcal{A}} \eta=\llbracket e \rrbracket^{\mathcal{A}} \eta @^{\mathcal{A}} \llbracket e_{1} \rrbracket^{\mathcal{A}} \eta$.

Sometimes we write $\llbracket e \rrbracket^{\mathcal{A}} \eta_{d}$ and $\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}$ for $\llbracket e \rrbracket^{\mathcal{A}} \eta$ and $\llbracket \tau \rrbracket^{\mathcal{A}} \eta$, respectively.

Note that in the case of Herbrand algebras, valuations are the same as substitutions. Some simple properties of evaluation are stated in the next proposition, whose proof is sketched in the Appendix.

## Proposition 2 (Basic Properties of Evaluation)

Assume $\tau \in$ Type, $e \in E x p_{\perp}, t \in P a t_{\perp}$ and $\eta \in \operatorname{Val}(\mathcal{A})$. Then:

1. $\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t} \in T^{\mathcal{A}}$, and $\llbracket e \rrbracket^{\mathcal{A}} \eta_{d} \in \mathcal{C}\left(D^{\mathcal{A}}\right)$.
2. If $f^{\mathcal{A}}$ is deterministic for every $f \in F S$ occurring in $e$, then $\llbracket e \rrbracket^{\mathcal{A}} \eta_{d} \in$ $\mathcal{I}\left(D^{\mathcal{A}}\right)$.
3. $\llbracket t \rrbracket^{\mathcal{A}} \eta_{d}=\langle v\rangle$, for some $v \in D^{\mathcal{A}}$. Moreover, if $t \in$ Pat is total and $\eta \in \operatorname{DefVal}(\mathcal{A})$, then $v \in \operatorname{Def}\left(D^{\mathcal{A}}\right)$.
4. If $\mathcal{A}$ is a Herbrand algebra, then $\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}=\tau \eta_{t}$ and $\llbracket t \rrbracket^{\mathcal{A}} \eta_{d}=\left\langle t \eta_{d}\right\rangle$.

Another basic result establishes a natural relationship between substitution and evaluation. We omit the straightforward proof by induction over the syntactic structure of $\tau, e$. Similar results can be found in $[18,5]$.

## Lemma 10 (Substitution Lemma)

Consider a valuation $\eta=\left(\eta_{t}, \eta_{d}\right) \in \operatorname{Val}(\mathcal{A})$ and a substitution $\sigma=\left(\sigma_{t}, \sigma_{d}\right)$. Define another valuation $\eta \sigma=\left(\eta \sigma_{t}, \eta \sigma_{d}\right) \in \operatorname{Val}(\mathcal{A})$ by the conditions:

- $\left(\eta \sigma_{t}\right)(\alpha)=\llbracket \sigma_{t}(\alpha) \rrbracket^{\mathcal{A}} \eta_{t}$ for all $\alpha \in$ TVar.
- $\left(\eta \sigma_{d}\right)(X)=v \in D^{\mathcal{A}}$ such that $\llbracket \sigma_{d}(X) \rrbracket^{\mathcal{A}} \eta_{d}=\langle v\rangle$ for all $X \in D$ Var; note that $v$ exists because of Proposition 2, item 3.

Then, $\llbracket \tau \sigma_{t} \rrbracket^{\mathcal{A}} \eta_{t}=\llbracket \tau \rrbracket^{\mathcal{A}} \eta \sigma_{t}$ for every $\tau \in$ Type, and $\llbracket e \sigma_{d} \rrbracket^{\mathcal{A}} \eta_{d}=\llbracket e \rrbracket^{\mathcal{A}} \eta \sigma_{d}$ for every $e \in E x p_{\perp}$.

Algebras and valuations are not always well-behaved w.r.t. types. The following definition isolates the well-typed ones.

## Definition 7 (Well-typed Algebras)

1. A valuation $\eta=\left(\eta_{t}, \eta_{d}\right)$ over $\mathcal{A}$ is well-typed w.r.t. a type environment $T$ iff every $X:: \tau \in T$ verifies that $\eta_{d}(X) \in \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$.
2. An algebra $\mathcal{A}$ is well-typed iff for every type valuation $\eta_{t}$ :
(a) $c^{\mathcal{A}} \in \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$, for $c:: \tau \in D C^{n}$.
(b) $f^{\mathcal{A}} \in \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$, for $f:: \tau \in F S^{n}, n>0$.
(c) $f^{\mathcal{A}} \subseteq \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$, for $f:: \tau \in F S^{0}$.
(d) For all $u, u_{1} \in D^{\mathcal{A}}$, for all $t, t_{1} \in T^{\mathcal{A}}$ : if $u \in \mathcal{E}^{\mathcal{A}}\left(t_{1} \Rightarrow^{\mathcal{A}}\right.$ t) and $u_{1} \in \mathcal{E}^{\mathcal{A}}\left(t_{1}\right)$ then $u @^{\mathcal{A}} u_{1} \subseteq \mathcal{E}^{\mathcal{A}}(t)$.

The next result, proved in the Appendix, guarantees that the evaluation of well-typed expressions in well-typed algebras behaves as expected.

## Proposition 3 (Well-typed Evaluation)

Assume a type environment $T$, a well-typed algebra $\mathcal{A}$, and a valuation $\eta \in$ $\operatorname{Val}(\mathcal{A})$ that is well-typed w.r.t. $T$. Then, for every $e \in \operatorname{Exp}_{\perp}$ such that $T \vdash_{W T} e:: \tau$, one has $\llbracket e \rrbracket^{\mathcal{A}} \eta_{d} \subseteq \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$.

In the rest of this section we prove the existence of least Herbrand models for CRWL programs. The notion of model, borrowed from [19], does not depend on the type system.

## Definition 8 (Models)

Given an algebra $\mathcal{A}$ and a program $\mathcal{P}$, we define:

1. $\mathcal{A}$ satisfies an approximation statement $e \rightarrow t$ under $\eta \in \operatorname{Val}(\mathcal{A})$ iff $\llbracket e \rrbracket^{\mathcal{A}} \eta \supseteq \llbracket t \rrbracket^{\mathcal{A}} \eta$.
2. $\mathcal{A}$ satisfies a condition $C$ under $\eta \in \operatorname{Val}(\mathcal{A})$ iff for every $a \bowtie b \in C$ there is some totally defined element $v \in \llbracket a \rrbracket^{\mathcal{A}} \eta \cap \llbracket b \rrbracket^{\mathcal{A}} \eta$.
3. $\mathcal{A}$ satisfies a rewrite rule $(l \rightarrow r \Leftarrow C \square T)$ iff $\llbracket l \rrbracket^{\mathcal{A}} \eta \supseteq \llbracket r \rrbracket^{\mathcal{A}} \eta$ holds for every $\eta \in \operatorname{Val}(\mathcal{A})$ such that $\mathcal{A}$ satisfies $C$ under $\eta$.
4. $\mathcal{A}$ is a model of $\mathcal{P}$ iff $\mathcal{A}$ satisfies all the rewrite rules belonging to $\mathcal{P}$.

Note that neither $\eta_{t}$ nor the type environments attached to rewrite rules are needed in the previous definition. Therefore, untyped programs can also have models. In the sequel, we write $(\mathcal{A}, \eta) \vDash \varphi$ (where $\varphi$ maybe an approximation statement or a joinability statement) to note that $\mathcal{A}$ satisfies $\varphi$ under $\eta$, and we write $\mathcal{A} \vDash \mathcal{P}$ to note that $\mathcal{A}$ is a model of $\mathcal{P}$. We are mainly interested in least Herbrand models, that are defined as follows:

## Definition 9 (Least Herbrand Models)

Assume a program $\mathcal{P}$ and a type environment $T$ such that $\operatorname{dom}(T)=D \operatorname{Var}$. The least Herbrand model of $\mathcal{P}$ over $T$, noted as $\mathcal{M}_{\mathcal{P}}(T)$, is the unique Herbrand algebra over $T$ that satisfies the two following requirements:

1. $f \bar{t}_{n-1} @ \mathcal{M}_{\mathcal{P}(T)} t_{n}=\left\{t \in P a t_{\perp} \mid \mathcal{P} \vdash_{G O R C} f \bar{t}_{n} \rightarrow t\right\}$, for $f \in F S^{n}, n>0$.
2. $f^{\mathcal{M}_{\mathcal{P}}(T)}=\left\{t \in\right.$ Pat $\left._{\perp} \mid \mathcal{P} \vdash_{G O R C} f \rightarrow t\right\}$, for $f \in F S^{0}$.

By inspecting Definitions 5, 6 and 9, it can be checked that $\mathcal{M}_{\mathcal{P}}(T)$ is well defined, and such that the following condition holds for any $f \in F S^{n}$ and arbitrary patterns $t_{1}, \ldots, t_{n} \in$ Pat $_{\perp}: f^{\mathcal{M}_{\mathcal{P}}(T)} \bar{t}_{n}=\left\{t \in P a t_{\perp} \mid \mathcal{P} \vdash_{G O R C}\right.$ $\left.f \bar{t}_{n} \rightarrow t\right\}$. More precisely, the essential properties of $\mathcal{M}_{\mathcal{P}}(T)$ are given by the next two lemmata, whose proofs can be found in the Appendix.

## Lemma 11 (Least Herbrand Models are Well Defined)

Assume a CRWL program $\mathcal{P}$ and the type environment $T$ such that $\operatorname{dom}(T)=$ DVar. Then:

1. $\mathcal{M}_{\mathcal{P}}(T)$ is a well-defined Herbrand algebra, in the sense of Definitions 5, 6.
2. Moreover, if $\mathcal{P}$ is well-typed, then $\mathcal{M}_{\mathcal{P}}(T)$ is also well-typed.

## Lemma 12 (Characterization Lemma)

Consider a least Herbrand model $\mathcal{M}_{\mathcal{P}}(T)$ and $\sigma_{d} \in D S u b_{\perp}$, which serves as a valuation over $\mathcal{M}_{\mathcal{P}}(T)$. Then:

1. For every $e \in \operatorname{Exp}_{\perp}: \llbracket e \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d}=\left\{t \in P a t_{\perp} \mid \mathcal{P} \vdash_{G O R C} e \sigma_{d} \rightarrow t\right\}$
2. For every approximation or joinability statement $\varphi$ :

$$
\left(\mathcal{M}_{\mathcal{P}}(T), \sigma_{d}\right) \vDash \varphi \Longleftrightarrow \mathcal{P} \vdash_{G O R C} \varphi \sigma_{d} .
$$

According to item 2 from Lemma $11, \mathcal{M}_{\mathcal{P}}(T)$ is well-typed whenever $\mathcal{P}$ is well-typed. The proof of this fact relies essentially on the subject reduction property of GORC, given by Theorem 2. According to Lemma 12, semantic validity in $\mathcal{M}_{\mathcal{P}}(T)$ behaves the same as derivability in GORC. This allows to prove the next theorem, which is the main result in this section.

## Theorem 3 (Canonicity of Least Herbrand Models)

$\mathcal{M}_{\mathcal{P}}(T) \vDash \mathcal{P}$ holds for any program $\mathcal{P}$, and for every approximation or joinability statement $\varphi$ the three following conditions are equivalent:

1. $\mathcal{P} \vdash_{G O R C} \varphi$.
2. $(\mathcal{A}, \eta) \vDash \varphi$, for all $A \vDash \mathcal{P}$ and all $\eta \in \operatorname{DefVal}(\mathcal{A})$.
3. $\left(\mathcal{M}_{\mathcal{P}}(T), i d\right) \vDash \varphi$.

A full proof of this theorem is given in the Appendix. The equivalence of items 1 and 2 shows that GORC is sound and complete for deriving those statements which hold in all models of a given program $\mathcal{P}$ under all possible totally defined valuations. The result cannot be weakened to arbitrary valuations, as shown by the statement $X \bowtie X$. Moreover, item 3 characterizes those statements in terms of truth in $\mathcal{M}_{\mathcal{P}}(T)$. Therefore, the canonic model $\mathcal{M}_{\mathcal{P}}(T)$ can be viewed as the logical semantics of $\mathcal{P}$, in analogy to the least Herbrand model of a LP program over a Herbrand universe with variables [14, 3]. Least Herbrand models of FO CRWL programs can be also characterized as least fixpoints and as free objects in a category of models $[36,18,5]$. These results could be extended to the present HO setting, but we will not dwell on this issue.

## 4 A Lazy Narrowing Calculus for Goal Solving

In this section we extend the untyped lazy narrowing calculus CLNC from [19] to prevent type errors at run time. Other existing narrowing calculi, as e.g. [42, 44, 45, 25, 48, 33], can be used as a basis for the goal solving mechanism of a HO FLP language. With the exception of [42], all these approaches deal with simply-typed $\lambda$-terms, which give rise to undecidable unification problems in the general case [17]. The calculus in [42] is designed for an untyped, $\lambda$-free setting, similarly to our former approach in [19]. The main novelty of the present approach is the treatment of polymorphic types in the context of a HO FLP language which avoids the complications related to general HO unification of $\lambda$-terms. As argued in [47], artificial incompleteness problems in narrowing calculi often arise due to an improper choice of the
semantics. This is not the case for our logical semantics from Section 3, which has been chosen to reflect the computational behaviour of lazy functions.

We recall that initial goals $G$ for CLNC are finite systems of joinability statements $a \bowtie b$. A correct solution for such a $G$ is any total data substitution $\theta_{d}$ such that $\mathcal{P} \vdash_{G O R C} a \theta_{d} \bowtie b \theta_{d}$ for all $a \bowtie b \in G$. Soundness and completeness of CLNC, as proved for untyped programs in [19], remain valid for well-typed programs. In the typed setting, however, one would like to avoid the computation of ill-typed answers, whenever the program and the initial goal are well-typed. Unfortunately, there are problematic situations where run time type errors can occur in CLNC. A first kind of problem arises when a HO logic variable $F$ occurs as head in some flexible expression $\left(F \bar{e}_{m}\right)$. In CLNC there are special transformations to guess a suitable pattern $t$ as binding for $F$ in such cases, and sometimes $t \bar{e}_{m}$ may become ill-typed. For instance, given the well-typed goal FX $\bowtie$ true, CLNC can guess the binding $\mathrm{F} \mapsto$ plus z , leading to an ill-typed goal and eventually to the ill-typed solution $\{\mathrm{F} \mapsto$ plus $\mathrm{z}, \mathrm{X} \mapsto$ true $\}$. As a second example, consider map F [true, X] $\bowtie[\mathrm{Y}, \mathrm{false}$ ]. This is also a well-typed goal, but CLNC can compute an ill-typed solution represented by the set of bindings $\{F \mapsto$ plus $z, X \mapsto$ false, $Y \mapsto$ true $\}$.

A second kind of problematic situation is related to statements $h \bar{a}_{m} \bowtie$ $h \bar{b}_{m}$, joining two rigid and passive expressions. In CLNC a decomposition transformation reduces such condition to a system of simpler conditions $a_{i} \bowtie b_{i}$. We say that such a decomposition step is transparent iff $h$ is $m$ transparent and opaque otherwise. In the case of an opaque decomposition step, some of the new conditions $a_{i} \bowtie b_{i}$ may become ill-typed. Consider for instance the two well-typed goals snd true $\bowtie$ snd $z$ and snd (map s []) $\bowtie$ snd (map not []). Both of them become ill-typed after a decomposition step. In the first case the goal is unsolvable, while in the second case the computation ultimately succeeds, in spite of the type error. Opaque decomposition steps are also possible for approximation statements $h \bar{a}_{m} \rightarrow h \bar{t}_{m}$. Moreover, guessing a binding for a logic variable $F$ which occurs as head in a flexible expression $\left(F \bar{e}_{m}\right)$, can subsequently give rise to opaque decomposition.

Unfortunately, avoiding opaque decomposition is not easy, because its eventual occurrence is undecidable, even for reasonably simple programs and goals. A proof of this result, as well as a brief discussion on the harmfulness of opaque decompositions from a practical viewpoint, can be found in Subsection 4.2 below. The other source of type errors described above, namely
the computation of ill-typed bindings logic variables, is a well-known problem. It can arise in the case of HO logic variables, and sometimes also in the case of FO logic variables (for programs which allow subtyping or do not impose transparency and type-generality requirements). Different solutions have been proposed, some of which are summarized below.

As shown in $[23,22,24]$ for the case of FO typed SLD resolution and FO typed narrowing, respectively, a goal solving procedure that works with fully type-annotated goals can detect ill-typed bindings at run time, since they cause failure at the level of type unification. For instance, when trying to solve the type-annotated goal $\left(F^{\alpha \rightarrow b o o l} \mathrm{X}^{\alpha}\right)^{\text {bool }} \bowtie$ true ${ }^{\text {bool }}$ the ill-typed binding $\mathrm{F}^{\alpha \rightarrow \text { bool }} \mapsto\left(\text { plus }^{\text {nat } \rightarrow \text { nat } \rightarrow \text { nat }} \mathrm{z}^{\text {nat }}\right)^{\text {nat } \rightarrow \text { nat }}$ would be prevented by a failure of type unification. Another possibility is to embed ad hoc mechanisms at a lower implementation level to take care of type unification problems at run time in an efficient way, as proposed in [31] for implementing polymorphic typing in the HO logic language $\lambda$-Prolog [40]. In the particular case of monomorphically typed programs, the problem is easier to solve, because no type unification is needed. In this vein, a recent paper [1] proposes a Warrenlike [49] type-preserving translation of HO programs into FO programs in a monomorphic FLP setting. This technique is useful to prune the search space and to ensure well-typed computations without dynamic type checking, but it fails to handle goals with polymorphic function-typed variables.

Full type annotations have the disadvantage that goal solving becomes more complex and less efficient, also for those computations that do not need any dynamic type checking. Therefore, some optimization techniques were proposed in $[23,22,24]$ to alleviate this difficulty. Our aim here is to adopt a less costly solution to extend CLNC with dynamic type checking, avoiding type-annotations. We use goals $G$ similar to those from [19], but extended with a type environment $T$, and the notion of solution will be also extended so that solutions can provide bindings both for the data variables occurring in $G$ and for the type variables occurring in $T$. Those CLNC transformations that must compute a binding $t$ for some HO variable $F$ will perform dynamic type checking, using type unification to ensure that the type of $t$ is compatible with $T(F)$. The CLNC transformations not related to HO variable bindings will perform no dynamic type checking. In case of a computation that involves no functional application of HO logic variables, the only overhead w.r.t. untyped CLNC consists in maintaining the type environment $T$ of the current goals, which of course evolves along the computation. This is not too costly, because all the type assumptions
needed for $T$ can be taken from the type environment of the initial goal and the type environments of the rewrite rules in the program, which are known in advance.

In the rest of this section we develop these ideas and we investigate the soundness, completeness and type preservation properties of the resulting lazy narrowing calculus. Since the eventual occurrence of opaque decomposition during a CLNC computation is undecidable, our soundness result guarantees a well-typed computed answer only under the assumption that no opaque decomposition steps have occurred in the computation. On the other hand, our completeness result only ensures the well-typed computation of those solutions whose correctness is witnessed by some type-annotated GORC proof.

### 4.1 Admissible Goals and Solutions

The lazy narrowing calculus CLNC from [19] works with goals that include both joinability statements $a \bowtie b$ to be solved and approximation statements $e \rightarrow t$ to represent delayed unifications, introduced by lazy narrowing steps. Moreover, goals in $G$ include a solved part to represent the answer data substitution computed so far, and they satisfy a number of goal invariants. Here we must extend this class of goals, adding a type environment and a second solved part to represent an answer type substitution. Those (data and type) variables of a goal that have been introduced locally by previous CLNC steps will be viewed as existential. For technical convenience, in the rest of the paper we assume a countable set of existential variables, and we use the notation $(l \rightarrow r \Leftarrow C \square T) \in_{\text {var }} \mathcal{P}$ to indicate that $(l \rightarrow r \Leftarrow C \square T)$ is a renaming of some defining rule from $\mathcal{P}$, using fresh existential type variables in $T$ and fresh existential data variables in the rewrite rule. We also write $a \asymp b$ for any one of the conditions $a \bowtie b$ or $b \bowtie a$. The formal definition of goal follows. More motivation and explanations can be found in [18, 47] for the untyped FO case.

## Definition 10 (Admissible Goals)

Admissible goals have the form $G=P \square C \square S_{d} \square S_{t} \square T$, where:

1. The delayed part $P=e_{1} \rightarrow t_{1}, \ldots, e_{k} \rightarrow t_{k}$ is a multiset of approximation statements, with $e_{i} \in E x p, t_{i} \in$ Pat. The set of produced data variables of $G$ is defined as pvar $(P)=\operatorname{var}\left(t_{1}\right) \cup \cdots \cup \operatorname{var}\left(t_{k}\right)$, and the
production relation is defined over $\operatorname{var}(G)$ by the condition $X>_{P} Y$ iff there is some $1 \leq i \leq k$ such that $X \in \operatorname{var}\left(e_{i}\right)$ and $Y \in \operatorname{var}\left(t_{i}\right)$.
2. The unsolved part $C=a_{1} \bowtie b_{1}, \ldots, a_{l} \bowtie b_{l}$ is a multiset of joinability statements. The set of demanded data variables of $G$ is defined as $d d v a r(C)=\left\{X \in D \operatorname{Var} \mid X \bar{e}_{m} \asymp b \in C\right.$, for some $\left.\bar{e}_{m}, b\right\}$.
3. The data solved part $S_{d}=\left\{X_{1} \approx s_{1}, \ldots, X_{n} \approx s_{n}\right\}$ is a set of equations in solved form, such that each $s_{i} \in$ Pat and each $X_{i}$ occurs exactly once in $P \square C \square S_{d}$. We write $\sigma_{d}$ for $m g u\left(S_{d}\right)$.
4. The type solved part $S_{t}=\left\{\alpha_{1} \approx \tau_{1}, \ldots, \alpha_{m} \approx \tau_{m}\right\}$ is a set of type equations in solved form, such that each $\tau_{i} \in$ Type and each $\alpha_{i}$ occurs exactly once in $G$. We write $\sigma_{t}$ for $m g u\left(S_{t}\right)$.
5. $T=\left\{X_{1}:: \tau_{1}, \ldots, X_{p}:: \tau_{p}\right\}$ is called the type environment of $G$. We assume that $\operatorname{var}\left(P \square C \square S_{d}\right) \subseteq\left\{X_{1}, \ldots, X_{p}\right\}=\operatorname{dom}(T)$.
6. G must fulfill the following conditions, called goal invariants:
$\mathbf{L N}$ The tuple $\left(t_{1}, \ldots, t_{k}\right)$ is linear.
EX All produced data variables are existential.
NC The transitive closure of the production relation $>_{P}$ is irreflexive.
SL No produced variable enters the solved part: $\operatorname{var}\left(S_{d}\right) \cap \operatorname{pvar}(P)=$ $\emptyset$.

Note that any admissible goal verifies $(P \square C) \sigma_{d}=(P \square C)$ and $T \sigma_{t}=$ $T$, because of the requirements in items 3 and 4 above. By convention, initial goals are of the form $G_{0}=\emptyset \square C \square \emptyset \square \emptyset \square T_{0}$, and include no existential variables.

For typing purposes, goals can be viewed as "expressions" built from variables, symbols in the current signature and binary "operations" ( $\bowtie$ ), $(\rightarrow),(\approx)$ of type $\alpha \rightarrow \alpha \rightarrow$ bool and (,) of type bool $\rightarrow$ bool $\rightarrow$ bool, used in infix notation. We say that a goal $G=P \square C \square S_{d} \square S_{t} \square T$ is well-typed iff there is some $T \leq T^{\prime}$ such that $T^{\prime} \vdash_{W T}\left(P, C, S_{d}\right)::$ bool. In addition, $G$ is called type-closed iff $T$ itself can be taken as $T^{\prime}$. More formally:

## Definition 11 (Well-typed Goals)

Consider an admissible goal $G=P \square C \square S_{d} \square S_{t} \square T$ and assume
$T R\left(T,\left(P, C, S_{d}\right)\right)=(-, E)$, where $T R$ is the type reconstruction algorithm from Subsection 2.2.

1. $G$ is called well-typed iff $\operatorname{TSol}(E) \neq \emptyset$. If this is the case, we write $\hat{\sigma}_{t}=\operatorname{mgu}\left(S_{t}, E\right), \hat{T}=T \hat{\sigma}_{t}$ and $\hat{G}=P \square C \square S_{d} \square \hat{S}_{t} \square \hat{T}$.
2. A well-typed goal $G$ is called type-closed iff $T=\hat{T}$. In the case that $G$ is well-typed, but not type-closed, $\hat{G}$ is called the type closure of $G$.

Note that a well-typed goal is not always type-closed, as shown next.

## Example 7 (Type-closure of a Well-typed Goal)

1. A well-typed goal which is not type-closed:

$$
G=\emptyset \square \mathrm{FX} \mathrm{X} \text { true } \square \emptyset \square \emptyset \square\left\{\mathrm{X}:: \alpha_{1}, \mathrm{~F}:: \alpha_{1} \rightarrow \alpha\right\} .
$$

2. Its type-closure:

$$
\hat{G}=\emptyset \square \mathrm{FX} \bowtie \operatorname{true} \square \emptyset \square \alpha \approx \operatorname{bool} \square\left\{\mathrm{X}:: \alpha_{1}, \mathrm{~F}:: \alpha_{1} \rightarrow \text { bool }\right\} .
$$

The following technical lemma gives a useful characterization of welltyped goals. A proof is included in the Appendix.

## Lemma 13 (Characterization of Well-typed Goals)

For any admissible goal $G=P \square C \square S_{d} \square S_{t} \square T$, the three following conditions are equivalent:
(a) $G$ is well-typed.
(b) There is some $T \leq T^{\prime}$ such that $T^{\prime} \vdash_{W T}\left(P, C, S_{d}\right)::$ bool.
(c) There is some $T \leq T^{\prime}$ such that
(c1) For every $(e \rightarrow t) \in P$ there is some type $\tau$ such that $T^{\prime} \vdash_{W T} e:: \tau$, $T^{\prime} \vdash_{W T} t:: \tau$.
(c2) For every $(a \bowtie b) \in C$ there is some type $\tau$ such that $T^{\prime} \vdash_{W T} a:: \tau$, $T^{\prime} \vdash_{W T} b:: \tau$.
(c3) For every $(X \approx t) \in S_{d}, T^{\prime} \vdash_{W T} t:: \tau$, where $\tau=T^{\prime}(X)$.
Moreover, $T^{\prime}$ can be always chosen as $\hat{T}$, if it exists.

In the sequel, the notation $T \vdash_{W T} G$ will abbreviate $T \vdash_{W T}\left(P, C, S_{d}\right)::$ bool. According to Lemma 13, this indicates that $G$ is well-typed and typeclosed. Similarly, the abbreviation $\hat{T} \vdash_{W T} G$ can be used to indicate that $G$ is a well-typed goal.

Next, we define solutions of admissible goals. According to our definition, solutions are proved to be correct by means of certain GORC proofs, called witnesses.

## Definition 12 (Solutions and Well-typed Solutions)

Let $G=P \square C \square S_{d} \square S_{t} \square T$ be an admissible goal for a program $\mathcal{P}$.

1. A solution of $G$ is any data substitution $\theta_{d} \in D S u b_{\perp}$ satisfying the following conditions:
(a) $\theta_{d}(X)$ is a total pattern, for all $X \in \operatorname{dom}\left(\theta_{d}\right) \backslash \operatorname{pvar}(P)$.
(b) $\theta_{d} \in \operatorname{Sol}\left(S_{d}\right)$.
(c) $\mathcal{P} \vdash_{G O R C}(P \square C) \theta_{d}$, intended to mean that $\mathcal{P} \vdash_{G O R C} \varphi \theta_{d}$ must hold for all $\varphi \in P \cup C$.
2. We write $\operatorname{Sol}(G)$ for the set of all the solutions of $G$. Any multiset $\mathcal{M}$ containing one GORC proof for each statement $\varphi \theta_{d}, \varphi \in P \cup C$, is called $a$ witness for $\theta_{d} \in \operatorname{Sol}(G)$.
3. $A$ well-typed solution of $G$ is any pair $(R, \theta)$ formed by a type environment $R$ and a substitution $\theta=\left(\theta_{t}, \theta_{d}\right)$ such that
(a) $\theta_{d} \in \operatorname{Sol}(G)$.
(b) $\operatorname{dom}(R) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T)$.
(c) $\theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$.
(d) $\left(T \theta_{t} \cup R\right) \vdash_{W T} T \theta$, intended to mean that $\left(T \theta_{t} \cup R\right) \vdash_{W T} X \theta_{d}:: \tau \theta_{t}$ must hold for all $(X:: \tau) \in T$.
4. We write $W T S o l(G)$ for the set of all the well-typed solutions of $G$. A witness for $(R, \theta)$ is defined simply as a witness for $\theta \in \operatorname{Sol}(G)$.

Items 1 and 2 in the previous definition correspond essentially to our former notion of solution in the untyped setting from [19]. The rôle of the type environment $R$ in well-typed solutions is to provide type assumptions for the new data variables introduced in $\operatorname{ran}\left(\theta_{d}\right)$; see item 3 in the definition.

Of course, ill-typed goals can have solutions, in the sense of items 1 and 2. More strangely perhaps, some ill-typed goals have well-typed solutions. For example $R=\emptyset, \theta_{t}=\emptyset$ and $\theta_{d}=\emptyset$ give a well-typed solution for the ill-typed goal $G=\emptyset$ 口 tail [z] $\bowtie$ tail [true] $\square \emptyset \square \emptyset \square \emptyset$.

In the case of well-typed solutions of well-typed goals, one expects the goal to remain well-typed when the solution is applied to it. As shown by the next lemma (proved in the Appendix) this can be guaranteed only for type-closed goals.

## Lemma 14 (Well-typed Solutions and Type-closure)

1. For any well-typed goal $G$, $W T S o l(\hat{G}) \subseteq W T S o l(G)$. The opposite inclusion is false in general.
2. Assume a well-typed and type-closed goal $G$ and $(R, \theta) \in W T S o l(G)$. Then $\left(T \theta_{t} \cup R\right) \vdash_{W T} G \theta_{d}$. In particular, for all $(a \bowtie b) \in C$ there is some $\tau^{\prime} \in$ Type such that $\left(T \theta_{t} \cup R\right) \vdash_{W T} a \theta_{d}:: \tau^{\prime}$ and $\left(T \theta_{t} \cup R\right) \vdash_{W T}$ $b \theta_{d}:: \tau^{\prime}$ (and analogously for $(e \rightarrow t) \in P$ and $\left.(X \approx t) \in S_{d}\right)$. These claims can fail if $G$ is not type-closed.

In view of the previous lemma, we restrict our attention to well-typed solutions of well-typed and type-closed goals. We are also interested in typeannotated witnesses for such solutions, in the sense of the following definition:

## Definition 13 (Type-annotated Witness)

Assume a well-typed and type-closed goal $G=P \square C \square S_{d} \square S_{t} \square T$ for a well-typed program $\mathcal{P}$. A type-annotated witness of $(R, \theta) \in W T S o l(G)$, if it exists, is obtained by considering the principal type annotation $(P \square C)^{b o o l}$ with implicit type environment $T$, and taking a multiset $\mathcal{M}$ of type-annotated GORC proofs for the type-annotated statement in $(P \square C)^{b o o l} \theta$. Note that the type-annotated "expression" $(P \square C)^{b o o l} \theta$ makes sense because of Lemma 5, and has implicit type environment $T \theta_{t} \cup R$.

In the sequel, we write $\operatorname{TASol}(G)$ for the set of all $(R, \theta) \in W T S o l(G)$ which have a type-annotated witness. Trivially, $\operatorname{TASol}(G) \subset W T S o l(G)$. However, the inclusion is strict, as shown by the next example.

## Example 8 (Type-annotated Witness)

Consider:

$$
\begin{aligned}
& G=\emptyset \square \operatorname{snd}(\operatorname{tail}[\mathrm{X}]) \bowtie \text { snd (tail }[\mathrm{Y}]) \square \emptyset \square \emptyset \square \\
& \left\{\mathrm{X}:: \alpha_{1}, \mathrm{Y}:: \alpha_{2}\right\},
\end{aligned}
$$

$R=\emptyset, \theta_{t}=\left\{\alpha_{1} \mapsto\right.$ nat, $\left.\alpha_{2} \mapsto \mathrm{bool}\right\}$ and $\theta_{d}=\{\mathrm{X} \mapsto \mathbf{z}, \mathrm{Y} \mapsto$ true $\}$. Note that $G$ is well-typed and type-closed, and $(R, \theta) \in \operatorname{WTSol}(G)$. However, no type-annotated witness exists due to Example 6(b).

As we will see in the next subsection, maintaining type-closed goals during CLNC computations would be as expensive as working with fully typeannotated goals. Therefore, CLNC is designed to avoid the computation of type closures whenever possible.

### 4.2 Lazy Narrowing Calculus

Now we are ready to extend the lazy narrowing calculus CLNC from [19] with dynamic type checking. We keep CLNC as the name of the new calculus. As in [19], the notation $G H_{C L N C} G^{\prime}$ means that $G$ is transformed into $G^{\prime}$ in one step. The aim when using CLNC is to transform a well-typed, type-closed initial goal $G_{0}=\emptyset \square C \square \emptyset \square \emptyset \square T_{0}$ into a well-typed solved goal $G_{n}=$ $\emptyset \square \emptyset \square S_{d} \square S_{t} \square T_{n}$ with type closure $\hat{G}_{n}=\emptyset \square \emptyset \square S_{d} \square \hat{S}_{t} \square \hat{T}_{n}$, and to return $\left(T_{n} \hat{\sigma}_{t} \backslash T_{0} \hat{\sigma}_{t},\left(\hat{\sigma}_{t}, \sigma_{d}\right)\right)$ as the answer computed for $G_{0}$. A sequence of transformation steps $G_{0} \mathbb{H}_{C L N C} \cdots H_{C L N C} G_{n}$ going from an initial goal $G_{0}$ to a solved goal $G_{n}$, is called CLNC derivation and noted as $G_{0} H^{*}{ }_{C L N C} G_{n}$. Due to Lemma 14, it is relevant to assume type-closedness for the initial goal $G_{0}$ and to compute the type closure of the final goal $G_{n}$ before extracting the computed answer. Some intermediate goals $G_{i}$ may be not type-closed, but nevertheless they stand for their closures $\hat{G}_{i}$ for the purpose of considering potential solutions. The need to include the type environments $\left(T_{n} \hat{\sigma}_{t} \backslash T_{0} \hat{\sigma}_{t}\right)$ as part of computed answers will be justified in Subsection 4.3.

Due to the convention that $P$ and $C$ are understood as multisets, CLNC assumes no particular selection strategy for choosing the goal statement to be processed in the next step. For writing failure rules we use FAIL, representing an irreducible inconsistent goal. We also use some hopefully selfexplanatory abbreviations for tuples. In particular, $\bar{a}_{m} \bowtie \bar{b}_{m}$ stands for $m$ new joinability statements $a_{i} \bowtie b_{i}$, and similarly for approximation statements. According to the notations introduced in Definition 10, CLNC rules
rely on the convention that $S_{t}^{\prime}$ is the set of type equations in solved form representing the unifier $\sigma_{t}^{\prime}$. Moreover, some CLNC rules use the notation "[...]" meaning an optional part of a goal, present only under certain conditions. Some other rules refer to the set svar(e) of those data variables that occur in $e$ at some position outside the scope of evaluable function calls. Formally, $\operatorname{svar}(X)=\{X\}$ for any data variable $X$; for a rigid and passive expression $e=h \bar{e}_{m}, \operatorname{svar}(e)=\bigcup_{i=1}^{m} \operatorname{svar}\left(e_{i}\right) ;$ and $\operatorname{svar}(e)=\emptyset$ in any other case.

In spite of their complex appearance, CLNC transformation rules are natural in the sense that they are designed to guess the shape of GORC derivations step by step. For instance, the transformations NR1 and GN guess the shape of OR steps in GORC proofs. As a lazy narrowing calculus, CLNC emulates suspensions and sharing by means of the approximation statements in the delayed part of goals. This and other interesting features regarding occurs check and safe cases for eager variable elimination, have been discussed briefly in [19] for the untyped HO case, and more widely in $[18,47]$ for the untyped FO case. Here we focus on the treatment of dynamic type checking. Each CLNC transformation has attached certain side conditions, labelled with the symbols $\bullet$, * and $\circ$, that must be checked before applying the transformation to the current goal $G$. In particular, those CLNC transformations whose name is marked with $\star$ have a side condition of type o that performs dynamic type checking. In all such cases, there is a candidate binding $X \mapsto t$ for some HO variable $X$. The type $T(X)$ assumed for $X$ in the current goal's environment is compared to the principal type of $t$ by means of type unification. In case of success, the type solved part of the goal is properly actualized, and the CLNC step can be performed. In case of failure, the CLNC step is forbidden for the particular binding $X \mapsto t$. Of course, this does not exclude the possibility to try a different application of the same CLNC transformation, with a different binding.

## The CLNC Calculus

## Rules for the Unsolved Part

Identity \& Decomposition (ID) $\star(p \geq 0)$

$$
\begin{aligned}
& P \square X \bar{a}_{p} \asymp X \bar{b}_{p}, C \square S_{d} \square S_{t} \square T \\
& H \quad\left(P \square \bar{a}_{p} \asymp \bar{b}_{p}, C \square S_{d}\right)\left[\rho_{d}, X \approx h \bar{V}_{m}\right] \square S_{t}^{\prime} \square\left(\left[\bar{V}_{m}:: \bar{\tau}_{m}\right], \hat{T}\right) \sigma_{t}^{\prime}
\end{aligned}
$$

- $X \notin \operatorname{pvar}(P)$.
- $p=0$ and $S_{t}^{\prime}=S_{t}$; or $\left[p>0, m \geq 0, h \bar{V}_{m} \bar{a}_{p}\right.$ rigid and passive; $\bar{V}_{m}$ fresh existential variables; $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau \approx \tau^{\prime}\right)$ where $\tau^{\prime}=\hat{T}(X)$, $h:: \bar{\tau}_{m} \rightarrow \tau \in_{\text {var }} \Sigma$.
* $\rho_{d}=\left\{X \mapsto h \bar{V}_{m}\right\}$.]


## Decomposition (DC1)

$$
\begin{aligned}
& P \square h \bar{a}_{m} \asymp h \bar{b}_{m}, C \square S_{d} \square S_{t} \square T \\
& H \quad P \square \bar{a}_{m} \asymp \bar{b}_{m}, C \square S_{d} \square S_{t} \square T
\end{aligned}
$$

- $h \bar{a}_{m}, h \bar{b}_{m}$ rigid and passive.


## Binding \& Decomposition (BD) $\star(k \geq 0)$

$$
\begin{aligned}
& P \square X \bar{a}_{k} \asymp s \bar{b}_{k}, C \square S_{d} \square S_{t} \square T \\
& H \quad\left(P \square \bar{a}_{k} \asymp \bar{b}_{k}, C \square S_{d}\right) \rho_{d}, X \approx s \square S_{t}^{\prime} \square \hat{T} \sigma_{t}^{\prime}
\end{aligned}
$$

- $s \in P a t ; X \notin \operatorname{var}(s) ; X \notin \operatorname{par}(P) ; \operatorname{var}(s) \cap \operatorname{pvar}(P)=\emptyset$.
* $\rho_{d}=\{X \mapsto s\}$.
- $k=0$ and $S_{t}^{\prime}=S_{t}$; or $k>0, s \bar{b}_{k}$ rigid and passive, and $\sigma_{t}^{\prime}=m g u\left(\hat{S}_{t}, \tau \approx\right.$ $\tau^{\prime}$ ) where $\tau=\hat{T}(X), \tau^{\prime}$ type-annotation of $s$ in $\operatorname{PA}\left(\hat{T}, s \bar{b}_{k}\right)$.


## Imitation \& Decomposition (IM) $\star(k \geq 0)$

$$
\begin{aligned}
& P \square X \bar{a}_{k} \asymp h \bar{e}_{m} \bar{b}_{k}, C \square S_{d} \square S_{t} \square T \\
& H \quad\left(P \square \bar{V}_{m} \bar{a}_{k} \asymp \bar{e}_{m} \bar{b}_{k}, C \square S_{d}\right) \rho_{d}, X \approx h \bar{V}_{m} \square S_{t}^{\prime} \\
& \quad\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}
\end{aligned}
$$

- $h \bar{e}_{m} \bar{b}_{k}$ rigid and passive; $X \notin \operatorname{pvar}(P) ; X \notin \operatorname{svar}\left(h \bar{e}_{m}\right) ; \bar{V}_{m}$ fresh existential variables; BD not applicable.
* $\rho_{d}=\left\{X \mapsto h \bar{V}_{m}\right\}$.
- $k=0$ and $S_{t}^{\prime}=S_{t}$; or $k>0$ and $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau \approx \tau^{\prime}\right)$ where $\tau^{\prime}=\hat{T}(X)$, $h:: \bar{\tau}_{m} \rightarrow \tau \in_{\text {var }} \Sigma$.

Outer Narrowing (NR1) ( $k \geq 0)$

$$
\begin{aligned}
& P \square f \bar{e}_{n} \bar{a}_{k} \asymp b, C \square S_{d} \square S_{t} \square T \\
& H \quad \bar{e}_{n} \rightarrow \bar{t}_{n}, P \square C^{\prime}, r \bar{a}_{k} \asymp b, C \square S_{d} \square S_{t} \square T^{\prime}, T
\end{aligned}
$$

- $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}\right) \in_{\text {var }} \mathcal{P}$.

Guess \& Outer Narrowing (GN) $\star(k \geq 0)$

$$
\begin{aligned}
& P \square X \bar{e}_{q} \bar{a}_{k} \asymp b, C \square S_{d} \square S_{t} \square T \\
& H \quad\left(\bar{e}_{q} \rightarrow \bar{s}_{q}, P \square C^{\prime}, r \bar{a}_{k} \asymp b, C \square S_{d}\right) \rho_{d}, X \approx f \bar{t}_{p} \square S_{t}^{\prime} \square \\
& \quad\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime}
\end{aligned}
$$

- $q>0 ; X \notin \operatorname{pvar}(P) ;\left(f \bar{t}_{p} \bar{s}_{q} \rightarrow r \Leftarrow C^{\prime}\right.$ ם $\left.T^{\prime}\right) \in_{v a r} \mathcal{P}$.
* $\rho_{d}=\left\{X \mapsto f \bar{t}_{p}\right\}$.
- $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau^{\prime} \approx \bar{\lambda}_{q} \rightarrow \tau\right)$ where $\left(f:: \bar{\tau}_{p} \rightarrow \bar{\lambda}_{q} \rightarrow \tau\right) \in_{v a r} \Sigma, \tau^{\prime}=$ $\hat{T}(X)$.


## Guess \& Decomposition (GD)

$$
\begin{aligned}
& P \square X \bar{a}_{p} \asymp Y \bar{b}_{q}, C \square S_{d} \square S_{t} \square T \\
& H \quad\left(P \square \bar{V}_{m-p}, \bar{a}_{p} \asymp \bar{W}_{m-q} \bar{b}_{q}, C \square S_{d}\right) \rho_{d}, X \approx h \bar{V}_{m-p}, \\
& \quad Y \approx h \bar{W}_{m-q} \square S_{t}^{\prime} \square\left(\bar{V}_{m-p}::{\overline{\tau^{\prime}}}_{m-p}, \bar{W}_{m-q}::{\overline{\tau^{\prime \prime}}}_{m-q}, \hat{T}\right) \sigma_{t}^{\prime}
\end{aligned}
$$

- $p+q>0 ; X, Y$ different; $X, Y \notin \operatorname{pvar}(P) ; \bar{V}_{m-p}, \bar{W}_{m-q}$ fresh existential variables; $\left(h \bar{V}_{m-p} \bar{a}_{p}\right),\left(h \bar{W}_{m-q} \bar{b}_{q}\right)$ rigid and passive.
* $\rho_{d}=\left\{X \mapsto h \bar{V}_{m-p}, Y \mapsto h \bar{W}_{m-q}\right\}$.
- $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau^{\prime} \approx \overline{\lambda^{\prime}} \rightarrow \tau_{0}^{\prime}, \tau^{\prime \prime} \approx \overline{\lambda^{\prime \prime}}{ }_{q} \rightarrow \tau_{0}^{\prime \prime}\right)$ where $\tau^{\prime}=\hat{T}(X)$, $\tau^{\prime \prime}=\hat{T}(Y),\left(h::{\overline{\tau^{\prime}}}_{m-p} \rightarrow{\overline{\lambda^{\prime}}}_{p} \rightarrow \tau_{0}^{\prime}\right),\left(h::{\overline{\tau^{\prime \prime}}}_{m-q} \rightarrow \overline{\lambda^{\prime \prime}}{ }_{q} \rightarrow \tau_{0}^{\prime \prime}\right) \in_{v a r} \Sigma$, two fresh variants of the principal type of $h$, sharing no type variables.


## Conflict (CF1)

$$
P \square h \bar{a}_{p} \asymp h^{\prime} \bar{b}_{q}, C \square S_{d} \square S_{t} \square T \quad H \quad \text { FAIL }
$$

- $h \neq h^{\prime}$ or $p \neq q ; h \bar{a}_{p}, h^{\prime} \bar{b}_{q}$ rigid and passive.


## Cycle (CY)

$$
P \square X \asymp a, C \square S_{d} \square S_{t} \square T \quad H \quad \text { FAIL }
$$

- $X \neq a$ and $X \in \operatorname{svar}(a)$.


## Rules for the Delayed Part

## Decomposition (DC2)

$$
\begin{aligned}
& h \bar{e}_{m} \rightarrow h \bar{t}_{m}, P \square C \square S_{d} \square S_{t} \square T \\
& H \quad \bar{e}_{m} \rightarrow \bar{t}_{m}, P \square C \square S_{d} \square S_{t} \square T
\end{aligned}
$$

- $h \bar{e}_{m}$ rigid and passive.


## Output Binding \& Decomposition (OB) $\star(k \geq 0)$

$$
X \bar{e}_{k} \rightarrow h \bar{t}_{m} \bar{s}_{k}, P \square C \square S_{d} \square S_{t} \square T
$$

$H \quad\left(\bar{e}_{k} \rightarrow \bar{s}_{k}, P \square C \square S_{d}\right) \rho_{d},\left[X \approx h \bar{t}_{m}\right] \square S_{t}^{\prime} \square \hat{T} \sigma_{t}^{\prime}$

- $[X \notin \operatorname{pvar}(P)$.
* $\rho_{d}=\left\{X \mapsto h \bar{t}_{m}\right\}$.
- $k=0$ and $S_{t}^{\prime}=S_{t}$; or $k>0$ and $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau \approx \tau^{\prime}\right)$ where $\tau^{\prime}=\hat{T}(X)$, $\left(h:: \bar{\tau}_{m} \rightarrow \tau\right) \in_{\text {var }} \Sigma$.

Input Binding (IB)

$$
t \rightarrow X, P \square C \square S_{d} \square S_{t} \square T
$$

$$
\Vdash \quad(P \square C) \rho_{d} \square S_{d} \square S_{t} \square T
$$

- $t \in$ Pat.
* $\rho_{d}=\{X \mapsto t\}$.

Input Imitation (IIM)

$$
\begin{aligned}
& h \bar{e}_{m} \rightarrow X, P \square C \square S_{d} \square S_{t} \square T \\
& H \quad\left(\bar{e}_{m} \rightarrow \bar{V}_{m}, P \square C\right) \rho_{d} \square S_{d} \square S_{t} \square\left(\bar{V}_{m}:: \bar{\tau}_{m}\right), T
\end{aligned}
$$

- $h \bar{e}_{m} \notin$ Pat rigid and passive; $X \in \operatorname{ddvar}(C) ; \bar{V}_{m}$ fresh existential variables.
* $\rho_{d}=\left\{X \mapsto h \bar{V}_{m}\right\}$.
- $\left(h:: \bar{\tau}_{m} \rightarrow \tau\right) \in_{v a r} \Sigma$.


## Elimination (EL)

$$
\begin{aligned}
& e \rightarrow X, P \square C \square S_{d} \square S_{t} \square T \\
& H P P \square C \square S_{d} \square S_{t} \square T
\end{aligned}
$$

- $X \notin \operatorname{var}(P$ व $C)$.

Outer Narrowing (NR2) ( $k \geq 0$ )

$$
\begin{aligned}
& f \bar{e}_{n} \bar{a}_{k} \rightarrow t, P \square C \square S_{d} \square S_{t} \square T \\
& +\bar{e}_{n} \rightarrow \bar{t}_{n}, r \bar{a}_{k} \rightarrow t, P \square C^{\prime}, C \square S_{d} \square S_{t} \square T^{\prime}, T
\end{aligned}
$$

- $(t \notin D \operatorname{Var}$ or $t \in \operatorname{ddvar}(C)) ;\left(f \bar{t}_{n} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}\right) \in_{v a r} \mathcal{P}$.


## Output Guess \& Outer Narrowing (OGN) $\star(k \geq 0)$

$X \bar{e}_{q} \bar{a}_{k} \rightarrow t, P \square C \square S_{d} \square S_{t} \square T$
$H \quad\left(\bar{e}_{q} \rightarrow \bar{s}_{q}, r \bar{a}_{k} \rightarrow t, P \square C^{\prime}, C \square S_{d}\right) \rho_{d},\left[X \approx f \bar{t}_{p}\right] \square S_{t}^{\prime} \square$ $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime}$

- $q>0 ;[X \notin \operatorname{pvar}(P)] ;\left(f \bar{t}_{p} \bar{s}_{q} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}\right) \in_{v a r} \mathcal{P} ; t \notin D V a r$ or $t \in d d v a r(C)$.
* $\rho_{d}=\left\{X \mapsto f \bar{t}_{p}\right\}$.
- $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau^{\prime} \approx \bar{\lambda}_{q} \rightarrow \tau\right)$ where $\left(f:: \bar{\tau}_{p} \rightarrow \bar{\lambda}_{q} \rightarrow \tau\right) \in_{v a r} \Sigma, \tau^{\prime}=$ $\hat{T}(X)$.


## Output Guess \& Decomposition (OGD)

$X \bar{e}_{q} \rightarrow Y, P \square C \square S_{d} \square S_{t} \square T$
$H \quad\left(\bar{e}_{q} \rightarrow \bar{W}_{q}, P \square C \square S_{d}\right) \rho_{d},\left[X \approx h \bar{V}_{p}\right] \square S_{t}^{\prime} \square$ $\left(\bar{V}_{p}:: \bar{\tau}_{p}, \bar{W}_{q}:: \bar{\lambda}_{q}, \hat{T}\right) \sigma_{t}^{\prime}$

- $q>0 ; \underline{Y} \in \operatorname{ddvar}(C) ;[X \notin \operatorname{pvar}(P)] ; \bar{V}_{p}, \bar{W}_{q}$ fresh existential variables; $\left(h \bar{V}_{p} \bar{W}_{q}\right)$ rigid and passive.
* $\rho_{d}=\left\{X \mapsto h \bar{V}_{p}, Y \mapsto\left(h \bar{V}_{p} \bar{W}_{q}\right)\right\}$.
- $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau^{\prime} \approx \bar{\lambda}_{q} \rightarrow \tau, \tau^{\prime \prime} \approx \tau\right)$ where $\left(h:: \bar{\tau}_{p} \rightarrow \bar{\lambda}_{q} \rightarrow \tau\right) \in_{\text {var }} \Sigma$, $\tau^{\prime}=\hat{T}(X), \tau^{\prime \prime}=\hat{T}(Y)$.


## Conflict (CF2)

$$
h \bar{a}_{p} \rightarrow h^{\prime} \bar{t}_{q}, P \square C \square S_{d} \square S_{t} \square T \quad H \quad \text { FAIL }
$$

- $h \neq h^{\prime}$ or $p \neq q ; h \bar{a}_{p}$ rigid and passive.

There is a simple relationship between the current presentation of CLNC and the untyped version from [19]. Dropping $S_{t} \square T$ from our current goals, and omitting all the side conditions which refer to types in our current CLNC transformations, gives back essentially the untyped goals and the CLNC transformations from [19], except for some minor modifications which we found convenient to introduce while working out the present soundness and completeness results. Due to this fact, the soundness and completeness results given for untyped CLNC in [19] are still valid in our present setting, with respect to "forgetful" CLNC derivations which omit dynamic checking. Of course, we are presently not interested in such untyped derivations, and the current CLNC transformations are intended for well-typed goals. Moreover, the CLNC transformations marked with $\star$ must be applied to the type closure $\hat{G}$ of the current goal $G$, rather than to $G$ itself, in the case that $G$ is not type-closed. For this reason, the formulation of the $\star$ transformations uses $\hat{S}_{t}$ and $\hat{T}$, rather than $S_{t}$ and $T$, for building the transformed goal. This caution is very important, because several CLNC transformations do not preserve type-closedness of goals, and the type environment in a type-closed goal bears more precise information in general. Therefore, for goals $G \neq \hat{G}$, the direct application of $\star$ to $G$ may leave some type errors undetected. In the case of CLNC derivations involving no functional applications of HO logic variables, $\star$ transformations are never applied, and the costly computation of type closures can be avoided.

Note that even the $\boldsymbol{\star}$ transformations do not perform dynamic type checking in some cases, as indicated in their formulation. For instance, ID in the case $p=0$ simply eliminates an identity $X \bowtie X$ from the current goal. Similar comments apply to BD, IM and OB in the case $k=0$.

At this point, we can prove that the detection of eventual opaque decomposition in CLNC computations is an undecidable problem. More precisely,
let us define the $\underline{O}$ paque $\underline{\text { Decomposition } \underline{P r o b l e m ~(O D P, ~ f o r ~ s h o r t) ~ a s ~ f o l l o w s: ~}}$ given a well-typed CRWL program $\mathcal{P}$ and a well-typed and type-closed initial goal $G$ for $\mathcal{P}$, tell if solving $G$ w.r.t. $\mathcal{P}$ by using CLNC can eventually lead to an opaque decomposition step. The next theorem, proved in the Appendix, shows that the restriction of ODP to a quite simple class of programs and goals is undecidable.

## Theorem 4 (Undecidability of ODP)

Let us say that a CRWL program $\mathcal{P}$ is simple iff all the defining rules in $\mathcal{P}$ are unconditional and have data terms as patterns in their left-hand sides. Analogously, let us consider simple initial goals of the form $\emptyset \square f \bar{t}_{n} \bowtie$ $g \bar{s}_{m} \square \emptyset \square \emptyset \square \emptyset$, where $f \in F S^{n}, g \in F S^{m}$ and $t_{i}$, $s_{j}$ are closed data terms. Then, the restriction of ODP to simple programs and simple initial goals is undecidable.

Note that Theorem 4 does not mean that CLNC is useless for the purpose of avoiding ill-typed computations. Type errors due to ill-typed bindings of HO logic variables are always avoided. Regarding type errors due to opaque decompositions, our feeling is that they occur rarely in practice. Obviously, the opaque decomposition problem cannot arise in FO CRWL programs, where transparent data terms are always used in place of possibly opaque patterns. In fact, type preservation results for lazy narrowing computations in such a setting are known [5, 4]. Beyond the FO case (which includes, of course, FO logic programming) opaque decompositions are possible, but sometimes they do not cause any type errors. We conjecture that the impossibility of run-time type errors due to opaque decomposition can be formally proved for a restricted subclass of HO CRWL programs and goals. More precisely, we have in mind the class of simple (but possible higher-order) programs used in the proof of Theorem 4, and goals of the form $\emptyset \square e \bowtie R \square \emptyset \square \emptyset \square\{R:: \tau\}$ where $e$ is a closed expression of type $\tau$. This essentially corresponds to pure functional programming.

To investigate the previous conjecture is beyond the scope of this paper. In any case, an actual implementation of CLNC could (and should) raise a warning to the user whenever some opaque decomposition step has occurred during the computation. This may (but not must) indicate a run time type error.

The soundness and completeness of CLNC are investigated in subsection 4.3. In the rest of this subsection we illustrate the behaviour of CLNC
by means of examples, all of them using well-typed functions defined in the program from Example 2. Some of the examples present a complete CLNC derivation. In such cases, the initial goal is always well-typed and typeclosed, and the part of the current goal which is transformed at each step is underlined.

Our first example shows that type-closedness of goals is not invariant under CLNC transformations. It can be lost because of an opaque decomposition step, as in item (a), or also because of a narrowing step, as in item (b). In the derivation (b), the new goal is not type closed because the principal type of the defined function head (introduced by the narrowing step) has not been unified with the type expected by the goal's environment. In both cases, the final solved goal must be type-closed before extracting the computed answer, which would be not a well-typed solution otherwise.

## Example 9 (Type-closedness of Goals is not CLNC Invariant)

(a) Opaque Decomposition

$$
\begin{aligned}
& G_{0}=\emptyset \square \operatorname{snd} \mathrm{X} \bowtie \operatorname{snd} \mathrm{Y} \square \emptyset \square \emptyset \square\{\mathrm{X}:: \alpha, \mathrm{Y}:: \beta\} \quad H_{\mathrm{DC} 1} \\
& G_{1}=\emptyset \square \overline{\mathrm{X} \bowtie \mathrm{Y}} \square \emptyset \square \emptyset \square\{\mathrm{X}:: \alpha, \mathrm{Y}:: \beta\} H_{\mathrm{BD}} \\
& G_{2}=\emptyset \square \overline{\emptyset \square \mathrm{X} \approx \mathrm{Y} \square \emptyset \square\{\mathrm{X}:: \alpha, \mathrm{Y}:: \beta\} \quad \neq} \\
& \hat{G}_{2}=\emptyset \square \emptyset \square \mathrm{X} \approx \mathrm{Y} \square \alpha \approx \beta \square\{\mathrm{X}, \mathrm{Y}:: \beta\}
\end{aligned}
$$

Computed answer, restricted to variables in $G_{0}$ :

$$
(\emptyset,(\{\alpha \mapsto \beta\},\{\mathrm{X} \mapsto \mathrm{Y}\})) .
$$

(b) Outer Narrowing

$$
\begin{aligned}
& G_{0}=\emptyset \square \text { head L } \bowtie \mathrm{H} \square \emptyset \square \emptyset \square\{\mathrm{~L}::[\alpha], \mathrm{H}:: \alpha\} H_{\mathrm{NR} 1} \\
& G_{1}=\mathrm{L} \rightarrow[\mathrm{X} \mid \mathrm{Xs}] \square \mathrm{X} \bowtie \mathrm{H} \square \emptyset \square \emptyset \square \\
& \{\mathrm{~L}::[\alpha], \mathrm{H}:: \alpha, \mathrm{Xs}::[\beta], \mathrm{X}:: \beta\} H^{\text {ов }} \\
& G_{2}=\emptyset \square \mathrm{X} \bowtie \mathrm{H} \square \mathrm{~L} \approx[\mathrm{X} \mid \mathrm{Xs}] \square \emptyset \square \\
& \{\mathrm{L}::[\alpha], \mathrm{H}:: \alpha \text {, Xs :: }[\beta], \mathrm{X}:: \beta\} \quad H_{\text {BD }} \\
& G_{3}=\emptyset \square \emptyset \square \mathrm{L} \approx[\mathrm{H} \mid \mathrm{Xs}], \mathrm{X} \approx \mathrm{H} \square \emptyset \square \\
& \{\mathrm{~L}::[\alpha], \mathrm{H}:: \alpha, \mathrm{Xs}::[\beta], \mathrm{X}:: \beta\} \neq \\
& \hat{G}_{3}=\emptyset \square \emptyset \square \mathrm{L} \approx[\mathrm{H} \mid \mathrm{Xs}], \mathrm{X} \approx \mathrm{H} \square \beta \approx \alpha \square \\
& \{\mathrm{~L}::[\alpha], \mathrm{H}:: \alpha, \mathrm{Xs}::[\alpha], \mathrm{X}:: \alpha\}
\end{aligned}
$$

Computed answer, restricted to variables in $G_{0}$ :

$$
(\{\mathrm{Xs}::[\alpha]\},(\emptyset,\{\mathrm{L} \mapsto[\mathrm{H} \mid \mathrm{Xs}]\})) .
$$

Our second example shows a complete CLNC derivation where no HO variables occur and no dynamic type checking is needed.

## Example 10 (A Well-typed Computation without Dynamic Type Checking)

```
G
(plus X) }->\textrm{F},[\textrm{Y}|[]]->[X1|X1s] ם [F X1|map F X1s] \bowtie [s z]
```



```
Y }->\mathrm{ X1, [] }->\mathrm{ X1s ם [(plus X) X1|map (plus X) X1s] ฝ [s z] ם Ø
```



```
\emptyset\square[plus XY|map (plus X)[]]\bowtie[sz|[]] व\emptyset\square\emptyset\square
```




```
    {X,Y :: nat; X1s :: [\alpha]; X1 :: \alpha; F :: \alpha -> \beta} H
X }->\mathrm{ (s X2), Y }->\textrm{Y}2\mathrm{ ם s(plus X2 Y2) ฝ s z, map (plus X) [] ฝ []
        \square\emptyset\square\emptyset\square{X,Y, X2, Y2 :: nat; X1s :: [\alpha]; X1 :: \alpha; F :: \alpha -> \beta}
        H
    \emptyset\squares(plus X2 Y)\bowties z, map (plus(s X2)) [] \ [] व X \approx s X2 ם
    \emptyset { X,Y, X2, Y2 :: nat; X1s :: [\alpha]; X1 :: \alpha; F :: \alpha -> \beta} 壮 DC1
```



```
        {X,Y,X2, Y2 :: nat; X1s :: [\alpha]; X1 :: \alpha; F :: \alpha 
    X2 }->\textrm{z},\textrm{Y}->\textrm{Y}3\squareY3\bowtiez,\operatorname{map}(plus(s X2))[] \ [] ם X \approx s X2
        \square\emptyset \square{X,Y, X2, Y2, Y3 :: nat; X1s :: [\alpha]; X1 :: \alpha; F :: \alpha -> \beta}
        H
```




```
    \emptyset व map (plus(s z)[]\bowtie[] व X \approxsz, X2 \approx z, Y \approx z व\emptyset
        {X,Y, X2, Y2, Y3 :: nat; X1s :: [\alpha]; X1 :: \alpha; F :: \alpha -> \beta} H + NR1
```

$$
\begin{aligned}
& (\mathrm{plus}(\mathrm{~s} \mathrm{z})) \rightarrow \mathrm{F} 1,[] \rightarrow[] \square[] \bowtie[] \square \mathrm{X} \approx \mathrm{~s} \mathrm{z}, \mathrm{X} 2 \approx \mathrm{z}, \mathrm{Y} \approx \mathrm{z} \\
& \square \square \square\{\mathrm{X} 1 \mathrm{~s}::[\alpha] ; \mathrm{X}, \mathrm{Y}, \mathrm{X} 2, \mathrm{Y} 2, \mathrm{Y} 3:: \text { nat; X1 }:: \alpha ; \mathrm{F}:: \alpha \rightarrow \beta ; \\
& \left.\mathrm{F} 1:: \alpha_{1} \rightarrow \beta_{1}\right\} \quad H_{\mathrm{IB}, \mathrm{DC} 2, \mathrm{DC} 1} \\
& \emptyset \square \emptyset \square \mathrm{X} \approx \mathrm{~s} \mathrm{z}, \mathrm{X} 2 \approx \mathrm{z}, \mathrm{Y} \approx \mathrm{z} \square \emptyset \square\{\mathrm{X}, \mathrm{Y}, \mathrm{X} 2, \mathrm{Y} 2, \mathrm{Y} 3:: \text { nat; } \\
& \left.\mathrm{X} 1 \mathrm{~s}::[\alpha] ; \mathrm{X} 1:: \alpha ; \mathrm{F}:: \alpha \rightarrow \beta ; \mathrm{F} 1:: \alpha_{1} \rightarrow \beta_{1}\right\}=G_{n}=\hat{G}_{n}
\end{aligned}
$$

Computed answer, restricted to variables in $G_{0}$ :

$$
(\emptyset,(\emptyset,\{\mathrm{X} \mapsto \mathrm{~s} \mathbf{z}, \mathrm{Y} \mapsto \mathrm{z}\}))
$$

Finally, we present a series of examples designed to show that the dynamic type checking side conditions embodied in CLNC are really needed. There is a different example for each of the eight transformations marked with $\boldsymbol{\star}$, which can perform dynamic type checking. All the examples show that type errors can occur if dynamic type checking is omitted, or applied to a goal which is not type-closed. Some of the $\star$ marked CLNC transformations are such that a type error caused by opaque decompositions can escape from dynamic type checking. The examples do also illustrate these situations.

## Example 11 (CLNC Transformation ID)

1. Type-closure and dynamic checking are necessary. Consider $G \neq \hat{G}$, given as:

$$
\begin{gathered}
G=\emptyset \square \mathrm{XY} \bowtie \mathrm{X}(\operatorname{not} \mathrm{Z}) \square \emptyset \square \emptyset \square\{\mathrm{X}:: \alpha \rightarrow \beta, \mathrm{Y}:: \alpha, \mathrm{Z}:: \gamma\} \\
\hat{G}=\emptyset \square \mathrm{X} Y \bowtie \mathrm{X}(\operatorname{not} \mathrm{Z}) \square \emptyset \square \alpha \approx \mathrm{bool}, \gamma \approx \mathrm{bool} \square \\
\{\mathrm{X}:: \mathrm{bool} \rightarrow \beta, \mathrm{Y}:: \text { bool, } \mathrm{Z}:: \text { bool }\}
\end{gathered}
$$

Dynamic type checking prevents the application of ID to $\hat{G}$ with binding $\{\mathrm{X} \mapsto$ twice $\}$, since $\hat{T}(\mathrm{X})=$ bool $\rightarrow \beta$, twice $::\left(\alpha^{\prime} \rightarrow \alpha^{\prime}\right) \rightarrow \alpha^{\prime}$ $\rightarrow \alpha^{\prime}$ and $m g u\left(\right.$ bool $\left.\rightarrow \beta \approx\left(\alpha^{\prime} \rightarrow \alpha^{\prime}\right) \rightarrow \alpha^{\prime} \rightarrow \alpha^{\prime}\right)=$ FAIL .

In the case of $G$, dynamic type checking does not prevent a type error. One gets: $T(\mathrm{X})=\alpha \rightarrow \beta$, twice $::\left(\alpha^{\prime} \rightarrow \alpha^{\prime}\right) \rightarrow \alpha^{\prime} \rightarrow \alpha^{\prime}$ and $m g u(\alpha \rightarrow$ $\left.\beta \approx\left(\alpha^{\prime} \rightarrow \alpha^{\prime}\right) \rightarrow \alpha^{\prime} \rightarrow \alpha^{\prime}\right)=\left\{\alpha \mapsto\left(\alpha^{\prime} \rightarrow \alpha^{\prime}\right), \beta \mapsto\left(\alpha^{\prime} \rightarrow \alpha^{\prime}\right)\right\}$ and hence $G H_{\text {ID, wrong }} G^{\prime}$, where

$$
\begin{gathered}
G^{\prime}=\emptyset \square \mathrm{Y} \bowtie \operatorname{not} \mathrm{Z} \square \mathrm{X} \approx \text { twice } \square \alpha \approx \alpha^{\prime} \rightarrow \alpha^{\prime}, \beta \approx \alpha^{\prime} \rightarrow \alpha^{\prime} \\
\square\left\{\mathrm{X}::\left(\alpha^{\prime} \rightarrow \alpha^{\prime}\right) \rightarrow \alpha^{\prime} \rightarrow \alpha^{\prime}, \mathrm{Y}:: \alpha^{\prime} \rightarrow \alpha^{\prime}, \mathrm{Z}:: \gamma\right\}
\end{gathered}
$$

Note that $G^{\prime}$ is ill-typed, although it admits an untyped solution: $\sigma_{d}=$ $\{\mathrm{X} \mapsto$ twice, $\mathrm{Y} \mapsto \mathrm{false}, \mathrm{Z} \mapsto$ true $\}$.
2. Opaque decomposition escapes from dynamic type checking. This is not possible for transformation ID. Since $\mathrm{X} \overline{a_{p}} \asymp \mathrm{X} \overline{b_{p}}$ is well-typed w.r.t. $\hat{T}$, the type $\hat{T}(\mathrm{X})$ forces the types of $\overline{a_{p}}$ and $\overline{b_{p}}$ to be the same.

## Example 12 (CLNC Transformation BD)

1. Type-closure and dynamic checking are necessary. Consider $G \neq \hat{G}$, given as:

$$
\begin{aligned}
& G=\emptyset \square \mathrm{XY} \bowtie \mathrm{si} \text {, negate } \mathrm{Y} \bowtie \mathrm{Z} \square \emptyset \square \emptyset \square \\
& \{\mathrm{X}:: \alpha \rightarrow \text { nat, } \mathrm{Y}:: \text { [bool], } \mathrm{Z}:: \text { [bool], } \mathrm{N}:: \text { nat }\} \\
& \hat{G}=\emptyset \square \mathrm{XY} \bowtie \mathrm{sN} \text {, negate } \mathrm{Y} \bowtie \mathrm{Z} \square \emptyset \square \alpha \approx[\text { bool }] \square \\
& \{\mathrm{X}:: \text { [bool] } \rightarrow \text { nat, } \mathrm{Y}:: \text { [bool], } \mathrm{Z}:: \text { [bool], } \mathrm{N}:: \text { nat }\}
\end{aligned}
$$

Dynamic type checking prevents the application of BD to $\hat{G}$ with binding $\{\mathrm{X} \mapsto \mathrm{s}\}$, since $\hat{T}(\mathrm{X})=[$ bool $] \rightarrow$ nat, $\mathrm{s}::$ nat $\rightarrow$ nat in $P A(\hat{T}, \mathrm{~s} N)$ and $\operatorname{mgu}([$ bool $] \rightarrow$ nat $\approx$ nat $\rightarrow$ nat $)=$ FAIL .

In the case of $G$, dynamic type checking does not prevent a type error. One gets: $T(\mathrm{X})=\alpha \rightarrow$ nat, $\mathrm{s}::$ nat $\rightarrow$ nat and $\operatorname{mgu}(\alpha \rightarrow$ nat $\approx$ nat $\rightarrow$ nat $)=\{\alpha \mapsto$ nat $\}$ and hence $G \Vdash_{\text {BD,wrong }} G^{\prime}$, where

$$
\begin{aligned}
G^{\prime}= & \emptyset \square \mathrm{Y} \bowtie \mathrm{~N}, \text { negate } \mathrm{Y} \bowtie \mathrm{Z} \square \mathrm{X} \approx \mathrm{~s} \square \alpha \approx \text { nat } \square \\
& \{\mathrm{X}:: \text { nat } \rightarrow \text { nat, } \mathrm{Y}:: \text { [bool], } \mathrm{Z}:: \text { [bool], } \mathrm{N}:: \text { nat }\}
\end{aligned}
$$

Note that $G^{\prime}$ is ill-typed, although it admits an untyped solution: $\sigma_{d}=$ $\{\mathrm{X} \mapsto \mathrm{s}, \mathrm{N} \mapsto[], \mathrm{Y} \mapsto[], \mathrm{Z} \mapsto[]\}$.
2. Opaque decomposition escapes from dynamic type checking. This is not possible for transformation BD. Since $X \overline{a_{k}} \asymp s \overline{b_{k}}$ is well-typed w.r.t. $\hat{T}$, the type $\hat{T}(X)$ and the type annotation of $s$ in $P A\left(\hat{T}, s \overline{b_{k}}\right)$ must have the form $\overline{\mu_{k}} \rightarrow \mu$ and $\overline{\nu_{k}} \rightarrow \mu$, respectively, with $\overline{\mu_{k}}$ and $\overline{\nu_{k}}$ such that $\hat{T} \vdash_{W T} \overline{a_{k}}:: \overline{\mu_{k}}$ and $\hat{T} \vdash_{W T} \overline{\overline{b_{k}}}:: \overline{\nu_{k}}$. Moreover, dynamic type checking unifies $\overline{\mu_{k}} \rightarrow \mu$ and $\overline{\nu_{k}} \rightarrow \mu$ as part of the $\mathbf{B D}$ transformation. Therefore, $\overline{a_{k}}$ and $\overline{b_{k}}$ cannot become ill-typed in the new goal.

## Example 13 (CLNC Transformation IM)

1. Type-closure and dynamic checking are necessary. Consider $G \neq \hat{G}$, given as:

$$
\begin{aligned}
& G=\emptyset \square \mathrm{XY} \bowtie \operatorname{cons}(\text { head [z]) L, negate } \mathrm{Y} \bowtie \mathrm{Z} \square \emptyset \square \emptyset \square \\
& \{\mathrm{X}:: \alpha \rightarrow \text { [nat], } \mathrm{Y}:: \text { [bool], } \mathrm{L}:: \text { [nat], } \mathrm{Z}:: \text { [bool] }\} \\
& \hat{G}=\emptyset \square X Y \bowtie \operatorname{cons}(\text { head }[z]) L \text {, negate } Y \bowtie Z \square \emptyset \square \\
& \alpha \approx[\text { bool }] \square\{\mathrm{X}:: \text { [bool] } \rightarrow \text { [nat], } \mathrm{Y}:: \text { [bool], } \\
& \mathrm{L}:: \text { [nat], } \mathrm{Z}:: \text { [bool] }\}
\end{aligned}
$$

Dynamic type checking prevents the application of IM to $\hat{G}$ with binding $\{\mathrm{X} \mapsto$ cons A $\}$, since $\hat{T}(\mathrm{X})=[$ bool $] \rightarrow$ [nat], cons A :: [ $\left.\alpha_{1}\right] \rightarrow$ $\left[\alpha_{1}\right]$ and $\operatorname{mgu}($ [bool $] \rightarrow$ nat $\left.] \approx\left[\alpha_{1}\right] \rightarrow\left[\alpha_{1}\right]\right)=$ FAIL .
In the case of $G$, dynamic type checking does not prevent a type error. One gets: $T(\mathrm{X})=\alpha \rightarrow$ [nat $]$, cons A :: $\left[\alpha_{1}\right] \rightarrow\left[\alpha_{1}\right], \operatorname{mgu}(\alpha \rightarrow$ [nat] $\left.\approx\left[\alpha_{1}\right] \rightarrow\left[\alpha_{1}\right]\right)=\left\{\alpha \mapsto\right.$ [nat], $\alpha_{1} \mapsto$ nat $\}$ and hence $G H_{\text {IM, wrong }} G^{\prime}$, where

$$
\begin{aligned}
& G^{\prime}=\emptyset \square \mathrm{A} \bowtie \text { head }[\mathrm{z}], \mathrm{Y} \bowtie \mathrm{~L}, \text { negate } \mathrm{Y} \bowtie \mathrm{Z} \square \mathrm{X} \approx \text { cons } \mathrm{A} \square \\
& \quad \alpha \approx\left[\text { nat }, \alpha_{1} \approx \text { nat } \square\{\mathrm{X}:: \text { [nat] } \rightarrow \text { [nat], } \mathrm{Y}:: \text { [bool] },\right. \\
& \quad \mathrm{L}:: \text { [nat], } \mathrm{Z}:: \text { [bool], } \mathrm{A}:: \text { nat }\}
\end{aligned}
$$

Note that $G^{\prime}$ is ill-typed, although it admits a solution: $\sigma_{d}=\{\mathrm{X} \mapsto$ cons $\mathrm{z}, \mathrm{A} \mapsto \mathrm{z}, \mathrm{Y} \mapsto[], \mathrm{L} \mapsto[], \mathrm{Z} \mapsto[]\}$.
2. Opaque decomposition escapes from dynamic type checking. Consider $G=\hat{G}$, given as:

$$
\begin{aligned}
G= & \emptyset \square \mathrm{X}(\text { tail }[\mathrm{z}]) \bowtie \text { third one (tail [true]) } \square \emptyset \square \emptyset \square \\
& \{\mathrm{X}::[\text { nat }] \rightarrow \beta \rightarrow \beta\}
\end{aligned}
$$

Dynamic type checking does not prevent the application of IM to $G$ with binding $\{\mathrm{X} \mapsto$ third A$\}$. In fact $T(\mathrm{X})=$ [nat] $\rightarrow \beta \rightarrow \beta$, third $\mathrm{A}:: \alpha_{1} \rightarrow \beta_{1} \rightarrow \beta_{1}, \operatorname{mgu}\left(\right.$ [nat] $\left.\rightarrow \beta \rightarrow \beta \approx \alpha_{1} \rightarrow \beta_{1} \rightarrow \beta_{1}\right)=$ $\left\{\alpha_{1} \mapsto[\right.$ nat $\left.], \beta_{1} \mapsto \beta\right\}$ and therefore:

$$
\begin{aligned}
& G \Vdash_{\mathrm{IM}} G^{\prime}=\emptyset \square \mathrm{A} \bowtie \text { one, tail }[\mathrm{z}] \bowtie \text { tail [true] } \square \mathrm{X} \approx \text { third } \mathrm{A} \\
& \quad \square \alpha_{1} \approx[\text { nat }], \beta_{1} \approx \beta \square\{\mathrm{X}::[\text { nat }] \rightarrow \beta \rightarrow \beta, \mathrm{A}:: \delta\}
\end{aligned}
$$

The step $G \Vdash_{I M} G^{\prime}$ involves opaque decomposition, and $G^{\prime}$ turns out to be ill-typed. Nevertheless $G^{\prime}$ admits the solution $\sigma_{d}=\{\mathrm{A} \mapsto \mathrm{s} \mathrm{z}, \mathrm{X} \mapsto$ third (s z) \}.

## Example 14 (CLNC Transformation GN)

Type-closure and dynamic checking are necessary. Consider $G \neq \hat{G}$, given as:

$$
\begin{aligned}
& G=\emptyset \square \mathrm{FX} \bowtie \operatorname{true} \square \emptyset \square \emptyset \square\left\{\mathrm{X}:: \alpha_{1}, \mathrm{~F}:: \alpha_{1} \rightarrow \alpha\right\} \\
& \hat{G}=\emptyset \square \mathrm{FX} \bowtie \operatorname{true} \square \emptyset \square \alpha \approx \mathrm{bool} \square\left\{\mathrm{X}:: \alpha_{1}, \mathrm{~F}:: \alpha_{1} \rightarrow \text { bool }\right\}
\end{aligned}
$$

Dynamic type checking prevents the application of GN to $\hat{G}$ with binding $\{\mathrm{F} \mapsto$ plus z$\}$, since $\hat{T}(\mathrm{~F})=\alpha_{1} \rightarrow$ bool, plus $\mathrm{z}::$ nat $\rightarrow$ nat and $\operatorname{mgu}\left(\alpha_{1} \rightarrow\right.$ bool $\approx$ nat $\rightarrow$ nat $)=$ FAIL .

In the case of $G$, dynamic type checking does not prevent a type error. One gets: $T(\mathrm{~F})=\alpha_{1} \rightarrow \alpha$, plus z $::$ nat $\rightarrow$ nat, $\operatorname{mgu}\left(\alpha_{1} \rightarrow \alpha \approx\right.$ nat $\rightarrow$ nat) $=\left\{\alpha \mapsto\right.$ nat, $\alpha_{1} \mapsto$ nat $\}$ and hence $G \Vdash_{\mathbf{G N}, \text { wrong }} G^{\prime}$, where

$$
\begin{aligned}
& G^{\prime}=\mathrm{X} \rightarrow \mathrm{~N} \square \mathrm{~N} \bowtie \text { true } \square \mathrm{F} \approx \text { plus } z \square \alpha \approx \text { nat, } \alpha_{1} \approx \text { nat } \\
& \quad\{\mathrm{F}:: \text { nat } \rightarrow \text { nat, } \mathrm{X}:: \text { nat, } \mathrm{N}:: \text { nat }\}
\end{aligned}
$$

Note that $G^{\prime}$ is ill-typed, although it admits a solution: $\sigma_{d}=\{\mathrm{F} \mapsto \mathrm{plus} \mathbf{z}$, $\mathrm{X} \mapsto$ true, $\mathrm{N} \mapsto$ true $\}$.

## Example 15 (CLNC Transformation GD)

1. Type-closure and dynamic checking are necessary. Consider $G \neq \hat{G}$, given as:

$$
\begin{aligned}
& G=\emptyset \square \mathrm{X}(\text { tail }[\mathrm{z}]) \bowtie \mathrm{Y}(\text { tail [true] }) \square \emptyset \square \emptyset \square \\
& \left\{\mathrm{X}:: \alpha_{1} \rightarrow \beta, \mathrm{Y}:: \alpha_{2} \rightarrow \beta\right\} \\
& \hat{G}=\emptyset \square \mathrm{X}(\text { tail }[\mathrm{z}]) \bowtie \mathrm{Y}(\text { tail }[\text { true }]) \square \emptyset \square \alpha_{1} \approx[\text { nat }], \\
& \quad \alpha_{2} \rightarrow[\text { bool }] \square\{\mathrm{X}::[\text { nat }] \rightarrow \beta, \mathrm{Y}::[\text { bool }] \rightarrow \beta\}
\end{aligned}
$$

Dynamic type checking prevents the application of GD to $\hat{G}$ with binding $\{\mathrm{X} \mapsto$ cons $\mathrm{A}, \mathrm{Y} \mapsto$ cons B$\}$, since $\hat{T}(\mathrm{X})=$ [nat] $\rightarrow \beta$, $\hat{T}(\mathrm{Y})=[$ bool $] \rightarrow \beta$, cons A :: $\left[\beta_{1}\right] \rightarrow\left[\beta_{1}\right]$, cons $\mathrm{B}::\left[\beta_{2}\right] \rightarrow\left[\beta_{2}\right]$ and $\operatorname{mgu}\left([\right.$ nat $] \rightarrow \beta \approx\left[\beta_{1}\right] \rightarrow\left[\beta_{1}\right]$, [bool] $\left.\rightarrow \beta \approx\left[\beta_{2}\right] \rightarrow\left[\beta_{2}\right]\right)=$ FAIL.

In the case of $G$, dynamic type checking does not prevent a type error. One gets: $T(\mathrm{X})=\alpha_{1} \rightarrow \beta, T(\mathrm{Y})=\alpha_{2} \rightarrow \beta$, cons $\mathrm{A}::\left[\beta_{1}\right] \rightarrow\left[\beta_{1}\right]$, cons $\mathrm{B}::\left[\beta_{2}\right] \rightarrow\left[\beta_{2}\right]$ and $\operatorname{mgu}\left(\alpha_{1} \rightarrow \beta \approx\left[\beta_{1}\right] \rightarrow\left[\beta_{1}\right], \alpha_{2} \rightarrow \beta \approx\right.$ $\left.\left[\beta_{2}\right] \rightarrow\left[\beta_{2}\right]\right)=\left\{\alpha_{1} \mapsto\left[\beta_{1}\right], \alpha_{2} \mapsto\left[\beta_{1}\right], \beta \mapsto\left[\beta_{1}\right], \beta_{2} \mapsto \beta_{1}\right\}$ and hence $G H^{\mathbf{G D}, \text { wrong }} G^{\prime}$ :

$$
\begin{aligned}
& \left.G^{\prime}=\emptyset \square \mathrm{A} \bowtie \mathrm{~B}, \text { tail }[\mathrm{z}] \bowtie \text { tail [true }\right] \square \mathrm{X} \approx \text { cons } \mathrm{A}, \\
& \\
& \quad \mathrm{Y} \approx \text { cons } \mathrm{B} \square \alpha_{1} \approx\left[\beta_{1}\right], \alpha_{2} \approx\left[\beta_{1}\right], \beta \approx\left[\beta_{1}\right], \beta_{2} \approx \beta_{1} \\
& \quad\left\{\mathrm{X}::\left[\beta_{1}\right] \rightarrow\left[\beta_{1}\right], \mathrm{Y}::\left[\beta_{1}\right] \rightarrow\left[\beta_{1}\right], \mathrm{A}:: \beta_{1}, \mathrm{~B}:: \beta_{1}\right\}
\end{aligned}
$$

Note that $G^{\prime}$ is ill-typed, although it admits a solution: $\sigma_{d}=\{\mathrm{X} \mapsto$ cons $\mathrm{A}, \mathrm{Y} \mapsto$ cons $\mathrm{A}, \mathrm{B} \mapsto \mathrm{A}\}$.
2. Opaque decomposition escapes from dynamic type checking. Consider $G=\hat{G}$, given as:

$$
\begin{aligned}
G= & \emptyset \square \mathrm{X}(\text { tail }[\mathrm{z}]) \bowtie \mathrm{Y}(\text { tail }[\text { true }]) \square \emptyset \square \emptyset \square \\
& \{\mathrm{X}::[\text { nat }] \rightarrow \beta, \mathrm{Y}::[\text { bool }] \rightarrow \beta\}
\end{aligned}
$$

Dynamic type checking does not prevent the application of GD to $G$ with binding $\{\mathrm{X} \mapsto$ snd, $\mathrm{Y} \mapsto$ snd $\}$. In fact $T(\mathrm{X})=$ [nat] $\rightarrow$ $\beta, T(\mathrm{Y})=[$ bool $] \rightarrow \beta$, snd $:: \alpha_{1} \rightarrow \beta_{1} \rightarrow \beta_{1}$, snd $:: \alpha_{2} \rightarrow \beta_{2} \rightarrow \beta_{2}$, $\operatorname{mgu}\left([\right.$ nat $] \rightarrow \beta \approx \alpha_{1} \rightarrow \beta_{1} \rightarrow \beta_{1}$, [bool] $\left.\rightarrow \beta \approx \alpha_{2} \rightarrow \beta_{2} \rightarrow \beta_{2}\right)=$ $\left\{\alpha_{1} \mapsto\right.$ [nat], $\alpha_{2} \mapsto$ [bool], $\left.\beta \mapsto\left(\beta_{1} \rightarrow \beta_{1}\right), \beta_{2} \mapsto \beta_{1}\right\}$ and therefore:

$$
\begin{aligned}
& G \Vdash_{\mathbf{G D}} G^{\prime}=\emptyset \square \text { tail }[\mathrm{z}] \bowtie \text { tail [true] } \square \mathrm{X} \approx \text { snd, } \mathrm{Y} \approx \text { snd } \\
& \quad \alpha_{1} \approx\left[\text { nat }, \alpha_{2} \approx\left[\text { bool }, \beta \approx\left(\beta_{1} \rightarrow \beta_{1}\right), \beta_{2} \approx \beta_{1} \square\right.\right. \\
& \quad\{\mathrm{X}:: \text { [nat }] \rightarrow \beta_{1} \rightarrow \beta_{1}, \mathrm{Y}::\left[\text { bool } \rightarrow \beta_{1} \rightarrow \beta_{1}\right\}
\end{aligned}
$$

The step $G H_{\text {GD }} G^{\prime}$ involves opaque decomposition, and $G^{\prime}$ turns out to be ill-typed. Nevertheless $G^{\prime}$ admits the solution $\sigma_{d}=\{\mathrm{X} \mapsto$ snd, $\mathrm{Y} \mapsto$ snd $\}$.

## Example 16 (CLNC Transformation OB)

Type-closure and dynamic checking are necessary. Consider $G \neq \hat{G}$, given as:

$$
\begin{aligned}
& G=\mathrm{XY} \rightarrow \mathrm{~s} \mathrm{~N} \square \text { negate } \mathrm{Y} \bowtie \mathrm{Z} \square \emptyset \square \emptyset \square\{\mathrm{X}:: \alpha \rightarrow \text { nat, } \\
& \mathrm{Y}:: \text { [bool], } \mathrm{Z} \text { :: [bool], } \mathrm{N}:: \text { nat }\} \\
& \hat{G}=\mathrm{XY} \rightarrow \mathrm{sN} \square \text { negate } \mathrm{Y} \bowtie \mathrm{Z} \square \emptyset \square \alpha \approx \text { [bool] } \\
& \{\mathrm{X}:: \text { [bool] } \rightarrow \text { nat, } \mathrm{Y}:: \text { [bool], } \mathrm{Z}:: \text { [bool], } \mathrm{N}:: \text { nat }\}
\end{aligned}
$$

Dynamic type checking prevents the application of $\mathbf{O B}$ to $\hat{G}$ with binding $\{\mathrm{X} \mapsto \mathrm{s}\}$, since $\hat{T}(\mathrm{X})=[$ bool $] \rightarrow$ nat, $\mathrm{s}::$ nat $\rightarrow$ nat and mgu([bool] $\rightarrow$ nat $\approx$ nat $\rightarrow$ nat $)=$ FAIL .

In the case of $G$, dynamic type checking does not prevent a type error. One gets: $T(\mathrm{X})=\alpha \rightarrow$ nat, $\mathrm{s}::$ nat $\rightarrow$ nat and $\operatorname{mgu}(\alpha \rightarrow$ nat $\approx$ nat $\rightarrow$ nat $)=\{\alpha \mapsto$ nat $\}$ and hence $G H_{\text {OB,wrong }} G^{\prime}$, where

$$
\begin{aligned}
& G^{\prime}=\mathrm{Y} \rightarrow \mathrm{~N} \square \text { negate } \mathrm{Y} \bowtie \mathrm{Z} \square \mathrm{X} \approx \mathrm{~s} \square \alpha \approx \text { nat } \square\{\mathrm{X}:: \text { nat } \rightarrow \text { nat }, \\
& \quad \mathrm{Y}::[\text { bool], } \mathrm{Z}:: \text { [bool], } \mathrm{N}:: \text { nat }\}
\end{aligned}
$$

Note that $G^{\prime}$ is ill-typed, although it admits a solution: $\sigma_{d}=\{\mathrm{X} \mapsto \mathrm{s}, \mathrm{Y} \mapsto$ []$, Z \mapsto[], N \mapsto[]\}$.

## Example 17 (CLNC Transformation OGN)

Type-closure and dynamic checking are necessary. Consider $G \neq \hat{G}$, given as:

$$
\begin{aligned}
& G=\mathrm{FX} \rightarrow \text { true } \square \emptyset \square \emptyset \square \emptyset \square\left\{\mathrm{X}:: \alpha_{1}, \mathrm{~F}:: \alpha_{1} \rightarrow \alpha\right\} \\
& \hat{G}=\mathrm{FX} \rightarrow \text { true } \square \emptyset \square \emptyset \square \alpha \approx \text { bool } \square\left\{\mathrm{X}:: \alpha_{1}, \mathrm{~F}:: \alpha_{1} \rightarrow \text { bool }\right\}
\end{aligned}
$$

Dynamic type checking prevents the application of OGN to $G$ with binding $\{\mathrm{F} \mapsto$ plus z$\}$, since $\hat{T}(\mathrm{~F})=\alpha_{1} \rightarrow$ bool, plus $\mathrm{z}::$ nat $\rightarrow$ nat and $m g u\left(\alpha_{1} \rightarrow\right.$ bool $\approx$ nat $\rightarrow$ nat $)=$ FAIL .

In the case of $G$, dynamic type checking does not prevent a type error. One gets: $T(F)=\alpha_{1} \rightarrow \alpha$, plus $z::$ nat $\rightarrow$ nat, $\operatorname{mgu}\left(\alpha_{1} \rightarrow \alpha \approx\right.$ nat $\rightarrow$ nat $)=\left\{\alpha \mapsto\right.$ nat, $\alpha_{1} \mapsto$ nat $\}$ and hence $G \Vdash_{\text {OGN,wrong }} G^{\prime}$, where

$$
\begin{aligned}
G^{\prime}= & \mathrm{X} \rightarrow \mathrm{~N}, \mathrm{~N} \rightarrow \text { true } \square \emptyset \square \mathrm{F} \approx \text { plus z } \square \alpha \approx \text { nat, } \alpha_{1} \approx \text { nat } \square \\
& \{\mathrm{F}:: \text { nat } \rightarrow \text { nat, } \mathrm{X}:: \text { nat, } \mathrm{N}:: \text { nat }\}
\end{aligned}
$$

Note that $G^{\prime}$ is ill-typed, although it admits a solution: $\sigma_{d}=\{\mathrm{F} \mapsto$ plus z, $\mathrm{X} \mapsto$ true, $\mathrm{N} \mapsto$ true $\}$.

## Example 18 (CLNC Transformation OGD)

Type-closure and dynamic checking are necessary. Consider $G \neq \hat{G}$, given as:

$$
\begin{aligned}
& G=\mathrm{X}(\text { tail }[\mathrm{z}]) \rightarrow \mathrm{Y} \square \mathrm{Y} \bowtie[\mathrm{Z} \mid \text { tail [true] }] \square \emptyset \square \emptyset \square \\
& \{\mathrm{X}:: \alpha \rightarrow[\beta], \mathrm{Y}::[\beta], \mathrm{Z}:: \beta\} \\
& \hat{G}=\mathrm{X}(\text { tail }[\mathrm{z}]) \rightarrow \mathrm{Y} \square \mathrm{Y} \bowtie[\mathrm{Z} \mid \text { tail [true] }] \square \emptyset \square \alpha \approx[\text { nat }], \\
& \quad \beta \approx \text { bool } \square\{\mathrm{X}::[\text { nat }] \rightarrow[\text { bool }], \mathrm{Y}:: \text { [bool], } \mathrm{Z}:: \text { bool }\}
\end{aligned}
$$

Dynamic type checking prevents the application of OGD to $\hat{G}$ with binding $\{\mathrm{X} \mapsto$ cons A$\}$, since $\hat{T}(\mathrm{X})=[$ nat $] \rightarrow[$ bool $]$, cons A :: $\left[\alpha_{1}\right] \rightarrow\left[\alpha_{1}\right]$, $\hat{T}(\mathrm{Y})=[\mathrm{bool}]$, cons AB $::\left[\alpha_{2}\right]$ and $m g u($ [nat $] \rightarrow[\mathrm{bool}] \approx\left[\alpha_{1}\right] \rightarrow$ $\left[\alpha_{1}\right]$, [bool] $\left.\approx\left[\alpha_{2}\right]\right)=$ FAIL .

In the case of $G$, dynamic type checking does not prevent a type error. One gets: $T(\mathrm{X})=\alpha \rightarrow[\beta]$, cons $\mathrm{A}::\left[\alpha_{1}\right] \rightarrow\left[\alpha_{1}\right], T(\mathrm{Y})=[\beta]$, cons A B :: $\left[\alpha_{2}\right], \operatorname{mgu}\left(\alpha \rightarrow[\beta] \approx\left[\alpha_{1}\right] \rightarrow\left[\alpha_{1}\right],[\beta] \approx\left[\alpha_{2}\right]\right)=\{\alpha \mapsto$ $\left.[\beta], \alpha_{1} \mapsto \beta, \alpha_{2} \mapsto \beta\right\}$ and hence $G H^{\mathbf{O G D}, \text { wrong }} G^{\prime}$, where

$$
\begin{aligned}
& G^{\prime}=\operatorname{tail}[\mathrm{z}] \rightarrow \mathrm{B} \square[\mathrm{~A} \mid \mathrm{B}] \bowtie[\mathrm{Z} \mid \text { tail }[\text { true }]] \square \mathrm{X} \approx \operatorname{cons} \mathrm{~A} \square \\
& \\
& \quad \alpha \approx[\beta], \alpha_{1} \approx \beta, \alpha_{2} \approx \beta \square\{\mathrm{X}::[\beta] \rightarrow[\beta], \mathrm{Y}::[\beta], \mathrm{Z}:: \beta, \\
& \quad \mathrm{A}:: \beta, \mathrm{B}::[\beta]\}
\end{aligned}
$$

Note that $G^{\prime}$ is ill-typed, although it admits a solution: $\sigma_{d}=\{\mathrm{X} \mapsto$ cons Z, $\mathrm{A} \mapsto \mathrm{Z}, \mathrm{B} \mapsto[]\}$.

Examples 11-18 illustrate situations where a type error leads to an illtyped goal which has nevertheless some solutions, in the sense of Definition 12, items 1, 2. Of course, there are also cases where a type error leads to an unsolvable goal.

### 4.3 Soundness and Completeness

In this final subsection we present soundness and completeness results for CNLC. The main results are Theorem 5 and Theorem 6, corresponding to Theorem 2 and Theorem 3 in [20]. After the publication of [20], where no proofs were included, we unfortunately discovered some mistakes in our handwritten proofs for these results. Regarding the Soundness Theorem 2 from [20], we missed to recognize that a well-typed solved goal must be type-closed before extracting a solution. Moreover, we did not notice that the empty type environment in the solution extracted from a solved goal must be extended to a generally non-empty environment, in order to obtain a computed answer for the initial goal. With respect to the Completeness Theorem 3 in [20], we failed to recognize that this result should be stated on the basis of solutions for the type-closures of the well-typed goals under consideration, rather than for the goals themselves. This is relevant because of the difference between the two sets of solutions $W T S o l(\hat{G})$ and $\operatorname{WTSol}(G)$ in the case that $G$ is well-typed, but not type-closed; see Lemma 14. Presently we have found proofs for revised formulations of both theorems.

We are interested in well-typed goals $G$ for a well-typed program $\mathcal{P}$. We write $T_{G}$ for the type environment of $G$, and we use the notation $(R, \theta) \in_{e x}$ $W T S o l(G)$ to indicate the existence of some $\left(R^{\prime}, \theta^{\prime}\right) \in W T S o l(G)$ such that $\theta$ and $\theta^{\prime}$ can differ only over existential variables. Remember that initial goals are of the form $G_{0}=\emptyset \square C \square \emptyset \square \emptyset \square T_{0}$ and include no existential variables, while solved goals have the form $G_{n}=\emptyset \square \emptyset \square S_{d} \square S_{t} \square T_{n}$. As defined at the beginning of Subsection 4.2, the answer computed by a CLNC derivation with initial goal $G_{0}$ and final solved goal $G_{n}$ is $\left(T_{n} \hat{\sigma}_{t} \backslash T_{0} \hat{\sigma}_{t},\left(\hat{\sigma}_{t}, \sigma_{d}\right)\right)$, where the type substitution $\hat{\sigma}_{t}$ comes from the type-closure of $G_{n}$. All these assumptions and notational conventions will be kept in the rest of this subsection.

Now we are ready to discuss soundness. The following lemma (proved in the Appendix) ensures the correctness of computed answers, extracted from solved goals.

## Lemma 15 (Computed Answers)

Assume a well-typed solved goal $G=\emptyset \square \emptyset \square S_{d} \square S_{t} \square T$ with type-closure $\hat{G}=\emptyset \square \emptyset \square S_{d} \square \hat{S}_{t} \square \hat{T}$. Then the computed answer $\left(\emptyset,\left(\hat{\sigma}_{t}, \sigma_{d}\right)\right)$ is a well-typed solution of both $G$ and $\hat{G}$.

Regarding soundness of one single CLNC step, we have the following lemma. A proof is given in the Appendix.

## Lemma 16 (One-step Soundness)

Assume a well-typed goal $G$, for a well-typed program $\mathcal{P}$. Then:

1. If $G H^{C L N C} \boldsymbol{F A I L}$, then $\operatorname{Sol}(G)=\emptyset$.
2. If $G H_{C L N C} G^{\prime}$, then $G^{\prime}$ is an admissible goal, and every $(R, \theta) \in$ $W T S o l\left(G^{\prime}\right)$ verifies $\left(\left(T_{G^{\prime}} \theta_{t} \backslash T_{G} \theta_{t}\right) \cup R, \theta\right) \in_{\text {ex }} W T S o l(G)$. Moreover, $G^{\prime}$ is again well-typed, unless the CLNC step from $G$ to $G^{\prime}$ has performed an opaque decomposition.

Our desired soundness result follows from Lemma 16:

## Theorem 5 (Soundness)

Consider a well-typed program $\mathcal{P}$ and a CLNC derivation $G_{0} H_{C L N C} \cdots$ $H_{C L N C} G_{n}$, where $G_{0}$ is well-typed and type-closed initial goal, $G_{n}$ is a solved goal, and all the steps are transparent. Then all the goals are well-typed and the computed answer is correct, i.e. $\left(T_{n} \hat{\sigma}_{t} \backslash T_{0} \hat{\sigma}_{t},\left(\hat{\sigma}_{t}, \sigma_{d}\right)\right) \in W T S o l\left(G_{0}\right)$.

Proof: Due to Lemma 15, we know $\left(\emptyset,\left(\hat{\sigma}_{t}, \sigma_{d}\right)\right) \in \operatorname{WTSol}\left(G_{n}\right)$. Moreover, the type environments of the goals along the CLNC derivation, affected by $\hat{\sigma}_{t}$, form an increasing chain $T_{0} \hat{\sigma}_{t} \subseteq \cdots \subseteq T_{n} \hat{\sigma}_{t}$. Therefore, by reiterated application of Lemma 16, we can obtain $\left(T_{n} \hat{\sigma}_{t} \backslash T_{0} \hat{\sigma}_{t},\left(\hat{\sigma}_{t}, \sigma_{d}\right)\right) \in_{e x} \operatorname{WTSol}\left(G_{0}\right)$. Since $G_{0}$ includes no existential variables, the desired conclusion follows.

The rôle of the type environment $\left(T_{n} \hat{\sigma}_{t} \backslash T_{0} \hat{\sigma}_{t}\right)$ in a computed answer is to provide type assumptions for the new variables occurring in the range of the computed data substitution. This can be seen in Example 9(b). An additional illustration is provided by the next example, based on the program from Example 2.

## Example 19 (Computed Answer with Non-empty Type Environment)

$$
\begin{aligned}
& \hat{G}_{0}=G_{0}=\emptyset \square \mathrm{ppN} \bowtie \text { true } \square \emptyset \square \emptyset \square\{\mathrm{N}:: \text { nat }\} H_{\mathrm{NR} 1} \\
& G_{1}=\mathrm{N} \rightarrow \mathrm{sX} \square \mathrm{pX} \text { Xtrue } \square \emptyset \square \emptyset \square\{\mathrm{N}, \mathrm{X}:: \text { nat }\} \quad H_{\text {ов }} \\
& G_{2}=\emptyset \square \mathrm{pX} \bowtie \text { true } \square \mathrm{N} \approx \mathrm{sX} \square \emptyset \square\{\mathrm{~N}, \mathrm{X}:: \text { nat }\} H_{\text {NR1 }} \\
& G_{3}=\mathrm{X} \rightarrow \mathrm{~s} \mathrm{Y} \square \text { true } \bowtie \text { true } \square \mathrm{N} \approx \mathrm{~s} \mathrm{X} \square \emptyset \square\{\mathrm{~N}, \mathrm{X}:: \text { nat }\} \quad H_{\text {ob }} \\
& G_{4}=\emptyset \square \text { true } \bowtie \text { true } \square \mathrm{N} \approx \mathrm{~s}(\mathrm{~s} \mathrm{Y}), \mathrm{X} \approx \mathrm{~s} \mathrm{Y} \square \emptyset \square\{\mathrm{~N}, \mathrm{X}, \mathrm{Y}:: \text { nat }\} \\
& H_{\text {DC1 }} \\
& G_{5}=\emptyset \square \emptyset \square \mathrm{N} \approx \mathrm{~s}(\mathrm{~s} \mathrm{Y}), \mathrm{X} \approx \mathrm{~s} \mathrm{Y} \square \emptyset \square\{\mathrm{~N}, \mathrm{X}, \mathrm{Y}:: \mathrm{nat}\}
\end{aligned}
$$

$G_{5}=\hat{G}_{5}$ yields the computed answer $\left(T_{G_{5}} \hat{\sigma}_{t} \backslash T_{G_{0}} \hat{\sigma}_{t}, \sigma\right)$ with $T_{G_{5}} \hat{\sigma}_{t} \backslash T_{G_{0}} \hat{\sigma}_{t}=$ $\{\mathrm{X}, \mathrm{Y}::$ nat $\}, \sigma_{t}=\emptyset$ and $\sigma_{d}=\{\mathrm{N} \mapsto \mathrm{s}(\mathrm{s} \mathrm{Y}), \mathrm{X} \mapsto \mathrm{s} \mathrm{Y}\}$.

This computed answer is a well-typed solution of $G_{0}$, as predicted by Theorem 5. The type environment $\left(T_{G_{5}} \hat{\sigma}_{t} \backslash T_{G_{0}} \hat{\sigma}_{t}\right)$ is necessary, since $(\emptyset, \sigma) \notin$ $W T S o l\left(G_{0}\right)$.

In order to prove completeness of CLNC, we use a well-founded ordering over witnesses of solutions, as in $[19,18]$. Let $\prec$ be the well-founded multiset ordering for multisets of natural numbers [11, 6]. Then:

## Definition 14 (Ordering for Witnesses)

Let $\mathcal{M}, \mathcal{M}^{\prime}$ be finite multisets of (possibly type-annotated) GORC proofs. Let $\mathcal{S M}, \mathcal{S M}^{\prime}$ be the corresponding multisets of natural numbers, obtained
by replacing each GORC proof by its size, understood as the number of GORC inference steps. Then we define $\mathcal{M} \triangleleft \mathcal{M}^{\prime}$ iff $\mathcal{S} \mathcal{M} \prec \mathcal{S}^{\prime}$.

The next result, also proved in the Appendix, guarantees that CLNC transformations can be chosen to make progress according to a given typeannotated witness.

## Lemma 17 (One-step Completeness)

Assume a well-typed goal $G$, for a well-typed program $\mathcal{P}$, as well as a solution $(R, \theta) \in \operatorname{TASol}(\hat{G})$ with type-annotated witness $\mathcal{M}$. If $G$ is not yet solved, there is some well-typed goal $G^{\prime}$ such that $G H_{C L N C} G^{\prime}$ and $(R, \theta) \in_{\text {ex }} \operatorname{TASol}\left(\hat{G^{\prime}}\right)$ with witness $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$.

In contrast to the formulation of Lemma 2 in [20], the previous lemma assumes well-typed solutions of the type closures of the goals under consideration. Omitting the type closures would lead to the following problem: $G$ might be not type-closed, and $G^{\prime}$ might become type-closed by virtue of one of the CLNC transformations marked with $\star$. In this case, proving $(R, \theta) \in_{e x} \operatorname{TASol}\left(\hat{G}^{\prime}\right)$ might be impossible due to item 1 from Lemma 14.

Our desired completeness result can be easily deduced from Lemma 17:

## Theorem 6 (Completeness)

Assume a well-typed goal $G_{0}$, for a well-typed program $\mathcal{P}$, as well as a typeannotated solution $(R, \theta) \in \operatorname{TASol}\left(G_{0}\right)$. Then there exists a CLNC derivation $G_{0} H^{*}$ CLNC $G_{n}$ consisting entirely of well-typed goals, where the solved form $G_{n}$ with associated computed answer $\left(T_{n} \hat{\sigma}_{t} \backslash T_{0} \hat{\sigma}_{t},\left(\hat{\sigma}_{t}, \sigma_{d}\right)\right)$ is such that $(R, \theta) \in_{e x} \operatorname{TASol}\left(\hat{G}_{n}\right)$, which implies $\hat{\sigma}_{t} \leq \theta_{t}\left[\operatorname{tvar}\left(G_{0}\right)\right]$ and $\sigma_{d} \leq \theta_{d}\left[\operatorname{var}\left(G_{0}\right)\right]$.

Proof: Reiterate the application of Lemma 17, starting from $(R, \theta) \in$ $\operatorname{TASol}\left(\hat{G}_{0}\right)$, which follows from the hypothesis because $G_{0}$ is type-closed. Since the ordering $\triangleleft$ is well-founded, the reiteration must eventually terminate with a well-typed solved goal $\hat{G}_{n}$ such that $(R, \theta) \in_{e x} \operatorname{TASol}\left(\hat{G}_{n}\right)$. This means the existence of some $\left(R^{\prime}, \theta^{\prime}\right) \in \operatorname{TASol}\left(\hat{G}_{n}\right)$ such that $\theta$ and $\theta^{\prime}$ can differ only over existential variables. Then $\theta_{t}^{\prime}=\hat{\sigma}_{t} \theta_{t}^{\prime}$ and $\theta_{d}^{\prime}=\sigma_{d} \theta_{d}^{\prime}$ follows from $\theta_{t}^{\prime} \in \operatorname{TSol}\left(\hat{S}_{t}\right)$ and $\theta_{d}^{\prime} \in \operatorname{Sol}\left(S_{d}\right)$, respectively. Since $G_{0}$ includes no existential variables, we can conclude that $\hat{\sigma}_{t} \leq \theta_{t}\left[\operatorname{tvar}\left(G_{0}\right)\right]$ and $\sigma_{d} \leq \theta_{d}\left[\operatorname{var}\left(G_{0}\right)\right]$ as desired.

Example 20 below illustrates the need of a type-annotated witness in the hypothesis of Theorem 6. We assume the program from Example 2. The
initial goal $G_{0}$ admits the well-typed solution $(\emptyset,(\emptyset,\{\mathrm{X} \mapsto[], \mathrm{Y} \mapsto[]\}))$. Due to opacity of snd, no type-annotated witness for this solution exists. In the CLNC derivation shown below, the goal $G_{1}$ becomes ill-typed after the first opaque decomposition step. The rest of the CLNC steps do not require any dynamic type checking and can be performed in spite of the fact that the goals are not well-typed. The ill-typed solved goal $G_{7}$ obtained at the end provides no well-typed computed answer. Nevertheless, the data substitution $\sigma_{d}$ extracted from $G_{7}$ subsumes the data part of the initially given solution. This is consistent with the completeness of untyped CLNC, as proved in Theorem 4.2 from [19].

## Example 20 (A Well-typed Solution Lacking a Type-annotated Witness)

$$
\begin{aligned}
& \left.\left.\hat{G}_{0}=G_{0}=\emptyset \square \text { snd (head }[\mathrm{X},[\text { true }]]\right) \bowtie \text { snd (head }[\mathrm{Y},[\mathrm{z}]]\right) \square \emptyset \\
& \square \emptyset \square\{\mathrm{X}:: \text { [bool], Y :: [nat] }\} H_{\mathrm{DC} 1} \\
& \hat{G}_{1} \neq G_{1}=\emptyset \text { a head [X,[true]] } \bowtie \text { head }[\mathrm{Y},[\mathrm{z}]] \square \emptyset \square \emptyset \square \\
& \{\mathrm{X}:: \text { [bool], } \mathrm{Y}:: \text { [nat] }\} H_{\text {NR1 }} \\
& G_{2}=[\mathrm{X} \mid[\text { [true }]] \rightarrow[\mathrm{X} 1 \mid \mathrm{X} 1 \mathrm{~s}] \square \mathrm{X} 1 \bowtie \operatorname{head}[\mathrm{Y},[\mathrm{z}]] \square \emptyset \square \emptyset \square \\
& \left\{\mathrm{X}:: \text { [bool], Y :: [nat], X1 :: } \alpha_{1}, \mathrm{X} 1 \mathrm{~s}::\left[\alpha_{1}\right]\right\} H_{\mathrm{DC} 2} \\
& G_{3}=\mathrm{X} \rightarrow \mathrm{X} 1,[\text { [true]] } \rightarrow \mathrm{X} 1 \mathrm{~s} \square \mathrm{X} 1 \bowtie \text { head }[\mathrm{Y},[\mathrm{z}]] \square \emptyset \square \emptyset \square \\
& \left\{\mathrm{X}:: \text { [bool], } \mathrm{Y}:: \text { [nat], X1 :: } \alpha_{1} \text {, X1s :: [ } \alpha_{1} \text { ] }\right\} H_{\mathrm{IB}^{2}} \\
& G_{4}=\emptyset \square \mathrm{X} \bowtie \text { head }[\mathrm{Y},[\mathrm{z}]] \square \emptyset \square \emptyset \square\{\mathrm{X}:: \text { [bool], } \mathrm{Y}:: \text { [nat], } \\
& \left.\mathrm{X} 1:: \alpha_{1}, \mathrm{X} 1 \mathrm{~s}::\left[\alpha_{1}\right]\right\} \quad H_{\mathrm{NR} 1} \\
& G_{5}=\underline{[\mathrm{Y} \mid[\mathrm{z}]]] \rightarrow[\mathrm{Y} 1 \mid \mathrm{Y} 1 \mathrm{~s}]} \square \mathrm{X} \bowtie \mathrm{Y} 1 \square \emptyset \square \emptyset \square\{\mathrm{X}::[\mathrm{bool}], \\
& \text { Y :: [nat], X1 :: } \left.\left.\alpha_{1} \text {, X1s :: [ } \alpha_{1} \text { ], Y1 :: } \alpha_{2} \text {, Y1s :: [ } \alpha_{2}\right]\right\} \\
& H_{\mathrm{DC} 2, \mathrm{IB}^{2}} \\
& G_{6}=\emptyset \square \mathrm{X} \bowtie \mathrm{Y} \square \emptyset \square \emptyset \square\left\{\mathrm{X}::[\mathrm{bool}], \mathrm{Y}:: \text { [nat], } \mathrm{X} 1:: \alpha_{1},\right. \\
& \left.\mathrm{X} 1 \mathrm{~s}::\left[\alpha_{1}\right], \mathrm{Y} 1:: \alpha_{2}, \mathrm{Y} 1 \mathrm{~s}::\left[\alpha_{2}\right]\right\} H_{\mathrm{BD}} \\
& G_{7}=\emptyset \square \emptyset \square \mathrm{X} \approx \mathrm{Y} \square \emptyset \square\left\{\mathrm{X}:: \text { [bool], } \mathrm{Y}:: \text { [nat], } \mathrm{X} 1:: \alpha_{1},\right. \\
& \text { X1s :: } \left.\left[\alpha_{1}\right], Y 1:: \alpha_{2}, \text { Y1s :: }\left[\alpha_{2}\right]\right\}
\end{aligned}
$$

## 5 Conclusions

We have presented a polymorphic type system which extends a previous approach to HO FLP, based on the rewriting logic CRWL [19]. We have defined a natural class of well-typed programs, and we have extended both the models and the lazy narrowing calculus CLNC from [19] to take types into account. Our logical semantics assigns a meaning both to well-typed and to untyped programs. With respect to lazy narrowing, we have identified two possible sources of run-time type errors in CLNC computations, namely opaque decompositions and ill-typed bindings for HO logic variables.

Regarding the first problem, we have shown that the eventual occurrence of opaque decomposition steps is undecidable in general, and we have argued that the difficulty is nevertheless bearable from a practical viewpoint. On the other hand, we have proposed dynamic type checking mechanisms to prevent the second problem, causing only a small overhead in computations that involve no use of HO logic variables acting as functions. We have proved that CLNC with dynamic type checking is sound and complete with respect to the logical semantics in a reasonable sense, namely: computed answers are always correct and well-typed unless opaque decomposition has taken place; and correct solutions which have a type-annotated witness are covered by well-typed computed answers.

As future work, we are interested in working out and testing an implementation of dynamic type checking. The $\mathcal{T} \mathcal{O} \mathcal{Y}$ system [32], which works on top on Prolog, is an available possibility. Another interesting approach would be to extend the abstract machine from [27] (whose design supports extensibility and modifiability) with dedicated mechanisms for dynamic type checking.

Acknowledgements We are grateful to two anonymous reviewers for their stimulating criticisms. We also thank our colleagues Miguel Palomino and Eva Ullán, who carefully read an earlier version of this paper and made many useful comments and suggestions.

## References

[1] S. Antoy and A. Tolmach. Typed Higher-order Narrowing without Higher-Order Strategies. In Proc. 4th Int. Symposium on Functional and

Logic Programming (FLOPS'99), volume 1722 of $L N C S$, pages 335-352. Springer-Verlag, 1999.
[2] K.R. Apt. Logic Programming. In J. van Leeuwen, editor, Handbook of Theoretical Computer Science, volume B, chapter 10, pages 493-574. Elsevier and The MIT Press, 1990.
[3] K.R. Apt and M. Gabbrielli. Declarative Interpretations Reconsidered. In Proc. Int. Conf. on Logic Programming (ICLP'94), The MIT Press, pages 74-89, 1994.
[4] P. Arenas-Sánchez and M. Rodríguez-Artalejo. A Lazy Narrowing Calculus for Functional Logic Programming with algebraic polymorphic types. In Proc. Int. Symp. on Logic Programming (ILPS'97), The MIT Press, pages 53-68, 1997.
[5] P. Arenas-Sánchez and M. Rodríguez-Artalejo. A Semantic Framework for Functional Logic Programming with Algebraic Polymorphic Types. In Proc. Int. Joint Conference on Theory and Practice of Software Development (TAPSOFT'97), volume 1214 of LNCS, pages 453-464. Springer-Verlag, 1997.
[6] F. Baader and T. Nipkow. Term Rewriting and All That. Cambridge University Press, 1998.
[7] W. Chen, M. Kifer, and D.S. Warren. Hilog: A Foundation for HigherOrder Logic Programming. Journal of Logic Programming, 15:187-230, 1993.
[8] N. Cutland. Computability. An Introduction to Recursive Function Theory. Cambridge University Press, 1980.
[9] L. Damas and R. Milner. Principal Type Schemes for Functional Programs. In Proc. ACM Symp. on Principles of Programming Languages (POPL'82), ACM Press, pages 207-212, 1982.
[10] N. Dershowitz and J.P. Jouannaud. Rewrite Systems. In J. van Leeuwen, editor, Handbook of Theoretical Computer Science, volume B, chapter 6, pages 243-320. Elsevier and The MIT Press, 1990.
[11] N. Dershowitz and Z. Manna. Proving Termination with Multiset Orderings. Communications of the ACM, 22(8):465-476, 1979.
[12] F. Pfenning (ed.). Types in Logic Programming. The MIT Press, 1992.
[13] M. Hanus (ed.). Curry: an Integrated Functional Logic Language, version 0.7.1. Technical report, Universität Kiel, June 2000. Available at http://www.informatik.uni-kiel.de/curry/.
[14] M. Falaschi, G. Levi, M. Martelli, and C. Palamidessi. A Model-theoretic Reconstruction of the Operational Semantics of Logic Programs. Information and Computation, 102(1):86-113, 1993.
[15] E. Giovannetti, G. Levi, C. Moiso, and C. Palamidessi. Kernel-LEAF: A Logic plus Functional Language. Journal of Computer and System Science, 42(2):139-185, 1991.
[16] J.A. Goguen and J. Meseguer. Models and Equality for Logical Programming. In Proc. Int. Joint Conference on Theory and Practice of Software Development (TAPSOFT'87), volume 250 of LNCS, pages 122. Springer-Verlag, 1987.
[17] W. Goldfarb. The Undecidibility of the Second-Order Unification Problem. Theoretical Computer Science, 13:225-230, 1981.
[18] J.C. González-Moreno, M.T. Hortalá-González, F.J. López-Fraguas, and M. Rodríguez-Artalejo. An Approach to Declarative Programming Based on a Rewriting Logic. Journal of Logic Programming, 40(1):4787, 1999.
[19] J.C. González-Moreno, M.T. Hortalá-González, and M. RodríguezArtalejo. A Higher Order Rewriting Logic for Functional Logic Programming. In Proc. Int. Conf. on Logic Programming (ICLP'97), The MIT Press, pages 153-167, 1997.
[20] J.C. González-Moreno, M.T. Hortalá-González, and M. RodríguezArtalejo. Semantics and Types in Functional Logic Programming. In Proc. 4th Fuji International Symposium on Functional and Logic Programming (FLOPS'99), volume 1722 of LNCS, pages 1-20. SpringerVerlag, 1999.
[21] C.A. Gunter and D. Scott. Semantic Domains. In J. van Leeuwen, editor, Handbook of Theoretical Computer Science, volume B, chapter 6, pages 633-674. Elsevier and The MIT Press, 1990.
[22] M. Hanus. Horn Clause Programs with Polymorphic Types: Semantics and Resolution. In Proc. Int. Joint Conf. on Theory and Practice of Software Development (TAPSOFT'89), volume 352 of LNCS, pages 225240. Springer-Verlag, 1989.
[23] M. Hanus. Polymorphic Higher-Order Programming in Prolog. In Proc. Int. Conf. on Logic Programming (ICLP'89), The MIT Press, pages 382-397, 1989.
[24] M. Hanus. A Functional and Logic Language with Polymorphic Types. In Proc. Int. Symp. on Design and Implementation of Symbolic Computation Systems, volume 429 of LNCS, pages 215-224. Springer-Verlag, 1990.
[25] M. Hanus and C. Prehofer. Higher-Order Narrowing with Definitional Trees. Journal of Functional Programming, 9(1):33-75, 1999.
[26] S. Hölldobler. Foundations of Equational Logic Programming. LNCS. Springer-Verlag, 1989.
[27] M.T. Hortalá-González and E. Ullán. An Abstract Machine Based System for a Lazy Narrowing Calculus. In Proc. 5th Fuji International Symposium on Functional and Logic Programming (FLOPS'2001), volume 2024 of LNCS, pages 216-232. Springer-Verlag, 2001.
[28] J. Jaffar, J.L. Lassez, and M.J. Maher. A Theory of Complete Logic Programs with Equality. Journal of Logic Programming, 1:211-223, 1984.
[29] A.J. Kfoury, J. Tiuryn, and P. Urzyczyn. Type Reconstruction in the Presence of Polymorphic Recursion. ACM Transactions on Programming Languages and Systems, 15(2):290-311, 1993.
[30] J.W. Klop. Term Rewriting Systems. In S. Abramsky, D.M. Gabbay, and T.S.E. Maibaum, editors, Handbook of Logic in Computer Science, volume 2, pages 2-116. Oxford University Press, 1992.
[31] K. Kwon, G. Nadathur, and D.S. Wilson. Implementing Polymorphic Typing in a Logic Programming Language. Computer Languages, 20(1):25-42, 1994.
[32] F.J. López-Fraguas and J. Sánchez-Hernández. TOY: A Multiparadigm Declarative System. In Proc. 10th Int. Conf. on Rewriting Techniques and Applications (RTA'99), volume 1631 of LNCS, pages 244-247. Springer-Verlag, 1999. Available at http://titan.sip.ucm.es/toy/.
[33] M. Marin, T. Ida, and T. Suzuki. On Reducing the Search Space of Higher-Order Lazy Narrowing. In Proc. 4th Fuji International Symposium on Functional and Logic Programming (FLOPS'99), volume 1722 of LNCS, pages 319-334. Springer-Verlag, 1999.
[34] G. Meyer. Dimensions of Typing in Logic Programming. In Addendum to the tutorial Types in Logic Programming. Int. Conf. on Logic Programming (ICLP'97), 1997.
[35] R. Milner. A Theory of Type Polymorphism in Programming. Journal of Computer and Systems Sciences, 17:348-375, 1978.
[36] J.M. Molina-Bravo and E. Pimentel. Modularity in Functional-Logic Programming. In Proc. Int. Conf. on Logic Programming (ICLP'g7), The MIT Press, pages 183-197, 1997.
[37] B. Möller. On the Algebraic Specification of Infinite Objects - Ordered and Continuous Models of Algebraic Types. Acta Informatica, 22:537578, 1985.
[38] J.J. Moreno-Navarro and M. Rodríguez-Artalejo. Logic Programming with Functions and Predicates: The Language BABEL. Journal of Logic Programming, 12:191-223, 1992.
[39] A. Mycroft and R.A. O'Keefe. A Polymorphic Type System for Prolog. Artificial Intelligence, 23:295-307, 1984.
[40] G. Nadathur and D. Miller. An Overview of $\lambda$-Prolog. In Proc. Int. Conf. on Logic Programming (ICLP'88), The MIT Press, pages 810-827, 1988.
[41] G. Nadathur and F. Pfenning. The Type System of a Higher-Order Logic Programming Language. In F. Pfenning, editor, Types in Logic Programming, pages 245-283. The MIT Press, 1992.
[42] K. Nakahara, A. Middeldorp, and T. Ida. A Complete Narrowing Calculus for Higher-Order Functional Logic Programming. In Proc. Int. Symp. on Programming Language Implementation and Logic Programming (PLILP'95), volume 982 of LNCS, pages 97-114. Springer-Verlag, 1995.
[43] J. Peterson and K. Hammond (eds.). Report on the Programming Language Haskell 98: A Non-strict, Purely Functional Language. Technical report, February 1999.
[44] C. Prehofer. Higher-Order Narrowing. In Proc. IEEE Symp. on Logic in Computer Science (LICS'94), IEEE Comp. Soc. Press, pages 507-516, 1994.
[45] C. Prehofer. A Call-by-Need Strategy for Higher-Order Functional Logic Programming. In Proc. Int. Logic Programming Symp. (ILPS'95), The MIT Press, pages 147-161, 1995.
[46] C. Prehofer. Solving Higher Order Equations: From Logic to Programming. Birkhäuser Verlag, 1998.
[47] M. Rodríguez-Artalejo. Functional and Constraint Logic Programming. In H. Comon, C. Marché, and R. Trainen, editors, Constraints in Computational Logics, volume 2002 of $L N C S$, pages 202-270. SpringerVerlag, 2001.
[48] T. Suzuki, K. Nakagawa, and T. Ida. Higher-Order Lazy Narrowing Calculus: A Computation Model for a Higher-Order Functional Logic Language. In Proc. Int. Conf. on Algebraic and Logic Programming (ALP'97), volume 1298 of LNCS, pages 99-113. Springer-Verlag, 1997.
[49] D.H.D. Warren. Higher-Order Extensions to Prolog: are they needed? In D. Michie J.E. Hayes and Y.H. Yao, editors, Machine Intelligence, volume 10, pages 441-454. Edinburg Univ. Press, 1982.

## 6 Appendix: Proofs

### 6.1 Proofs of Results from Subsection 2.2

Proof of Theorem 1: We prove items 1 and 2 simultaneously, by structural induction over $e$.
Case $X \in D$ Var: Assume $T(X)=\tau$. Applying VR we get $T R(T, X)=$ $\left(X^{\tau}, \emptyset\right)$. Then:

1. For every $\sigma_{t} \in \operatorname{TSol}(\emptyset), T \sigma_{t} \vdash_{W T} X:: \tau \sigma_{t}$, due to VR.
2. Assume $T \leq T^{\prime}$ such that $T^{\prime} \vdash_{W T} X:: \tau^{\prime}$. Then $T^{\prime}(X)=\tau^{\prime}$, and $T^{\prime}=$ $T \sigma_{t}$ for some $\sigma_{t}$. This $\sigma_{t}$ surely satisfies $\sigma_{t} \in \operatorname{TSol}(\emptyset)$ and $X^{\tau} \sigma_{t}=X^{\tau^{\prime}}$.

Case $h \in D C \cup F S$ : Consider a fresh variant $(h:: \tau) \in_{\text {var }} \Sigma$ of $h$ 's principal type declaration. Applying ID we get $T R(T, h)=\left(h^{\tau}, \emptyset\right)$. Then:

1. For every $\sigma_{t} \in \operatorname{TSol}(\emptyset), T \sigma_{t} \vdash_{W T} h:: \tau \sigma_{t}$, due to ID.
2. Assume $T \leq T^{\prime}$ such that $T^{\prime} \vdash_{W T} h:: \tau^{\prime}$. Then $\tau \leq \tau^{\prime}$, and we can choose $\sigma_{t}$ such that $T^{\prime}=T \sigma_{t}, \tau^{\prime}=\tau \sigma_{t}$. This $\sigma_{t}$ surely satisfies $\sigma_{t} \in \operatorname{TSol}(\emptyset)$ and $h^{\tau} \sigma_{t}=h^{\tau^{\prime}}$.

Case $\left(e e_{1}\right)$ : Assume $T R(T, e)=\left(e^{\tau}, E\right)$ and $T R\left(T, e_{1}\right)=\left(e_{1}^{\tau_{1}}, E_{1}\right)$ with $\operatorname{tvar}(E) \cap \operatorname{tvar}\left(E_{1}\right) \subseteq \operatorname{ran}(T)$. Applying AP we obtain $T R\left(T,\left(e e_{1}\right)\right)=$ $\left(\left(e^{\tau_{1} \rightarrow \gamma} e_{1}^{\tau_{1}}\right)^{\gamma}, E \cup E_{1} \cup\left\{\tau \approx \tau_{1} \rightarrow \gamma\right\}\right)$, where $\gamma$ is a fresh type variable not occurring in $T, E, E_{1}$. Then:

1. Assume $\sigma_{t} \in \operatorname{TSol}\left(E \cup E_{1} \cup\left\{\tau \approx \tau_{1} \rightarrow \gamma\right\}\right)$. By induction hypothesis for $e$ and $e_{1}$, we get $T \sigma_{t} \vdash_{W T} e:: \tau \sigma_{t}$ and $T \sigma_{t} \vdash_{W T} e_{1}:: \tau_{1} \sigma_{t}$. Moreover, $\tau \sigma_{t}=\tau_{1} \sigma_{t} \rightarrow \gamma \sigma_{t}$ because $\sigma_{t} \in \operatorname{TSol}\left(\tau \approx \tau_{1} \rightarrow \gamma\right)$. Hence, $T \sigma_{t} \vdash_{W T}$ $\left(e e_{1}\right):: \gamma \sigma_{t}$ can be derived by applying AP.
2. Assume $T \leq T^{\prime}$ such that $T^{\prime} \vdash_{W T}\left(e e_{1}\right):: \tau^{\prime}$. The last step in the derivation must have used AP. Therefore, there must be some type $\tau_{1}^{\prime}$ such that $T^{\prime} \vdash_{W T} e:: \tau_{1}^{\prime} \rightarrow \tau^{\prime}$ and $T^{\prime} \vdash_{W T} e_{1}:: \tau_{1}^{\prime}$. By induction hypothesis applied to $e$ and $e_{1}$, we can assume $\sigma_{t} \in \operatorname{TSol}(E), \sigma_{t}^{1} \in$ $\operatorname{TSol}\left(E_{1}\right)$ such that $T \sigma_{t}=T^{\prime}, e^{\tau} \sigma_{t}=e^{\tau_{1}^{\prime} \rightarrow \tau^{\prime}}, T \sigma_{t}^{1}=T^{\prime}, e_{1}^{\tau_{1}} \sigma_{t}^{1}=e_{1}^{\tau_{1}^{\prime}}$. In particular, we can conclude that $\sigma_{t}=\sigma_{t}^{1}[\operatorname{ran}(T)]$. Since $\gamma$ is a fresh type variable, we can define $\hat{\sigma}_{t} \in T S u b$ such that $\hat{\sigma}_{t} \upharpoonright \operatorname{ran}(T)=$
$\sigma_{t} \upharpoonright \operatorname{ran}(T)=\sigma_{t}^{1} \upharpoonright \operatorname{ran}(T)$ and $\hat{\sigma}_{t}(\gamma)=\tau^{\prime}$. From this construction it follows that $\hat{\sigma}_{t} \in \operatorname{TSol}\left(E \cup E_{1} \cup\left\{\tau \approx \tau_{1} \rightarrow \gamma\right\}\right)$. In particular, we get: $\tau \hat{\sigma}_{t}=\tau \sigma_{t}=\tau_{1}^{\prime} \rightarrow \tau^{\prime}=\tau_{1} \sigma_{t}^{1} \rightarrow \gamma \hat{\sigma}_{t}=\left(\tau_{1} \rightarrow \gamma\right) \hat{\sigma}_{t}$. Moreover, $e^{\tau} \hat{\sigma}_{t}=\left(e^{\tau_{1} \rightarrow \gamma} e_{1}^{\tau_{1}}\right)^{\gamma} \hat{\sigma}_{t}=\left(e^{\tau_{1}^{\prime} \rightarrow \tau^{\prime}} e_{1}^{\tau_{1}^{\prime}}\right)^{\tau^{\prime}}$. This concludes the proof.

Proof of Lemma 2: We reason by induction over the syntactic structure of $t$. The base cases $t=X(X \in D V a r)$ and $t=\perp$ are trivial, because the only $t^{\prime} \sqsupseteq t$ are $\perp$ and $t$ itself. The remaining case is $t=h \bar{t}_{m}$. Due to the assumption $T \vdash_{W T} t:: \tau$, there must be types $\tau_{i}(1 \leq i \leq m)$ such that (a) $T \vdash_{W T} e_{i}:: \tau_{i}$ for all $(1 \leq i \leq m)$ and (b) $\bar{\tau}_{m} \rightarrow \tau$ is an instance of $h$ 's principal type. For $t^{\prime} \sqsupseteq t$ there are only two possibilities: $t^{\prime}=\perp$ or $t^{\prime}=h \overline{t^{\prime}}{ }_{m}$, where $t_{i}^{\prime} \sqsupseteq t_{i}$ for all $(1 \leq i \leq m)$. In the first case, $T \vdash_{W T} \perp:: \tau$ can be derived by ID. In the second case, (a) and the induction hypothesis allow us to assume (c) $T \vdash_{W T} t_{i}^{\prime}:: \tau_{i}$ for all $(1 \leq i \leq m)$ and then $T \vdash_{W T} h{\overline{t^{\prime}}}_{m}:: \tau$ follows from (c) and (b).

Proof of Lemma 3: We reason by structural induction over $e$.
Case $\perp$ : In this case $e \sigma_{d}=\perp$ and $T_{1} \vdash_{W T} \perp:: \tau \sigma_{t}$ follows from ID, since $(\perp:: \alpha) \in_{v a r} \Sigma_{\perp}$.
Case $X \in D$ Var: $T_{0} \vdash_{W T} X:: \tau$ must be proved by applying VR. Hence, $T_{0}(X)=\tau$ and $T_{1} \vdash_{W T} X \sigma_{d}:: \tau \sigma_{t}$ holds by hypothesis.
Case $h \in D C \cup F S:$ In this case $h \sigma_{d}=h$ and $T_{0} \vdash_{W T} h:: \tau$ must be proved by applying ID. Then the principal type of $h$ must be $\left(h:: \tau_{0}\right) \in_{\text {var }} \Sigma$ such that $\tau_{0} \leq \tau$. Since $\tau_{0} \leq \tau \leq \tau \sigma_{t}, T_{1} \vdash_{W T} h:: \tau \sigma_{t}$ follows from ID.
Case $\left(e e_{1}\right): T_{0} \vdash_{W T}\left(e e_{1}\right):: \tau$ must be proved by applying AP, having proved previously $T_{0} \vdash_{W T} e:: \tau_{1} \rightarrow \tau$ and $T_{0} \vdash_{W T} e_{1}:: \tau_{1}$ for some $\tau_{1}$. By induction hypothesis for $e$ and $e_{1}$, we can assume $T_{1} \vdash_{W T} e \sigma_{d}:: \tau_{1} \sigma_{t} \rightarrow$ $\tau \sigma_{t}$ and $T_{1} \vdash_{W T} e_{1} \sigma_{d}:: \tau_{1} \sigma_{t}$. Then $T_{1} \vdash_{W T}\left(e e_{1}\right) \sigma_{d}:: \tau \sigma_{t}$ follows by one application of AP.

Proof of Lemma 4: This follows as a simple corollary from Lemma 3, taking $T$ as $T_{0}, T \sigma_{t}$ as $T_{1}$, and the identity data substitution $i d_{d}$ as $\sigma_{d}$.

Proof of Lemma 5: First, note that $e^{\tau} \sigma$ must be understood as the result of replacing each type $\tau_{0}$ occurring in $e^{\tau}$ by $\tau_{0} \sigma_{t}$ and each variable $X^{\tau_{0}}$ occurring in $e^{\tau}$ by a type-annotated expression $\left(X \sigma_{d}\right)^{\tau_{0} \sigma_{t}}$. This leads to a correct type-annotated expression because of Lemmata 1 and 3.

Proof of Lemma 6: We reason by structural induction over $t$.
Case $X \in D V a r:$ In this case, $T_{1} \vdash_{W T} X:: \tau$ and $T_{2} \vdash_{W T} X:: \tau$ imply $T_{1}(X)=\tau=T_{2}(X)$, due to the type inference rule $\mathbf{V R}$.

Case $h \in D C \cup F S:$ Since $t=h \bar{t}_{m}$ is transparent, $h$ must be m-transparent, and its principal type must be of the form $h:: \bar{\tau}_{m} \rightarrow \tau_{0}$ with $\operatorname{tvar}\left(\bar{\tau}_{m}\right) \subseteq$ $\operatorname{tvar}\left(\tau_{0}\right)$. By the assumptions of the lemma and the form of the type derivation rules, there must be types $\tau_{i}^{\prime}, \tau_{i}^{\prime \prime}(1 \leq i \leq m)$ such that
(a) $T_{1} \vdash_{W T} t_{i}:: \tau_{i}^{\prime}$ for all $(1 \leq i \leq m)$ and ${\overline{\tau^{\prime}}}_{m} \rightarrow \tau \leq \bar{\tau}_{m} \rightarrow \tau_{0}$.
(b) $T_{2} \vdash_{W T} t_{i}:: \tau_{i}^{\prime \prime}$ for all $(1 \leq i \leq m)$ and ${\overline{\tau^{\prime \prime}}}_{m} \rightarrow \tau \leq \bar{\tau}_{m} \rightarrow \tau_{0}$.

Since $\operatorname{tvar}\left(\bar{\tau}_{m}\right) \subseteq \operatorname{tvar}\left(\tau_{0}\right)$, (a) and (b) imply that $\tau_{i}^{\prime}=\tau_{i}^{\prime \prime}$ for all $(1 \leq i \leq m)$. Then, by the induction hypothesis applied to each $t_{i}$, we can conclude that $T_{1}(X)=T_{2}(X)$ for all $X \in \bigcup\left\{\operatorname{var}\left(t_{i}\right) \mid 1 \leq i \leq m\right\}=\operatorname{var}\left(h \bar{t}_{m}\right)$.

Proof of Lemma 7: By the assumption of the lemma and the form of the type inference rules, there must be types $\tau_{i}, \tau_{i}^{\prime}(1 \leq i \leq m)$ such that
(a) $T \vdash_{W T} a_{i}:: \tau_{i}$ for all $(1 \leq i \leq m)$ and $T \vdash_{W T} h:: \bar{\tau}_{m} \rightarrow \tau$.
(b) $T \vdash_{W T} b_{i}:: \tau_{i}^{\prime}$ for all $(1 \leq i \leq m)$ and $T \vdash_{W T} h::{\overline{\tau^{\prime}}}_{m} \rightarrow \tau$.

Consider the type environments $T_{1}=\left\{X_{1}:: \tau_{1}, \ldots, X_{m}:: \tau_{m}\right\}$ and $T_{2}=$ $\left\{X_{1}:: \tau_{1}^{\prime}, \ldots, X_{m}:: \tau_{m}^{\prime}\right\}$. Due to (a) and (b), we obtain $T_{1} \vdash_{W T} h \bar{X}_{m}:: \tau$ and $T_{2} \vdash_{W T} h \bar{X}_{m}:: \tau$. By applying Lemma 6 to $T_{1}, T_{2}$ and the transparent pattern $h \bar{X}_{m}$, we can conclude that $\tau_{i}=\tau_{i}^{\prime}$ for all $(1 \leq i \leq m)$, which completes the proof.

### 6.2 Proofs of Results from Subsection 3.1

Proof of Lemma 9: Since the given defining rule is well-typed, we can assume: (a) $T_{0} \vdash_{W T} t_{i}:: \tau_{i}$ for all $1 \leq i \leq n$, (b) $T_{0} \vdash_{W T} r:: \tau_{0}$. By the assumptions of the lemma, we also have (c) $T \vdash_{W T} t_{i} \sigma_{d}:: \tau_{i} \sigma_{t}$ for all $1 \leq i \leq n$. From (a) and the Type Instantiation Lemma 4, we get (d) $T_{0} \sigma_{t} \vdash_{W T} t_{i}:: \tau_{i} \sigma_{t}$ for all $1 \leq i \leq n$. On the other hand, taking into account (c) and the linearity of $f \bar{t}_{n}$ we can build a type environment $T_{0}^{\prime}$ with $\operatorname{dom}\left(T_{0}^{\prime}\right)=\operatorname{var}\left(f \bar{t}_{n}\right)$ and such that $(\mathrm{e}) T_{0}^{\prime} \vdash_{W T} t_{i}:: \tau_{i} \sigma_{t}$ for all $1 \leq$ $i \leq n$, (f) $T \vdash_{W T} X \sigma_{d}:: T_{0}^{\prime}(X)$ for all $X \in \operatorname{var}\left(f \bar{t}_{n}\right)$. To build $T_{0}^{\prime}$, it
is enough to choose as $T_{0}^{\prime}(X)$ the type $\tau_{X}$ inferred for $X \sigma_{d}$ as part of the type inference ensured by (c) (for that $t_{i}$ in which $X$ occurs). Note that $t_{1}, \ldots, t_{n}$ are transparent patterns without variables in common. Therefore we can apply the Transparency Lemma 6 to (d), (e) and we obtain: (g) $T_{0}^{\prime}(X)=\left(T_{0} \sigma_{t}\right)(X)=T_{0}(X) \sigma_{t}$ for all $X \in \operatorname{var}\left(f \bar{t}_{n}\right)$ From (g), (f) and $\operatorname{var}(r) \subseteq \operatorname{var}\left(f \bar{t}_{n}\right)$, we get: $(\mathrm{h}) T \vdash_{W T} X \sigma_{d}:: T_{0}(X) \sigma_{t}$ for all $X \in \operatorname{var}(r)$. Finally, (b) and (h) allow us to apply the Well-typed Substitution Lemma 3, which gives $T \vdash_{W T} r \sigma_{d}:: \tau \sigma_{t}$, as we wanted to prove.

Proof of Theorem 2: Assume a given GORC proof $\Pi$ for $\mathcal{P} \vdash_{G O R C} e \rightarrow t$, with size $k \geq 1$, measured as the number of GORC inference steps. We reason by induction over $k$.
In the base case, $k=1$ and there are three possible cases:
Case BT: In this case $\Pi$ consists of one single application of BT. Then $t=\perp$, and $T \vdash_{W T} \perp:: \tau$ follows from the type inference rule ID, since $(\perp:: \alpha) \in_{\text {var }} \Sigma_{\perp}$.
Case RR: If $\Pi$ consists of one single application of $\mathbf{R R}$, then $e=t=X$, for some variable $X$, and the conclusion is trivial.
Case DC: In this case $\Pi$ must consist of one single application of DC with $m=0$, since $m>0$ would yield size greater that 1 for $\Pi$. Therefore, $e=t=h \in D C \cup F S$, and the conclusion is trivial again.
For the induction step, we assume $k>1$ and we analyze the two possible cases according to the GORC inference rule applied at the last step of $\Pi$ :

Case DC: In this case, $e \rightarrow t$ has the form of the conclusion of the GORCrule $\mathbf{D C}$, with $m \geq 1$. The assumption $T \vdash_{W T} e:: \tau$ becomes $T \vdash_{W T} h \bar{e}_{m}:: \tau$, which implies the existence of types $\tau_{i}$ such that (a) $T \vdash{ }_{W T} e_{i}:: \tau_{i}$ for all $1 \leq i \leq m$, (b) $T \vdash_{W T} h:: \bar{\tau}_{m} \rightarrow \tau$. For each $1 \leq i \leq m$, we have $\mathcal{P} \vdash_{G O R C} e_{i} \rightarrow t_{i}$ with a GORC proof of size less than $k$. By induction hypothesis, we can assume: (c) $T \vdash_{W T} t_{i}:: \tau_{i}$ for all $1 \leq i \leq m$. From (b) and (c), we can conclude $T \vdash_{W T} h \bar{t}_{m}:: \tau$, which is the same as $T \vdash_{W T} t:: \tau$.
Case OR: Now we can assume that $e \rightarrow t$ has the form of the conclusion of the GORC-rule OR, where each premise has a GORC proof of size smaller than $k$. In particular, $e=f \bar{e}_{n} \bar{a}_{m}$ for some $f \in F S^{n}$, and the assumption $T \vdash_{W T} e:: \tau$, implies the existence of types $\tau_{i}, \mu_{j}$ such that: (d) $T \vdash_{W T} e_{i}:: \tau_{i}$ for all $1 \leq i \leq n$, (e) $T \vdash_{W T} a_{j}:: \mu_{j}$ for all $1 \leq j \leq m$, (f) $T \vdash_{W T} f:: \bar{\tau}_{n} \rightarrow$
$\bar{\mu}_{m} \rightarrow \tau$. By the induction hypothesis applied to $e_{i} \rightarrow t_{i}$, we can assume: (g) $T \vdash{ }_{W T} t_{i}:: \tau_{i}$ for all $1 \leq i \leq n$. Due to (f) and (g), we can apply Lemma 9 to $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C\right) \in[\mathcal{P}]_{\perp}$, and we obtain (h) $T \vdash_{W T} r:: \bar{\mu}_{m} \rightarrow \tau$. From (e) and (h) we can infer $T \vdash_{W T} r \bar{a}_{m}:: \tau$. Finally, we can apply the induction hypothesis to $r \bar{a}_{m} \rightarrow t$ to conclude $T \vdash_{W T} t:: \tau$. Note that our reasoning in this case ignores the GORC proofs for $C$ in the premises of OR. In fact, some of these conditions could be ill-typed. This eventuality does not contradict the Subject Reduction Theorem.

### 6.3 Proofs of Results from Subsection 3.2

Proof of Proposition 2: The four items can be proved straightforwardly, using structural induction over $\tau, e$ or $t$, according to the case. A similar result for FO CRWL can be found in [18] as Proposition 5.1. Here we limit ourselves to give the proof of item 3, reasoning by induction of the structure of a partial pattern $t \in P a t_{\perp}$. There are four cases to consider:
Case $t=X, X \in D$ Var: This is a base case. $\llbracket X \rrbracket^{\mathcal{A}} \eta_{d}=\left\langle\eta_{d}(X)\right\rangle$, where $\eta_{d}(X) \in \operatorname{Def} \operatorname{Val}(\mathcal{A})$, if $\eta \in \operatorname{DefVal}(\mathcal{A})$.
Case $t=\perp$ : This is also a base case. $\llbracket \perp \rrbracket^{\mathcal{A}} \eta_{d}=\langle\perp\rangle$.
Case $t=c \bar{t}_{m}, c \in D C^{n}, 0 \leq m \leq n$ : By induction hypothesis, we can assume elements $v_{i} \in D^{\mathcal{A}}$ such that $\llbracket t_{i} \rrbracket^{\mathcal{A}} \eta_{d}=\left\langle v_{i}\right\rangle(1 \leq i \leq m)$. In case that $\eta \in \operatorname{DefVal}(\mathcal{A})$ and the $t_{i}$ are total patterns, we can assume $v_{i} \in \operatorname{Def}\left(D^{\mathcal{A}}\right)$. By item 9 of Definition 5 and monotonicity of @ ${ }^{\mathcal{A}}$, we get

$$
\llbracket c \bar{c}_{m} \rrbracket^{\mathcal{A}} \eta_{d}=c^{\mathcal{A}} @ @^{\mathcal{A}} v_{1} @^{\mathcal{A}} \ldots @^{\mathcal{A}} v_{m}=\langle v\rangle
$$

for some $v \in D^{\mathcal{A}}$, and $v \in \operatorname{Def}\left(D^{\mathcal{A}}\right)$ in the case that $v_{1}, \ldots, v_{m} \in \operatorname{Def}\left(D^{\mathcal{A}}\right)$.
Case $t=f \bar{t}_{m}, f \in F S^{n}, 0 \leq m<n$ : This case is similar to the previous case, also using the induction hypothesis and item 9 of Definition 5 .

Proof of Proposition 3: We reason by induction on the size $n$ (measured as the number of inference steps) of a given derivation of the type judgement $T \vdash{ }_{W T} e:: \tau$.
In the base case, $n=1$ and there are two subcases:
Case VT: In this case $e$ is a variable $X$ and $T \vdash_{W T} X:: \tau$ is proved by one single VR step. Then $\llbracket X \rrbracket^{\mathcal{A}} \eta_{d}=\left\langle\eta_{d}(X)\right\rangle \subseteq \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$, since $\eta$ is well-typed w.r.t. $T$.

Case ID: In this case $e=h \in D C \cup F S$ with principal type declaration $\left(h:: \tau_{0}\right) \in_{\text {var }} \Sigma_{\perp}$. Note that $h=\perp$ is possible here. Necessarily, $T \vdash_{W T} h:: \tau$ has been proved by one single ID step, and $\tau=\tau_{0} \sigma_{t}$ for some $\sigma_{t} \in T S u b$. By the Substitution Lemma 10, $\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}=\llbracket \tau_{0} \rrbracket^{\mathcal{A}} \eta \sigma_{t}$. On the other hand, $\llbracket h \rrbracket^{\mathcal{A}} \eta_{d}$ equals $h^{\mathcal{A}}$ if $h \in F S^{0}$ and $\left\langle h^{\mathcal{A}}\right\rangle$ otherwise. In both cases, $\llbracket h \rrbracket^{\mathcal{A}} \eta_{d} \subseteq$ $\mathcal{E}^{\mathcal{A}}\left(\llbracket \tau_{0} \rrbracket^{\mathcal{A}} \eta \sigma_{t}\right)$ because $\mathcal{A}$ is a well-typed algebra.
For the induction step, we consider a derivation of $T \vdash_{W T}\left(e e_{1}\right):: \tau$ in $n$ steps, $n>1$. The last step must use AP, and there must be shorter derivations proving $T \vdash_{W T} e:: \tau_{1} \rightarrow \tau$ and $T \vdash_{W T} e_{1}:: \tau_{1}$ for some type $\tau_{1}$. By induction hypothesis, we can assume: (a) $\llbracket e \rrbracket^{\mathcal{A}} \eta_{d} \subseteq \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau_{1} \rightarrow \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$ and $\llbracket e_{1} \rrbracket^{\mathcal{A}} \eta_{d} \subseteq \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau_{1} \rrbracket^{\mathcal{A}} \eta_{t}\right)$. Since $\mathcal{A}$ is a well-typed algebra, we know that: (b) $u @^{\mathcal{A}} u_{1} \subseteq \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$ for all $u \in \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau_{1} \rightarrow \tau \rrbracket^{\mathcal{A}} \eta_{t}\right), u_{1} \in \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau_{1} \rrbracket^{\mathcal{A}} \eta_{t}\right)$. On the other hand, we also have: (c) $\llbracket\left(e e_{1}\right) \rrbracket^{\mathcal{A}} \eta_{d}=\llbracket e \rrbracket^{\mathcal{A}} \eta_{d} @{ }^{\mathcal{A}} \llbracket e_{1} \rrbracket^{\mathcal{A}} \eta_{d}=$ $\bigcup\left\{u @{ }^{\mathcal{A}} u_{1} \mid u \in \llbracket e \rrbracket^{\mathcal{A}} \eta_{d}, u_{1} \in \llbracket e_{1} \rrbracket^{\mathcal{A}} \eta_{d}\right\}$. From (a), (b), (c) it follows that $\llbracket\left(e e_{1}\right) \rrbracket^{\mathcal{A}} \eta_{d} \subseteq \mathcal{E}^{\mathcal{A}}\left(\llbracket \tau \rrbracket^{\mathcal{A}} \eta_{t}\right)$, as we wanted to prove.

Proof of Lemma 11: To prove item 1 we have to check that all the technical conditions stated in the Definitions 5, 6 are fulfilled. The crucial points are the following ones:
1 (a) @ $\mathcal{M}_{\mathcal{P}}(T)$ must be monotonic mapping returning cones as values. This follows from items 2 and 3 of Lemma 8. The key fact is that, for patterns $t_{i}, t_{i}^{\prime} \in P a t_{\perp}$ such that $t_{i} \sqsupseteq t_{i}^{\prime}$, one gets:

$$
\left\{t \in P a t_{\perp} \mid \mathcal{P} \vdash_{G O R C} f \bar{t}_{m} \rightarrow t\right\} \subseteq\left\{t \in P a t_{\perp} \mid \mathcal{P} \vdash_{G O R C} f{\overline{t^{\prime}}}_{m}^{\prime} \rightarrow t\right\}
$$

where both sets are cones.
1(b) For every $\tau \in$ Type, the set $\mathcal{E}^{\mathcal{M}_{\mathcal{P}}(T)}(\tau)=\left\{t \in\right.$ Pat $\left._{\perp} \mid T \vdash_{W T} t:: \tau\right\}$ must be a cone. Indeed, $T \vdash_{W T} \perp:: \tau$ holds because of the type inferring rule ID. Moreover, assuming $T \vdash_{W T} t^{\prime}:: \tau$ and $t \sqsupseteq t^{\prime}, T \vdash_{W T} t:: \tau$ follows from Lemma 2.
1(c) For every $f \in F S^{0}$, the set $f \mathcal{M}_{\mathcal{P}(T)}=\left\{t \in\right.$ Pat $\left._{\perp} \mid \mathcal{P} \vdash_{G O R C} f \rightarrow t\right\}$ must be a cone. This is true because of item 2 from Lemma 8 .

To prove item 2 , let us assume that $\mathcal{P}$ is a well-typed program. Considering item 4 of the Proposition 2, as well as the construction of $\mathcal{M}_{\mathcal{P}}(T)$, proving that $\mathcal{M}_{\mathcal{P}}(T)$ is well-typed reduces to check the following conditions:
2(a) $T \vdash_{W T} c:: \tau \sigma_{t}$, for every $c:: \tau \in D C^{n}, \sigma_{t} \in T S u b$.

2(b) $T \vdash_{W T} f:: \tau \sigma_{t}$, for every $f:: \tau \in F S^{n}, \sigma_{t} \in T S u b$.
2(c) For every $\left(f:: \bar{\tau}_{n} \rightarrow \tau_{0}\right) \in F S^{n}, n \geq 0$, for every $t_{i}, t_{i}^{\prime} \in$ Pat $t_{\perp}$, for every $\sigma_{t} \in T S u b: T \vdash_{W T} t_{i}:: \tau_{i} \sigma_{t}(1 \leq i \leq n)$ and $\mathcal{P} \vdash_{G O R C} f \bar{t}_{n} \rightarrow t \Longrightarrow$ $T \vdash_{W T} t:: \tau_{0} \sigma_{t}$.

Indeed, 2(a) and 2(b) follows from the type inference rule ID. On the other hand, the assumptions in $2(\mathrm{c})$ imply $T \vdash_{W T} f \bar{t}_{n}:: \tau_{0} \sigma_{t}$, which allows to deduce $T \vdash_{W T} t:: \tau_{0} \sigma_{t}$ by an application of the Subject Reduction Theorem 2.

Proof of Lemma 12: We start by showing that item 2 is an easy consequence of item 1. The statement $\varphi$ can be either $e \rightarrow t$ or $a \bowtie b$. In the first case, we have:

$$
\begin{aligned}
& \left(\mathcal{M}_{\mathcal{P}}(T), \sigma_{d}\right) \vDash e \rightarrow t \Longleftrightarrow \llbracket t \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d} \subseteq \llbracket e \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d} \Longleftrightarrow \\
& t \sigma_{d} \in \llbracket e \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d} \Longleftrightarrow \mathcal{P} \vdash_{G O R C} e \sigma_{d} \rightarrow t \sigma_{d}
\end{aligned}
$$

where the first equivalence is justified by Definition 8 , the second equivalence is true because of item 4 in Proposition 2 and the third equivalence holds by item 1 of the present lemma.
In the case $\varphi=a \bowtie b$ we reason as follows: $\left(\mathcal{M}_{\mathcal{P}}(T), \sigma_{d}\right) \vDash a \bowtie b \Longleftrightarrow$ there is a total pattern $t \in \llbracket a \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d} \cap \llbracket b \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d} \Longleftrightarrow$ there is a pattern $t \in$ Pat such that $\mathcal{P} \vdash_{G O R C} a \sigma_{d} \rightarrow t$ and $\mathcal{P} \vdash_{G O R C} b \sigma_{d} \rightarrow t \quad \Longleftrightarrow \mathcal{P} \vdash_{G O R C}$ $a \sigma_{d} \bowtie b \sigma_{d}$, where the first equivalence is justified by Definition 8 , the second equivalence is true by item 1 of this lemma, and the third equivalence is justified by the GORC rule JN.
In order to prove item 1, we observe that $(*) \llbracket e \sigma_{d} \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} i d=\llbracket e \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} i d \sigma_{d}=$ $\llbracket e \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d}$, where the first identity holds because of the Substitution Lemma 10 and the second identity is true because $\llbracket \sigma_{d}(X) \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} i d=\left\langle\sigma_{d}(X)\right\rangle$. We will show that every $e \in E x p_{\perp}$ verifies $(* *) \llbracket e \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} i d=\left\{t \in P a t_{\perp} \mid \mathcal{P} \vdash_{G O R C}\right.$ $e \rightarrow t\}$ Note that item 1 follows from (*), (**) (with $e$ replaced by $e \sigma_{d}$ in $(* *)$ ). To simplify the notation in the rest of this proof, we abbreviate " $\llbracket \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} i d$ " as " $\llbracket e \rrbracket^{\mathcal{P} "}$ and " $\mathcal{P} \vdash_{G O R C} e \rightarrow t$ " as " $e \rightarrow_{\mathcal{P}} t$ ". We give separate proofs for the two inclusions: (A) $\llbracket e \rrbracket^{\mathcal{P}} \subseteq\left\{t \in \operatorname{Pat}_{\perp} \mid e \rightarrow_{\mathcal{P}} t\right\}$ and (B) $\left\{t \in P a t_{\perp} \mid e \rightarrow_{\mathcal{P}} t\right\} \subseteq \llbracket e \rrbracket^{\mathcal{P}}$.

Proof of (A) Due to the construction of $\mathcal{M}_{\mathcal{P}}(T)$ and the recursive definition $\overline{\text { of expression }}$ evaluation, the true facts of the form " $t \in \llbracket e \rrbracket^{\mathcal{P}}$ " are exactly
those that can be derived in finitely many steps by means of the following rules:
(D1) $\perp \in \llbracket e \rrbracket^{\mathcal{P}}$, for all $e \in E x p_{\perp}$.
(D2) $X \in \llbracket X \rrbracket^{\mathcal{P}}$, for all $X \in D$ Var.
(D3) $t_{i} \in \llbracket e_{i} \rrbracket^{\mathcal{P}}(1 \leq i \leq m) \Longrightarrow h \bar{t}_{m} \in \llbracket h \bar{e}_{m} \rrbracket^{\mathcal{P}}$, for all rigid and passive expressions $h \bar{e}_{m}$.
(D4) $t_{i} \in \llbracket e_{i} \rrbracket^{\mathcal{P}}(1 \leq i \leq n), u \in \llbracket f \bar{t}_{n} \rrbracket^{\mathcal{P}}, t \in \llbracket u \bar{a}_{m} \rrbracket^{\mathcal{P}} \Longrightarrow t \in \llbracket f \bar{e}_{n} \bar{a}_{m} \rrbracket^{\mathcal{P}}$, for all rigid and active expressions $f \bar{e}_{n} \bar{a}_{m}$.

Assume that " $t \in \llbracket e \rrbracket^{\mathcal{P}}$ " has been derived in $k$ steps by means of the rules (D1)-(D4) above. We use induction over $k$ to show that $e \rightarrow_{\mathcal{P}} t$.
In the base case $k=1, t \in \llbracket e \rrbracket^{\mathcal{P}}$ has been derived by one single application of (D1), (D2) or (D3) with $m=0$. In all these cases, $e \rightarrow_{\mathcal{P}} t$ is trivial.
For the inductive case, $k>1$, the last step in the derivation of $t \in \llbracket e \rrbracket^{\mathcal{P}}$ must correspond to rule (D3) with $m>0$, or to rule (D4). In the (D3) subcase, we get $e=h \bar{e}_{m}$ and $t=h \bar{t}_{m}$ where $e_{i} \rightarrow_{\mathcal{p}} t_{i}(1 \leq i \leq m)$ can be assumed by induction hypothesis. Therefore, $e \rightarrow \mathcal{p} t$ follows by the GORC rule DC. In the (D4) subcase $e=f \bar{e}_{n} \bar{a}_{m}$, and by induction hypothesis we obtain $e_{i} \rightarrow_{\mathcal{P}} t_{i}$ $(1 \leq i \leq n)$ and $u \bar{a}_{m} \rightarrow_{\mathcal{P}} t$, where $u \in \llbracket f \bar{t}_{n} \rrbracket^{\mathcal{P}}$. By construction of $\mathcal{M}_{\mathcal{P}}(T)$, $u \in \llbracket f \bar{t}_{n} \rrbracket^{\mathcal{P}}$ implies $f \bar{t}_{n} \rightarrow_{\mathcal{P}} u$. By Proposition 1, GORC is equivalent to BRC, where reduction is transitive and preserved by contexts. Therefore, we can combine the reductions $e_{i} \rightarrow_{\mathcal{P}} t_{i}(1 \leq i \leq n) ; f \bar{t}_{n} \rightarrow_{\mathcal{P}} u ; u \bar{a}_{m} \rightarrow_{\mathcal{P}} t$ to obtain:

$$
f \bar{e}_{n} \bar{a}_{m} \rightarrow_{\mathcal{P}} f \bar{t}_{n} \bar{a}_{m} \rightarrow_{\mathcal{P}} u \bar{a}_{m} \rightarrow_{\mathcal{P}} t
$$

which proves $f \bar{e}_{n} \bar{a}_{m} \rightarrow_{\mathcal{P}} t$, as desired
Proof of (B) We assume that $e \rightarrow_{\mathcal{P}} t$ has been established be means of a


The base case, $k=1$, corresponds to a GORC proof consisting of one single application of $\mathbf{B T}, \mathbf{R R}$ or $\mathbf{D C}$ with $m=0$. In all these situations, $t \in \llbracket e \rrbracket^{\mathcal{P}}$ is obvious.
For the inductive case, $k>1$, we distinguish two subcases, according to the inference rule used at the last step of the given GORC proof.

Case DC with $m>1$ : We have $e=h \bar{e}_{m}, t=h \bar{t}_{m}$, and $t_{i} \in \llbracket e_{i} \rrbracket^{\mathcal{P}}(1 \leq i \leq$ $m$ ) can be assumed by induction hypothesis. Then $\left.h \bar{t}_{m} \in \llbracket h \bar{e}_{m}\right) \rrbracket^{\mathcal{P}}$ follows by construction of $\mathcal{M}_{\mathcal{P}}(T)$.
Case OR: We have a rule instance $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C\right) \in[\mathcal{P}]_{\perp}$ such that (a) $e_{i} \rightarrow_{\mathcal{P}} t_{i}(1 \leq i \leq n)$, (b) $\mathcal{P} \vdash_{G O R C} C$, (c) $r \bar{a}_{m} \rightarrow_{\mathcal{P}} t$. By induction hypothesis applied to (a), (c), we get $t_{i} \in \llbracket e_{i} \rrbracket^{\mathcal{P}}(1 \leq i \leq n)$ and $t \in \llbracket r \bar{a}_{m} \rrbracket^{\mathcal{P}}$. These facts, together with the monotonicity of the apply operation in any algebra and the definition of expression evaluation, imply the following: (d) $t \in \llbracket r \bar{a}_{m} \rrbracket^{\mathcal{P}}$ and $\llbracket f \bar{t}_{n} \bar{a}_{m} \rrbracket^{\mathcal{P}} \subseteq \llbracket f \bar{e}_{n} \bar{a}_{m} \rrbracket^{\mathcal{P}}$. By (d), it is enough to show that $\llbracket r \bar{a}_{m} \rrbracket^{\mathcal{P}} \subseteq \llbracket f \bar{t}_{n} \bar{a}_{m} \rrbracket^{\mathcal{P}}$, which in turn follows from $\llbracket r \rrbracket^{\mathcal{P}} \subseteq \llbracket f \bar{t}_{n} \rrbracket^{\mathcal{P}}$. To show this, let us assume $u \in \llbracket r \rrbracket^{\mathcal{P}}$. Because of the inclusion (A) (already proved above) we obtain: (e) $r \rightarrow_{\mathcal{P}} u$. Moreover, due to item 1 from Lemma 8, we also have (f) $t_{i} \rightarrow_{\mathcal{P}} t_{i}(1 \leq i \leq n)$. Now, $f \bar{t}_{n} \rightarrow_{\mathcal{P}} u$ follows from (f), (b), (e) and the GORC rule OR. Due to the construction of $\mathcal{M}_{\mathcal{P}}(T)$, $f \bar{t}_{n} \rightarrow_{\mathcal{P}} u$ implies $u \in \llbracket f \bar{t}_{n} \rrbracket^{\mathcal{P}}$, which completes the proof of $\llbracket r \rrbracket^{\mathcal{P}} \subseteq \llbracket f \bar{t}_{n} \rrbracket^{\mathcal{P}}$ and the Lemma.

Proof of Theorem 3: In order to prove $\mathcal{M}_{\mathcal{P}}(T) \vDash \mathcal{P}$, we consider any defining rule $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C \square T\right) \in \mathcal{P}$ and any data substitution $\sigma_{d} \in$ $D S u b_{\perp}$ (which is the same as a data valuation over $\mathcal{M}_{\mathcal{P}}(T)$ ). Assume that $\left(\mathcal{M}_{\mathcal{P}}(T), \sigma_{d}\right) \vDash C$. By item 2 from Lemma 12, this means that $\mathcal{P} \vdash_{G O R C} C \sigma_{d}$. We have to check $\llbracket r \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d} \subseteq \llbracket f \bar{t}_{n} \rrbracket^{\mathcal{M}_{\mathcal{P}}(T)} \sigma_{d}$. By item 1 from Lemma 12, this amounts to show:

$$
\left\{t \in P a t_{\perp} \mid \mathcal{P} \vdash_{G O R C} r \sigma_{d} \rightarrow t\right\} \subseteq\left\{t \in P a t_{\perp} \mid \mathcal{P} \vdash_{G O R C}\left(f \bar{t}_{n}\right) \sigma_{d} \rightarrow t\right\}
$$

This is true, because for any $t \in P a t_{\perp}$ such that $\mathcal{P} \vdash_{G O R C} r \sigma_{d} \rightarrow t$, we can derive $\mathcal{P} \vdash_{G O R C}\left(f \bar{t}_{n}\right) \sigma_{d} \rightarrow t$ in one OR step, using $\mathcal{P} \vdash_{G O R C} C \sigma_{d}$ (which we are assuming) and $\mathcal{P} \vdash_{G O R C} t_{i} \sigma_{d} \rightarrow t_{i} \sigma_{d}$ (which is true by item 1 from Lemma 8). Next, we show the equivalence of the items in the Theorem's statement by proving three implications.
$\underline{1 \Longrightarrow 2}$ : Let us fix any model $\mathcal{A} \vDash \mathcal{P}$ and any totally defined valuation $\eta \in \operatorname{DefVal}(\mathcal{A})$. We assume $\mathcal{P} \vdash_{G O R C} \varphi$ with some proof $\Pi$ of size $k$, and we reason by induction over $k$ to prove $(\mathcal{A}, \eta) \vDash \varphi$.
In the base case, $k=1, \varphi$ must be either $e \rightarrow \perp$ or $X \rightarrow X$ or $h \rightarrow h$, and $(\mathcal{A}, \eta) \vDash \varphi$ is trivially true.
In the inductive case, $k>1$, we must consider three subcases.
(a) The proof $\Pi$ ends with a DC step. Then $\varphi=h \bar{e}_{m} \rightarrow h \bar{t}_{m}$, and by induction hypothesis applied to the premises of the DC inference, we get $(\mathcal{A}, \eta) \vDash e_{i} \rightarrow t_{i}$, which amounts to $\llbracket t_{i} \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket e_{i} \rrbracket^{\mathcal{A}} \eta$, for all $1 \leq i \leq n$, $\llbracket h \bar{t}_{m} \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket h \bar{e}_{m} \rrbracket^{\mathcal{A}} \eta$ is easy to check, using the definition of expression evaluation. Therefore, $(\mathcal{A}, \eta) \vDash h \bar{e}_{m} \rightarrow h \bar{t}_{m}$.
(b) The proof $\Pi$ ends with an OR step. Then $\varphi=f \bar{e}_{n} \bar{a}_{m} \rightarrow t$, and by induction hypothesis applied to the premises of the OR inference, we get (b1) $(\mathcal{A}, \eta) \vDash e_{i} \rightarrow t_{i}$, i.e. $\left.\llbracket t_{i}\right]^{\mathcal{A}} \eta \subseteq \llbracket e_{i} \rrbracket^{\mathcal{A}} \eta$, $(1 \leq i \leq n)$, (b2) $(\mathcal{A}, \eta) \vDash C$, (b3) $(\mathcal{A}, \eta) \vDash r \bar{a}_{m} \rightarrow t$, i.e. $\llbracket t \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket r \bar{a}_{m} \rrbracket^{\mathcal{A}} \eta$ where $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C\right) \in[\mathcal{P}]_{\perp}$ is the instance of $\mathcal{P}$-rule used in the OR step. Since $\mathcal{A}$ is a model of $\mathcal{P}, \mathcal{A}$ satisfies all the rewrite rules in $\mathcal{P}$. Due to Lemma $10, \mathcal{A}$ satisfies also all the instances of rules in $\mathcal{P}$, in particular, $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C\right)$. Then, from (b2) we can infer $(\mathrm{b} 4)(\mathcal{A}, \eta) \vDash f \bar{t}_{n} \rightarrow r$, i.e. $\llbracket r \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket f \bar{t}_{n} \rrbracket^{\mathcal{A}} \eta$. Considering the definition of expression evaluation, it is easy to see that (b3), (b4) and (b1) can be applied successively, leading to the inclusions:

$$
\llbracket t \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket r \bar{a}_{m} \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket f \bar{t}_{n} \bar{a}_{m} \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket f \bar{e}_{n} \bar{a}_{m} \rrbracket^{\mathcal{A}} \eta
$$

This entails $\llbracket t \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket f \bar{e}_{n} \bar{a}_{m} \rrbracket^{\mathcal{A}} \eta$, i.e. $(\mathcal{A}, \eta) \vDash f \bar{e}_{n} \bar{a}_{m} \rightarrow t$.
(c) The proof $\Pi$ ends with a JN step. Then $\varphi=a \bowtie b$, and by induction hypothesis applied to the premises of the $\mathbf{J N}$ inference, we get a total pattern $t \in P a t$ such that $\llbracket t \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket a \rrbracket^{\mathcal{A}} \eta$ and $\llbracket t \rrbracket^{\mathcal{A}} \eta \subseteq \llbracket b \rrbracket^{\mathcal{A}} \eta$. Since $\eta$ is totally defined, we can assume $\llbracket t \rrbracket^{\mathcal{A}} \eta=\langle v\rangle$, for some $v \in \operatorname{Def}\left(D^{\mathcal{A}}\right)$, by item 3 of Proposition 2. Then there exists a totally defined element $v \in\left(\llbracket a \rrbracket^{\mathcal{A}} \eta \cap \llbracket b \rrbracket^{\mathcal{A}} \eta\right)$, which means $(\mathcal{A}, \eta) \vDash a \bowtie b$.
$\underline{2 \Longrightarrow 3}$ : This implication holds because $\mathcal{M}_{\mathcal{P}}(T) \vDash \mathcal{P}$, as we have proved already, and $i d$ is a totally defined valuation.
$3 \Longrightarrow 1$ : This follows from item 2 of Lemma 12 , taking the identity substitution $i d$ as $\sigma_{d}$.

### 6.4 Proofs of Results from Subsection 4.1

## Proof of Lemma 13:

$(a) \Longrightarrow(b)$ : Assume that $G$ is well-typed, and take $T^{\prime}=\hat{T}$. By the Type Reconstruction Theorem 1, $\hat{T} \vdash_{W T}\left(P, C, S_{d}\right)::$ bool.
$(b) \Longrightarrow(c)$ : This follows from the form of the type inference rules and the principal types of the "operations" $(\rightarrow),(\bowtie),(\approx)$ and $($,$) .$
$(c) \Longrightarrow(a):$ Assume $T \leq T^{\prime}$ for which (c1), (c2) and (c3) holds. Then it is easy to see that $T^{\prime} \vdash_{W T}\left(P, C, S_{d}\right)::$ bool. Then, the Type Reconstruction Theorem 1 ensures $\left.T R\left(T,\left(P, C, S_{d}\right)\right)=\left((-)^{\tau}, E\right)\right)$ and $\sigma_{t} \in \operatorname{TSol}(E)$ such that $T \sigma_{t}=T^{\prime}$ and $\tau \sigma_{t}=$ bool. In particular, $G$ is well-typed because $\operatorname{TSol}(E) \neq \emptyset$.

## Proof of Lemma 14:

Item 1: To show the inclusion, let us assume $(R, \theta) \in W T S o l(\hat{G})$. Then $\theta_{d} \in \operatorname{Sol}(G)$ and also: (a) $\operatorname{dom}(R) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(\hat{T})$, (b) $\theta_{t} \in \operatorname{TSol}\left(\hat{S}_{t}\right)$, (c) $\left(\hat{T} \theta_{t} \cup R\right) \vdash_{W T} X \theta_{d}:: \hat{T}(X) \theta_{t}$, for all $X \in \operatorname{dom}(\hat{T})$. To show $(R, \theta) \in$ $W T S o l(G)$ we need: $\left(\mathrm{a}^{\prime}\right) \operatorname{dom}(R) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T),\left(\mathrm{b}^{\prime}\right) \theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$, ( $\left.\mathrm{c}^{\prime}\right)$ $\left(T \theta_{t} \cup R\right) \vdash_{W T} X \theta_{d}:: T(X) \theta_{t}$, for all $X \in \operatorname{dom}(T)$. By construction of $\hat{G}$ from $G$, we have $\hat{T}=T \hat{\sigma}_{t}$, where $\hat{\sigma}_{t}=m g u\left(S_{t}, E\right)$. Then $(\mathrm{a}) \Longleftrightarrow\left(\mathrm{a}^{\prime}\right)$ and $(\mathrm{b}) \Longrightarrow$ (b'). Moreover, (b) also implies $\theta_{t}=\hat{\sigma}_{t} \theta_{t}$, which entails $\hat{T} \theta_{t}=T \hat{\sigma}_{t} \theta_{t}=T \theta_{t}$ and also $\hat{T}(X) \theta_{t}=T(X) \hat{\sigma}_{t} \theta_{t}=T(X) \theta_{t}$ for all $X \in \operatorname{dom}(T)=\operatorname{dom}(\hat{T})$. This being the case, $(\mathrm{c}) \Longleftrightarrow\left(\mathrm{c}^{\prime}\right)$.

To show that the opposite inclusion can fail, consider $G \neq \hat{G}$ given as follows:

$$
\begin{aligned}
& G=\emptyset \square[\mathrm{X} \mid \mathrm{Xs}] \bowtie[\mathrm{Y} \mid \mathrm{Ys}] \square \emptyset \square \emptyset \square\{\mathrm{X}:: \alpha, \mathrm{Xs}::[\beta], \mathrm{Y}:: \alpha, \\
& \mathrm{Ys}::[\beta]\} \\
& \hat{G}=\emptyset \square[\mathrm{X} \mid \mathrm{Xs}] \bowtie[\mathrm{Y} \mid \mathrm{Ys}] \square \emptyset \square \beta \approx \alpha \square\{\mathrm{X}, \mathrm{Y}:: \alpha ; \mathrm{Xs}, \mathrm{Ys}::[\alpha]\}
\end{aligned}
$$

Then, with the substitutions $\theta_{t}=\{\alpha \mapsto$ nat, $\beta \mapsto$ bool $\}$ and $\theta_{d}=\{\mathrm{X} \mapsto \mathrm{z}$, Xs $\mapsto$ [true], Y $\mapsto \mathrm{z}, \mathrm{Ys} \mapsto[$ true] $\}$ we get $(\emptyset, \theta) \in \operatorname{WTSol}(G) \backslash W T S o l(\hat{G})$.
Item 2: Assume $(a \bowtie b) \in C$. Since $G$ is well-typed and $\hat{G}=G$, there must be some $\tau \in$ Type such that (a) $T \vdash_{W T} a:: \tau$ and $T \vdash_{W T} b:: \tau$. On the other hand, since $(R, \theta) \in W T S o l(G)$, we have (b) $\left(T \theta_{t} \cup R\right) \vdash_{W T} X \theta_{d}:: T(X) \theta_{t}$, for all $X \in \operatorname{var}(a) \cup \operatorname{var}(b)$. Now, (a), (b) match the hypothesis of Lemma 3 (with $T$ as $T_{0}$ and $T \theta_{t} \cup R$ as $T_{1}$ ) and we can conclude $\left(T \theta_{t} \cup R\right) \vdash_{W T} a \theta_{d}::$ $\tau \theta_{t}$ and $\left(T \theta_{t} \cup R\right) \vdash_{W T} b \theta_{d}:: \tau \theta_{t}$. An analogous reasoning can be made for $(e \rightarrow t) \in P$ and $(X \approx t) \in S_{d}$.

To show that the result can fail if $G \neq \hat{G}$, consider $G, \hat{G}$ and $\theta$ as in the previous item. Then $(\emptyset, \theta) \in W \operatorname{TSol}(G)$, but $T \theta_{t}=\{\mathrm{X}, \mathrm{Y}::$ nat; $\mathrm{Xs}, \mathrm{Ys}::$ [bool] $\} \nvdash_{W T}([\mathrm{X} \mid \mathrm{Xs}] \bowtie[\mathrm{Y} \mid \mathrm{Ys}]) \theta_{d}=[$ z|true $] \bowtie[$ [z|true $]$.

### 6.5 Proofs of Results from Subsection 4.2

Proof of Theorem 4: We rely on some basic facts from computability theory, which can be found in textbooks such as [8]. In particular, we recall the following well-known, undecidable problem $K$ : given a natural number $n$, tell if $\varphi_{n}(n) \downarrow$ holds. Here, the notation $\varphi_{n}(n) \downarrow$ means that the computable function $\varphi_{n}$ with index $n$ eventually halts when given $n$ itself as argument.

Using the type nat and the constructors $\mathbf{z}$, s from Example 2, it is possible to write a well-typed simple program $\mathcal{P}$ including defining rules for a function halt :: nat $\rightarrow$ nat such that, for all $n \in \mathbb{N}$, one has:

- If $\varphi_{n}(n)$ halts in $k$ steps, the evaluation of halt ( $\mathbf{s}^{n} \mathbf{z}$ ) w.r.t. $\mathcal{P}$ computes the result $\mathbf{s}^{k} \mathbf{z}$.
- If $\varphi_{n}(n)$ does not halt, the evaluation of halt ( $\mathbf{s}^{n} z$ ) w.r.t. $\mathcal{P}$ does not terminate, but computes the potentially infinite result $\mathrm{s}(\mathrm{s}(\mathrm{s}(\mathrm{s}(\mathrm{s} \ldots$.

In the two items above, the notation $\mathbf{s}^{n} \mathbf{z}$ refers to the natural representation of $n \in \mathbb{N}$ using the data constructors $\mathbf{z}$ and $\mathbf{s}$. Building the program $\mathcal{P}$ so that halt behaves as described is possible, because simple CRWL programs are powerful enough to simulate Turing machines (or any other Turing-complete computation model). We omit the tedious proof of this claim, that would follow well-known techniques from computability theory.

To continue with our proof, let us assume that program $\mathcal{P}$ is expanded to include the defining rules for the functions tail and second, as given in Example 2, as well as the following defining rules for four new functions:

```
oh, fefo :: nat }->(\alpha->\alpha
oh N }->\mathrm{ fefo(halt N) }\Leftarrow\emptyset \square {N :: nat
fefoz }->\mathrm{ snd (tail [true]) & Ø ם Ø
fefo(sN)}->\mathrm{ fefoN }\Leftarrow\emptyset\square{N:: nat
ah, fefa :: nat -> ( }\alpha->\alpha
ah N }->\mathrm{ fefa(halt N) & Ø ם {N :: nat}
fefaz }->\mathrm{ snd (tail [z]) & Ø व Ø
fefa(sN)}->\mathrm{ fefaN }\Leftarrow\emptyset\square {N :: nat
```

Finally, let $G_{n}$ be the simple goal $\emptyset \square$ oh ( $\mathrm{s}^{n} \mathrm{z}$ ) $\bowtie$ ah ( $\mathrm{s}^{n} \mathrm{z}$ ) $\square \emptyset \square \emptyset \square \emptyset$. Due to the behaviour of the function halt w.r.t. program $\mathcal{P}$, the following equivalences hold for any natural number $n: \varphi_{n}(n) \downarrow \Longleftrightarrow \exists k \in \mathbb{N}$ such
that $\varphi_{n}(n)$ halts in $k$ steps $\Longleftrightarrow$ solving $G_{n}$ w.r.t. $\mathcal{P}$ using CLNC eventually leads to an opaque decomposition step.

In fact, in case that $\varphi_{n}(n) \downarrow$, solving $G_{n}$ eventually leads to solving the goal snd (tail [true]) $\bowtie$ snd (tail [z]), which needs opaque decomposition; and in the case that $\varphi_{n}(n) \downarrow$ does not halt, solving $G_{n}$ gives rise to a nonterminating CLNC computation without opaque decompositions. With this we have shown that $K$ can be reduced to the simple restriction of ODP, which is thus undecidable.

### 6.6 Proofs of Results from Subsection 4.3

Proof of Lemma 15: Assume $T R\left(T, S_{d}\right)=(-, E)$. Since $\hat{G}$ is the type closure of $G$, we know that: (a) $\hat{\sigma}_{t}=m g u\left(S_{t}, E\right)$, (b) $\hat{T}=T \hat{\sigma}_{t}$. By Definition $12,\left(\emptyset,\left(\hat{\sigma}_{t}, \sigma_{d}\right)\right)$ is a well-typed solution of $G$ and $\hat{G}$ iff the following four conditions are satisfied: (c) $\hat{\sigma}_{t} \in T \operatorname{Sol}\left(S_{t}\right)$, (d) $T \hat{\sigma}_{t} \vdash_{W T} X \sigma_{d}:: \tau \hat{\sigma}_{t}$, for all $(X:: \tau) \in T,\left(c^{\prime}\right) \hat{\sigma}_{t} \in T S o l\left(\hat{S}_{t}\right),\left(\mathrm{d}^{\prime}\right) T \hat{\sigma}_{t} \hat{\sigma}_{t} \vdash_{W T} X \sigma_{d}:: \tau \hat{\sigma}_{t} \hat{\sigma}_{t}$, for all $(X:: \tau) \in T$. Note that $\left(\mathrm{d}^{\prime}\right)$ can be stated like this because of $(\mathrm{b})$. Moreover, (c) holds because of (a), (c') holds because $\hat{S}_{t}$ is the set of equations in solved form representing $\hat{\sigma}_{t}$, and (d), ( $\mathrm{d}^{\prime}$ ) are equivalent because $\hat{\sigma}_{t}$ is idempotent. In order to prove (d) we distinguish two cases:
$X \notin \operatorname{dom}\left(\sigma_{d}\right)$ : Then $X \sigma_{d}=X$ and (d) holds because of the type inference rule VR.
$X \in \operatorname{dom}\left(\sigma_{d}\right)$ : Then $X \sigma_{d}=t$ for some $t$ such that $(X \approx t) \in S_{d}$. Because of Lemma 13, T $\hat{\sigma}_{t} \vdash_{W T} t::\left(T \hat{\sigma}_{t}\right)(X)$. Since $t=X \sigma_{d}$ and $\left(T \hat{\sigma}_{t}\right)(X)=$ $T(X) \hat{\sigma}_{t}=\tau \hat{\sigma}_{t},(\mathrm{~d})$ is proved.

Proof of Lemma 16: To prove the lemma, we consider the CLNC transformation rules one by one. In each case, we assume that $G$ and $G^{\prime}$ are exactly as they appear in the presentation of the CLNC given in Subsection 4.2.
$G^{\prime}$ is admissible: For each CLNC rule, we can prove the preservation of the admissibility conditions LN, EX, NC and SL as in the first-order case [18].
In the sequel, we will use the notation $T_{1} \uplus T_{2} \uplus \ldots \uplus T_{k}$ to express the union of $k \geq 2$ type environments with pairwise disjoint domains.

## Rules for the Unsolved Part

(ID) (a) Because of $(R, \theta) \in W T S o l\left(G^{\prime}\right)$ we know:

1. $\theta_{d} \in \operatorname{Sol}\left(S_{d} \rho_{d}, X \approx h \bar{V}_{m}\right)$ with $\rho_{d}=\left\{X \mapsto h \bar{V}_{m}\right\}$.
2. $\operatorname{dom}(R) \subseteq\left(\operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)\right.$.
3. $\mathcal{P} \vdash_{G O R C}\left(P \square \bar{a}_{p} \asymp \bar{b}_{p}, C\right) \rho_{d} \theta_{d}$.
4. $\theta_{t} \in \operatorname{TSol}\left(S_{t}^{\prime}\right)$ with $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau \approx \tau^{\prime}\right)$, where $\left(h:: \bar{\tau}_{m} \rightarrow \tau\right) \in_{v a r} \Sigma$ and $\hat{T}(X)=\tau^{\prime}$.
5. $\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}::\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)(Y) \theta_{t}$ must hold, for all $Y \in \operatorname{dom}\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)$.

Therefore, it holds that:
(D) $\rho_{d} \theta_{d}=\theta_{d}$ by 1 .
(T) $\sigma_{t}^{\prime} \theta_{t}=\theta_{t}$ and $\hat{\sigma}_{t} \sigma_{t}^{\prime}=\sigma_{t}^{\prime}$ by 4 .
(E) Since the variables of $\left\{\bar{V}_{m}:: \bar{\tau}_{m}\right\}$ are fresh, $\operatorname{dom}\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)=$ $\left\{\bar{V}_{m}\right\} \uplus \operatorname{dom}(T)$. Moreover, (T) implies that $\hat{T} \sigma_{t}^{\prime}=T \sigma_{t}^{\prime}, \hat{T} \sigma_{t}^{\prime} \theta_{t}=T \theta_{t}$ and $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \theta_{t}=\left\{\bar{V}_{m}:: \bar{\tau}_{m} \theta_{t}\right\} \uplus T \theta_{t}$.

Now we prove that $\left(\left\{\bar{V}_{m}:: \bar{\tau}_{m} \theta_{t}\right\} \cup R, \theta\right) \in W T S o l(G)$ :

- $\theta_{d} \in \operatorname{Sol}\left(S_{d}\right)$, by 1 and (D).
- $\operatorname{dom}\left(\left\{\bar{V}_{m}:: \bar{\tau}_{m} \theta_{t}\right\} \cup R\right) \subseteq\left(\operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T)\right)$, by $(\mathbf{E})$ and 2 .
- $\mathcal{P} \vdash_{G O R C}\left(P\right.$ ם $\left.\bar{a}_{p} \asymp X \bar{b}_{p}, C\right) \theta_{d}$ : By 3 and (D), for $i \in\{1, \ldots, p\}$ $\mathcal{P} \vdash_{G O R C}\left(a_{i} \asymp b_{i}\right) \theta_{d}$, then $\mathcal{P} \vdash_{G O R C}\left(h \bar{V}_{m} \bar{a}_{p} \asymp h \bar{V}_{m} \bar{b}_{p}\right) \theta_{d}$. Since $X \theta_{d}=X \rho_{d} \theta_{d}=\left(h \bar{V}_{m}\right) \theta_{d}$, we obtain that $\mathcal{P} \vdash_{G O R C}\left(X \bar{a}_{p} \asymp X \bar{b}_{p}\right) \theta_{d}$.
- $\theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$, because 4 implies $\theta_{t} \in \operatorname{TSol}\left(S_{t}^{\prime}\right) \subseteq \operatorname{TSol}\left(\hat{S}_{t}\right) \subseteq \operatorname{TSol}\left(S_{t}\right)$.
- $\left(T \theta_{t} \cup\left\{\bar{V}_{m}:: \bar{\tau}_{m} \theta_{t}\right\} \cup R\right) \vdash_{W T} Y \theta_{d}:: T(Y) \theta_{t}$ for all $Y \in \operatorname{dom}(T) \subseteq$ $\operatorname{dom}\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)$, by (E) and 5 .
(b) To obtain that $G^{\prime}$ is also well-typed, we only need to prove:
[1] $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(X \approx h \bar{V}_{m}\right)::$ bool: Because of $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right)$ $\vdash_{W T} X:: \tau^{\prime},\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \vdash_{W T} h \bar{V}_{m}:: \tau$ and Lemma $4,\left(\bar{V}_{m}::\right.$ $\left.\bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} X:: \tau^{\prime} \sigma_{t}^{\prime}$ and $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} h \bar{V}_{m}:: \tau \sigma_{t}^{\prime}$. Moreover, $\tau \sigma_{t}^{\prime}=\tau^{\prime} \sigma_{t}^{\prime}$ by 4 .
[2] $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(P, C, S_{d}\right) \rho_{d}::$ bool: This follows from $\hat{T} \vdash_{W T}$ $\left(P, C, S_{d}\right)::$ bool by applying Lemma 3 with $T_{0}=\hat{T}, T_{1}=\left(\bar{V}_{m}::\right.$ $\left.\bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}, \sigma_{t}=\sigma_{t}^{\prime}, \sigma_{d}=\rho_{d}$. This is possible by [1].
[3] For $i \in\{1, \ldots, p\}\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(a_{i} \asymp b_{i}\right) \rho_{d}::$ bool: Since $G$ is well-typed, $\hat{T} \vdash_{W T}\left(X \bar{a}_{p} \asymp X \bar{b}_{p}\right)::$ bool. Thanks to [1], we can apply Lemma 3 with $T_{0}=\hat{T}, T_{1}=\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}, \sigma_{t}=\sigma_{t}^{\prime}, \sigma_{d}=\rho_{d}$ and we obtain $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(X \bar{a}_{p} \asymp X \bar{b}_{p}\right) \rho_{d}::$ bool, which can be rewritten as $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(h \bar{V}_{m} \bar{a}_{p} \asymp h \bar{V}_{m} \bar{b}_{p}\right) \rho_{d}::$ bool. Since we are assuming a transparent step, $h$ must be $(m+p)$-transparent. Then, we can apply Lemma 7 to obtain types $\mu_{i}, i \in\{1, \ldots, p\}$ such that $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} a_{i} \rho_{d}:: \mu_{i}:: b_{i} \rho_{d}$.
(DC1) (a) Because of $(R, \theta) \in \operatorname{WTSol}\left(G^{\prime}\right)$ we know:

1. $\theta_{d} \in \operatorname{Sol}\left(S_{d}\right)$.
2. $\operatorname{dom}(R) \subseteq\left(\operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T)\right)$.
3. $\mathcal{P} \vdash_{G O R C}\left(P \square \bar{a}_{m} \asymp \bar{b}_{m}, C\right) \theta_{d}$.
4. $\theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$.
5. $\left(T \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}:: T(Y) \theta_{t}$ must hold, for all $Y \in \operatorname{dom}(T)$.
$(R, \theta) \in W T S o l(G): \mathcal{P} \vdash_{G O R C}\left(P \square h \bar{a}_{m} \asymp h \bar{b}_{m}, C\right) \theta_{d}$ follows easily from 3. Moreover, $S_{t}, S_{d}$ and $T$ are not modified.
(b) $G$ well-typed implies, in particular, that $\hat{T} \vdash_{W T}\left(P, C, S_{d}\right)::$ bool and $\hat{T} \vdash_{W T}\left(h \bar{a}_{m} \asymp h \bar{b}_{m}\right)::$ bool. Therefore, $G^{\prime}$ is well-typed, if we can prove that $\hat{T} \vdash_{W T}\left(a_{i} \asymp b_{i}\right)::$ bool, for $i \in\{1, \ldots, m\}$. Since $\hat{T} \vdash_{W T}\left(h \bar{a}_{m} \asymp h \bar{b}_{m}\right)::$ bool and we are assuming a transparent step, $h$ must be $m$-transparent. By Lemma 7, there exist types $\tau_{i}$ for all $i \in\{1, \ldots, m\}$ such that $\hat{T} \vdash_{W T} a_{i}::$ $\tau_{i}:: b_{i}$, which implies $\hat{T} \vdash_{W T}\left(a_{i} \asymp b_{i}\right)::$ bool.
(BD) (a) Because of $(R, \theta) \in \operatorname{WTSol}\left(G^{\prime}\right)$ we know:
6. $\theta_{d} \in \operatorname{Sol}\left(S_{d} \rho_{d}, X \approx s\right)$ with $\rho_{d}=\{X \mapsto s\}$.
7. $\operatorname{dom}(R) \subseteq\left(\operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}\left(\hat{T} \sigma_{t}^{\prime}\right)\right.$.
8. $\mathcal{P} \vdash_{G O R C}\left(P \square \bar{a}_{k} \asymp \bar{b}_{k}, C\right) \rho_{d} \theta_{d}$.
9. $\theta_{t} \in \operatorname{TSol}\left(S_{t}^{\prime}\right), \sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau \approx \tau^{\prime}\right)$ with $\operatorname{PA}\left(\hat{T}, s \bar{b}_{k}\right)=\left(s^{\tau^{\prime}-}\right)^{-}$, $\hat{T}(X)=\tau$.
10. $\left(\hat{T} \sigma_{t}^{\prime} \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}::\left(\hat{T} \sigma_{t}^{\prime}\right)(Y) \theta_{t}$ must hold, for all $Y \in \operatorname{dom}\left(\hat{T} \sigma_{t}^{\prime}\right)$.

Therefore, it holds that:
(D) $\rho_{d} \theta_{d}=\theta_{d}$ by 1 .
(T) $\sigma_{t}^{\prime} \theta_{t}=\theta_{t}$ and $\hat{\sigma}_{t} \sigma_{t}^{\prime}=\sigma_{t}^{\prime}$ by 4 .
(E) $\hat{T} \sigma_{t}^{\prime}=T \sigma_{t}^{\prime}$ and $\hat{T} \sigma_{t}^{\prime} \theta_{t}=T \theta_{t}$ using (T).

Now we prove that $(R, \theta) \in W T S o l(G)$ :

- $\theta_{d} \in \operatorname{Sol}\left(S_{d}\right)$, by 1 and (D).
- $\operatorname{dom}(R) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T)$, by $(\mathbf{E})$ and 2 .
- $\mathcal{P} \vdash_{G O R C}\left(P \square X \bar{a}_{k} \asymp s \bar{b}_{k}, C\right) \theta_{d}$ : By 3 and (D), for $i \in\{1, \ldots, k\}$ $\mathcal{P} \vdash_{G O R C}\left(a_{i} \asymp b_{i}\right) \theta_{d}$, then $\mathcal{P} \vdash_{G O R C}\left(s \bar{a}_{k} \asymp s \bar{b}_{k}\right) \theta_{d}$. Since $X \theta_{d}=$ $X \rho_{d} \theta_{d}=s \theta_{d}$, we obtain that $\mathcal{P} \vdash_{G O R C}\left(X \bar{a}_{k} \asymp s \bar{b}_{k}\right) \theta_{d}$.
- $\theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$, because 4 implies $\operatorname{TSol}\left(S_{t}^{\prime}\right) \subseteq \operatorname{TSol}\left(\hat{S}_{t}\right) \subseteq \operatorname{TSol}\left(S_{t}\right)$.
- $\left(T \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}:: T(Y) \theta_{t}$ for all $Y \in \operatorname{dom}(T)$, because of (E) and 5.
(b) To obtain that $G^{\prime}$ is also well-typed, we only need to prove:
[1] $\hat{T} \sigma_{t}^{\prime} \vdash_{W T}(X \approx s)::$ bool: Because of $\hat{T} \vdash_{W T} X:: \tau, \hat{T} \vdash_{W T} s:: \tau^{\prime}$ and Lemma 4, $\hat{T} \sigma_{t}^{\prime} \vdash_{W T} X:: \tau \sigma_{t}^{\prime}$ and $\hat{T} \sigma_{t}^{\prime} \vdash_{W T} s:: \tau^{\prime} \sigma_{t}^{\prime}$. Moreover, $\tau \sigma_{t}^{\prime}=\tau^{\prime} \sigma_{t}^{\prime}$ by 4.
[2] $\hat{T} \sigma_{t}^{\prime} \vdash_{W T}\left(P, C, S_{d}\right) \rho_{d}::$ bool: This follows from $\hat{T} \vdash_{W T}\left(P, C, S_{d}\right)::$ bool by applying the Lemma 3 with $T_{0}=\hat{T}, T_{1}=\hat{T} \sigma_{t}^{\prime}, \sigma_{t}=\sigma_{t}^{\prime}$, $\sigma_{d}=\rho_{d}$. This is possible by [1].
[3] For $i \in\{1, \ldots, k\}, \hat{T} \sigma_{t}^{\prime} \vdash_{W T}\left(a_{i} \asymp b_{i}\right) \rho_{d}::$ bool: Since $G$ is well-typed, $\hat{T} \vdash_{W T}\left(X \bar{a}_{k} \asymp s \bar{b}_{k}\right)::$ bool. Applying Lemma 3 as in [2], we can deduce $\hat{T} \sigma_{t}^{\prime} \vdash_{W T}\left(X \bar{a}_{k} \asymp s \bar{b}_{k}\right) \rho_{d}::$ bool, which can be rewritten as $\hat{T} \sigma_{t}^{\prime} \vdash_{W T}\left(s \bar{a}_{k} \asymp s \bar{b}_{k}\right) \rho_{d}::$ bool, where $s$ must have the form $h \bar{t}_{m}$ due to the assumptions of (BD). Since we are assuming a transparent step, $h$ must be ( $m+k$ )-transparent. Then, we can apply Lemma 7 to obtain types $\tau_{i}, i \in\{1, \ldots, k\}$ such that $\hat{T} \sigma_{t}^{\prime} \vdash_{W T} a_{i} \rho_{d}:: \tau_{i}:: b_{i} \rho_{d}$.
(IM) (a) Because of $(R, \theta) \in W T S o l\left(G^{\prime}\right)$ we know:

1. $\theta_{d} \in \operatorname{Sol}\left(S_{d} \rho_{d}, X \approx h \bar{V}_{m}\right)$ with $\rho_{d}=\left\{X \mapsto h \bar{V}_{m}\right\}$.
2. $\operatorname{dom}(R) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)$.
3. $\mathcal{P} \vdash_{G O R C}\left(P \square \bar{V}_{m} \bar{a}_{k} \asymp \bar{e}_{m} \bar{b}_{k}, C\right) \rho_{d} \theta_{d}$.
4. $\theta_{t} \in \operatorname{TSol}\left(S_{t}^{\prime}\right)$, with $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau \approx \tau^{\prime}\right)$, where $\left(h:: \bar{\tau}_{m} \rightarrow \tau\right) \in_{\text {var }} \Sigma$ and $\hat{T}(X)=\tau^{\prime}$.
5. $\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}::\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)(Y) \theta_{t}$ must hold, for all $Y \in \operatorname{dom}\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)$.

Therefore, it holds that:
(D) $\rho_{d} \theta_{d}=\theta_{d}$ by 1 .
(T) $\sigma_{t}^{\prime} \theta_{t}=\theta_{t}$ and $\hat{\sigma}_{t} \sigma_{t}^{\prime}=\sigma_{t}^{\prime}$ by 4 .
(E) Since the variables of $\left\{\bar{V}_{m}:: \bar{\tau}_{m}\right\}$ are fresh, $\operatorname{dom}\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)=$ $\left\{\bar{V}_{m}\right\} \uplus \operatorname{dom}(T)$. Moreover, (T) implies that $\hat{T} \sigma_{t}^{\prime}=T \sigma_{t}^{\prime}, \hat{T} \sigma_{t}^{\prime} \theta_{t}=T \theta_{t}$ and $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \theta_{t}=\left\{\bar{V}_{m}:: \bar{\tau}_{m} \theta_{t}\right\} \uplus T \theta_{t}$.

Now we prove that $\left(\left\{\bar{V}_{m}:: \bar{\tau}_{m} \theta_{t}\right\} \cup R, \theta\right) \in \operatorname{WTSol}(G)$ :

- $\theta_{d} \in \operatorname{Sol}\left(S_{d}\right)$, by 1 and (D).
- $\operatorname{dom}\left(\left\{\bar{V}_{m}:: \bar{\tau}_{m} \theta_{t}\right\} \cup R\right) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T)$, by $(\mathbf{E})$ and 2 .
- $\mathcal{P} \vdash_{G O R C}\left(P\right.$ व $\left.X \bar{a}_{k} \asymp h \bar{e}_{m} \bar{b}_{k}, C\right) \theta_{d}$ : By 3 and (D), for $i \in\{1, \ldots, k\}$ $\mathcal{P} \vdash_{G O R C}\left(a_{i} \asymp b_{i}\right) \theta_{d}$; for $j \in\{1, \ldots, m\} \mathcal{P} \vdash_{G O R C}\left(V_{j} \asymp e_{j}\right) \theta_{d}$, then $\mathcal{P} \vdash_{G O R C}\left(h \bar{V}_{m} \bar{a}_{k} \asymp h \bar{e}_{m} \bar{b}_{k}\right) \theta_{d}$. Since $X \theta_{d}=X \rho_{d} \theta_{d}=\left(h \bar{V}_{m}\right) \theta_{d}$, we obtain that $\mathcal{P} \vdash_{G O R C}\left(X \bar{a}_{k} \asymp h \bar{e}_{m} \bar{b}_{k}\right) \theta_{d}$.
- $\theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$, because 4 implies $\operatorname{TSol}\left(S_{t}^{\prime}\right) \subseteq \operatorname{TSol}\left(\hat{S}_{t}\right) \subseteq \operatorname{TSol}\left(S_{t}\right)$.
- $\left(T \theta_{t} \cup\left\{\bar{V}_{m}:: \bar{\tau}_{m} \theta_{t}\right\} \cup R\right) \vdash_{W T} Y \theta_{d}:: T(Y) \theta_{t}$ for all $Y \in \operatorname{dom}(T) \subseteq$ $\operatorname{dom}\left(\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}\right)$, by (E) and 5 .
(b) To obtain that $G^{\prime}$ is also well-typed, we only need to prove:
[1] $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(X \approx h \bar{V}_{m}\right)::$ bool: Because of $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right)$ $\vdash_{W T} X:: \tau^{\prime},\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \vdash_{W T} h \bar{V}_{m}:: \tau$ and Lemma $4,\left(\bar{V}_{m}::\right.$ $\left.\bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} X:: \tau^{\prime} \sigma_{t}^{\prime}$ and $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} h \bar{V}_{m}:: \tau \sigma_{t}^{\prime}$. Moreover, $\tau \sigma_{t}^{\prime}=\tau^{\prime} \sigma_{t}^{\prime}$ by 4 .
[2] $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(P, C, S_{d}\right) \rho_{d}::$ bool: Analogous to [2] of rule (BD).
[3] For $i \in\{1, \ldots, k\}\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(a_{i} \asymp b_{i}\right) \rho_{d}::$ bool and for $j \in\{1, \ldots, m\}\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash{ }_{W T}\left(V_{j} \asymp e_{j}\right) \rho_{d}::$ bool: Since $G$ is well-typed, $\hat{T} \vdash_{W T}\left(X \bar{a}_{k} \asymp h \bar{e}_{m} \bar{b}_{k}\right)::$ bool. Thanks to [1], we can apply Lemma 3 with $T_{0}=\hat{T}, T_{1}=\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime}, \sigma_{t}=\sigma_{t}^{\prime}, \sigma_{d}=\rho_{d}$ and we obtain $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(X \bar{a}_{k} \asymp h \bar{e}_{m} \bar{b}_{k}\right) \rho_{d}::$ bool, which can be rewritten as $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(h \bar{V}_{m} \bar{a}_{k} \asymp h \bar{e}_{m} \bar{b}_{k}\right) \rho_{d}::$ bool. Since we are assuming a transparent step, $h$ must be ( $m+k$ )-transparent. Then, we can apply Lemma 7 to obtain types $\mu_{i}, i \in\{1, \ldots, k\}$ and $\nu_{j}, j \in\{1, \ldots, m\}$ such that $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} a_{i} \rho_{d}:: \mu_{i}:: b_{i} \rho_{d}$ and $\left(\bar{V}_{m}:: \bar{\tau}_{m}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} V_{j} \rho_{d}:: \nu_{j}:: e_{j} \rho_{d}$. Moreover, $V_{j} \rho_{d}=V_{j}$, for all $j \in\{1, \ldots, m\}$.
(NR1) (a) Because of $(R, \theta) \in W \operatorname{TSol}\left(G^{\prime}\right)$ we know:

1. $\theta_{d} \in \operatorname{Sol}\left(S_{d}\right)$.
2. $\operatorname{dom}(R) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}\left(T \cup T^{\prime}\right)$ and $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}\right) \in_{\text {var }} \mathcal{P}$.
3. $\mathcal{P} \vdash_{G O R C}\left(\bar{e}_{n} \rightarrow \bar{t}_{n}, P \square C^{\prime}, r \bar{a}_{k} \asymp b, C\right) \theta_{d}$.
4. $\theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$.
5. $\left(\left(T \cup T^{\prime}\right) \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}::\left(T \cup T^{\prime}\right)(Y) \theta_{t}$ must hold, for all $Y \in$ $\operatorname{dom}\left(T \cup T^{\prime}\right)$.

Since all the variables in $T^{\prime}$ are fresh, it holds that:
(E) $T \cup T^{\prime}=T \uplus T^{\prime}$ and $\left(T \cup T^{\prime}\right) \theta_{t}=\left(T \theta_{t} \uplus T^{\prime} \theta_{t}\right)$.

Now we prove that $\left(T^{\prime} \theta_{t} \cup R, \theta\right) \in W T S o l(G)$. Since $S_{t}$ and $S_{d}$ are not modified, we only need to prove that:

- $\operatorname{dom}\left(T^{\prime} \theta_{t} \cup R\right) \subseteq\left(\operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T)\right)$, by $(\mathbf{E})$ and 2 .
- $\left(T \theta_{t} \cup T^{\prime} \theta_{t} \cup R\right)=\left(\left(T \cup T^{\prime}\right) \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}:: T(Y) \theta_{t}$ for all $Y \in$ $\operatorname{dom}(T) \subseteq \operatorname{dom}\left(T \cup T^{\prime}\right)$, by $(\mathbf{E})$ and 5 .
- $\mathcal{P} \vdash_{G O R C}\left(P\right.$ ם $\left.f \bar{e}_{n} \bar{a}_{k} \asymp b, C\right) \theta_{d} . \mathcal{P} \vdash_{G O R C} P \theta_{d}$ and $\mathcal{P} \vdash_{G O R C} C \theta_{d}$ are obvious by 3 . Moreover, 3 also implies that (a): $\mathcal{P} \vdash_{G O R C}\left(e_{i} \rightarrow t_{i}\right) \theta_{d}$, (b): $\mathcal{P} \vdash_{G O R C} C^{\prime} \theta_{d}$ and (c): $\mathcal{P} \vdash_{G O R C}\left(r \bar{a}_{k} \asymp b\right) \theta_{d} \Longleftrightarrow$ There exists a total pattern $t$ such that (d): $\mathcal{P} \vdash_{G O R C}\left(r \bar{a}_{k}\right) \theta_{d} \rightarrow t$ and (e): $\mathcal{P} \vdash_{G O R C}$ $b \theta_{d} \rightarrow t$. With (a), (b) and (d) we obtain that $\mathcal{P} \vdash_{G O R C}\left(f \bar{e}_{n} \bar{a}_{k}\right) \theta_{d} \rightarrow t$, this fact and (e) implies that $\mathcal{P} \vdash{ }_{G O R C}\left(f \bar{e}_{n} \bar{a}_{k} \asymp b\right) \theta_{d}$.
(b) $\left(f \bar{t}_{n} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}\right) \in_{\text {var }} \mathcal{P}$ implies that $T^{\prime} \vdash_{W T} t_{i}:: \tau_{i}$, for $i \in$ $\{1, \ldots, n\}, T^{\prime} \vdash_{W T} r:: \tau, T^{\prime} \vdash_{W T} C^{\prime}::$ bool and $T^{\prime} \vdash_{W T} f:: \bar{\tau}_{n} \rightarrow \tau$. To prove that $G^{\prime}$ is also well-typed, we apply Lemma 13(b), finding $\lambda_{t} \in T S u b$ such that $\left(T^{\prime} \lambda_{t}, \hat{T}\right) \vdash_{W T} G^{\prime}$.
[1] Independently of the choice of $\lambda_{t},\left(T^{\prime} \lambda_{t}, \hat{T}\right) \vdash_{W T}\left(P, C, C^{\prime}, S_{d}\right)::$ bool follows from Lemma 4, because $G$ and ( $f \bar{t}_{n} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}$ ) are well-typed.
[2] We still have to deal with the rest of $G^{\prime}$, namely $e_{i} \rightarrow t_{i}$, for $i \in$ $\{1, \ldots, n\}$ and $r \bar{a}_{k} \asymp b$. Because $\hat{T} \vdash_{W T} G$, we know that $\hat{T} \vdash_{W T}$ $\left(f \bar{e}_{n} \bar{a}_{k} \asymp b\right)::$ bool, and there must exist types $\nu_{i}, \mu_{j}, \mu$ such that $\hat{T} \vdash_{W T} e_{i}:: \nu_{i}$, for $i \in\{1, \ldots, n\}, \hat{T} \vdash_{W T} a_{j}:: \mu_{j}$, for $j \in\{1, \ldots, k\}$, $\hat{T} \vdash_{W T} b:: \mu$ and $\left(\bar{\nu}_{n} \rightarrow \bar{\mu}_{k} \rightarrow \mu\right) \geq \bar{\tau}_{n} \rightarrow \tau$. We choose $\lambda_{t} \in$ TSub such that $\left(\bar{\tau}_{n} \rightarrow \tau\right) \lambda_{t}=\left(\bar{\nu}_{n} \rightarrow \bar{\mu}_{k} \rightarrow \mu\right)$. Therefore, $\nu_{i}=\tau_{i} \lambda_{t}$, for $i \in$ $\{1, \ldots, n\}$, and $\tau \lambda_{t}=\left(\bar{\mu}_{k} \rightarrow \mu\right)$. Due to Lemma 4, $\left(T^{\prime} \lambda_{t}, \hat{T}\right) \vdash_{W T} t_{i}::$ $\tau_{i} \lambda_{t}=\nu_{i}$, and hence $\left(T^{\prime} \lambda_{t}, \hat{T}\right) \vdash{ }_{W T}\left(e_{i} \rightarrow t_{i}\right)::$ bool, for $i \in\{1, \ldots, n\}$. Also because of Lemma 4, $\left(T^{\prime} \lambda_{t}, \hat{T}\right) \vdash_{W T} r:: \tau \lambda_{t}=\left(\bar{\mu}_{k} \rightarrow \mu\right)$, which implies $\left(T^{\prime} \lambda_{t}, \hat{T}\right) \vdash_{W T} r \bar{a}_{k}:: \mu:: b$ and hence $\left(T^{\prime} \lambda_{t}, \hat{T}\right) \vdash_{W T}\left(r \bar{a}_{k} \asymp b\right)::$ bool.
(GN) (a) Because of $(R, \theta) \in W \operatorname{TSol}\left(G^{\prime}\right)$ we know:

1. $\theta_{d} \in \operatorname{Sol}\left(S_{d} \rho_{d}, X \approx f \bar{t}_{p}\right)$, with $\rho_{d}=\left\{X \mapsto f \bar{t}_{p}\right\}$.
2. $\operatorname{dom}(R) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}\left(\left(\hat{T} \cup T^{\prime}\right) \sigma_{t}^{\prime}\right)$ and $\left(f \bar{t}_{p} \bar{s}_{q} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}\right) \in_{v a r}$ $\mathcal{P}$.
3. $\mathcal{P} \vdash_{G O R C}\left(\bar{e}_{q} \rightarrow \bar{s}_{q}, P \square C^{\prime}, r \bar{a}_{k} \asymp b, C\right) \rho_{d} \theta_{d}$.
4. $\theta_{t} \in \operatorname{TSol}\left(\underline{S}_{t}^{\prime}\right)$ with $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau^{\prime} \approx \bar{\tau}_{q} \rightarrow \tau\right)$ where $\tau^{\prime}=\hat{T}(X)$ and $\left(f:: \bar{\tau}_{p} \rightarrow \bar{\lambda}_{q} \rightarrow \tau\right) \in_{\text {var }} \Sigma$.
5. $\left(\left(\hat{T} \cup T^{\prime}\right) \sigma_{t}^{\prime} \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}::\left(\hat{T} \cup T^{\prime}\right)(Y) \sigma_{t}^{\prime} \theta_{t}$ must hold, for all $Y \in \operatorname{dom}\left(\left(\hat{T} \cup T^{\prime}\right) \sigma_{t}^{\prime}\right)$.

Therefore, it holds that:
(D) $\rho_{d} \theta_{d}=\theta_{d}$ by 1 .
(T) $\sigma_{t}^{\prime} \theta_{t}=\theta_{t}$ and $\hat{\sigma}_{t} \sigma_{t}^{\prime}=\sigma_{t}^{\prime}$ by 4 .
(E) Since all the variables in $T^{\prime}$ are fresh, $\hat{T} \cup T^{\prime}=T \uplus T^{\prime}$. Moreover, (T) implies that $\left(\hat{T} \cup T^{\prime}\right) \sigma_{t}^{\prime}=\left(T \cup T^{\prime}\right) \sigma_{t}^{\prime}$ and $\left(\hat{T} \cup T^{\prime}\right) \sigma_{t}^{\prime} \theta_{t}=\left(T \theta_{t} \cup T^{\prime} \theta_{t}\right)$.

Now we prove that $\left(T^{\prime} \theta_{t} \cup R, \theta\right) \in W T S o l(G)$ :

- $\theta_{d} \in \operatorname{Sol}\left(S_{d}\right)$, by 1 and (D).
- $\operatorname{dom}\left(T^{\prime} \theta_{t} \cup R\right) \subseteq\left(\operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T)\right)$, by $(\mathbf{E})$ and 2 .
- $\mathcal{P} \vdash_{G O R C}\left(P \square X \bar{e}_{q} \bar{a}_{k} \asymp b, C\right) \theta_{d}:$ By 3 and (D), we have (a): $\mathcal{P} \vdash_{G O R C}$ $C^{\prime} \theta_{d}$, (b): $\mathcal{P} \vdash_{G O R C}\left(e_{j} \rightarrow s_{j}\right) \theta_{d}$, for $j \in\{1, \ldots, q\}$, and (c): $\mathcal{P} \vdash_{G O R C}$ $\left(r \bar{a}_{k} \asymp b\right) \theta_{d} \Longleftrightarrow$ There exists a total pattern $t$ such that (d): $\mathcal{P} \vdash_{G O R C}$ $\left(r \bar{a}_{k}\right) \theta_{d} \rightarrow t$ and (e): $\mathcal{P} \vdash_{G O R C} b \theta_{d} \rightarrow t$. By (a), (b), (d) and $X \theta_{d}=$ $X \rho_{d} \theta_{d}=\left(f \bar{t}_{p}\right) \theta_{d}$, we have that $\mathcal{P} \vdash_{G O R C}\left(X \bar{e}_{q} \bar{a}_{k}\right) \theta_{d} \rightarrow t$. Therefore, by (e) we conclude that $\mathcal{P} \vdash_{G O R C}\left(X \bar{e}_{q} \bar{a}_{k} \asymp b\right) \theta_{d}$.
- $\theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$, because 4 implies $\operatorname{TSol}\left(S_{t}^{\prime}\right) \subseteq \operatorname{TSol}\left(\hat{S}_{t}\right) \subseteq \operatorname{TSol}\left(S_{t}\right)$.
- $\left(T \theta_{t} \cup T^{\prime} \theta_{t} \cup R\right) \vdash_{W T} Y \theta_{d}:: T(Y) \theta_{t}$ for all $Y \in \operatorname{dom}(T) \subseteq \operatorname{dom}\left(\hat{T} \cup T^{\prime}\right)$, because (E) and 5 .
(b) Since $\left(f \bar{t}_{p} \bar{s}_{q} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}\right) \in_{\text {var }} \mathcal{P}$ is a fresh variant of a well-typed f-rule and $\left(f:: \bar{\tau}_{p} \rightarrow \bar{\lambda}_{q} \rightarrow \tau\right) \in_{v a r} \Sigma$, we have that for $l \in\{1, \ldots, p\}$ : $T^{\prime} \vdash_{W T} t_{l}:: \tau_{l}$; for $j \in\{1, \ldots, q\}: T^{\prime} \vdash_{W T} s_{j}:: \lambda_{j} ; T^{\prime} \vdash_{W T} r:: \tau$ and $T^{\prime} \vdash_{W T} C^{\prime}::$ bool. To obtain that $G^{\prime}$ is also well-typed, we need to prove:
[1] $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(X \approx f \bar{t}_{p}\right)::$ bool: Because of $\hat{T} \vdash_{W T} X:: \tau^{\prime}$ and $T^{\prime}$ $\vdash_{W T} f \bar{t}_{p}::\left(\bar{\lambda}_{q} \rightarrow \tau\right)$ and Lemma 4, $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} X:: \tau^{\prime} \sigma_{t}^{\prime}$ and $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} f \bar{t}_{p}::\left(\bar{\lambda}_{q} \rightarrow \tau\right) \sigma_{t}^{\prime}$. Moreover, $\tau^{\prime} \sigma_{t}^{\prime}=\left(\bar{\lambda}_{q} \rightarrow \tau\right) \sigma_{t}^{\prime}$ by 4.
[2] $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(P, C^{\prime}, C, S_{d}\right) \rho_{d}::$ bool: This follows by Lemma 3 from $\left(T^{\prime}, \hat{T}\right) \vdash_{W T}\left(P, C, C^{\prime}, S_{d}\right)::$ bool, which can be applied because of [1].
[3] Because $\hat{T} \vdash_{W T} G$, we know that $\hat{T} \vdash_{W T}\left(X \bar{e}_{q} \bar{a}_{k} \asymp b\right)::$ bool, and there must exist types $\nu_{i}, \mu_{j}, \mu$ such that $\hat{T} \vdash_{W T} e_{i}:: \nu_{i}$, for $i \in$ $\{1, \ldots, q\}, \hat{T} \vdash_{W T} a_{j}:: \mu_{j}$, for $j \in\{1, \ldots, k\}, \hat{T} \vdash_{W T} b:: \mu$ and $\left(\bar{\nu}_{q} \rightarrow \bar{\mu}_{k} \rightarrow \mu\right)=\hat{T}(X)=\tau^{\prime}$. By 4, $\tau^{\prime} \sigma_{t}^{\prime}=\left(\bar{\lambda}_{q} \rightarrow \tau\right) \sigma_{t}^{\prime}$, i.e., $\left(\bar{\nu}_{q} \rightarrow\right.$ $\left.\bar{\mu}_{k} \rightarrow \mu\right) \sigma_{t}^{\prime}=\left(\bar{\lambda}_{q} \rightarrow \tau\right) \sigma_{t}^{\prime}$. Therefore, $\nu_{i} \sigma_{t}^{\prime}=\lambda_{i} \sigma_{t}^{\prime}$, for $i \in\{1, \ldots, q\}$, and $\tau \sigma_{t}^{\prime}=\left(\bar{\mu}_{k} \rightarrow \mu\right) \sigma_{t}^{\prime}$. Using Lemma 3 (which can be applied thanks to [1]) we get $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} e_{i} \rho_{d}:: \nu_{i} \sigma_{t}^{\prime},\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} s_{i} \rho_{d}:: \lambda_{i} \sigma_{t}^{\prime}$ for $i \in\{1, \ldots, q\}$. Since $\nu_{i} \sigma_{t}^{\prime}=\lambda_{i} \sigma_{t}^{\prime}$, we obtain $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(e_{i} \rightarrow s_{i}\right) \rho_{d}::$ bool. Applying again Lemma 3, we get now $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} a_{j} \rho_{d}:: \mu_{j} \sigma_{t}^{\prime}$, $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} b \rho_{d}:: \mu \sigma_{t}^{\prime}$ and $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T} r \rho_{d}:: \tau \sigma_{t}^{\prime}=\left(\bar{\mu}_{k} \rightarrow \mu\right) \sigma_{t}^{\prime}$. Hence $\left(T^{\prime}, \hat{T}\right) \sigma_{t}^{\prime} \vdash_{W T}\left(r \bar{a}_{k} \asymp b\right) \rho_{d}::$ bool.
(GD) (a) Because of $(R, \theta) \in W T S o l\left(G^{\prime}\right)$ we know:

1. $\theta_{d} \in \operatorname{Sol}\left(S_{d} \rho_{d}, X \approx h \bar{V}_{m-p}, Y \approx h \bar{W}_{m-q}\right)$ where $\rho_{d}=\left\{X \mapsto h \bar{V}_{m-p}\right.$, $\left.Y \mapsto h \bar{W}_{m-q}\right\}$.
2. $\operatorname{dom}(R) \subseteq \operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}\left(\left(\left\{\bar{V}_{m-p}::{\overline{\tau^{\prime}}}_{m-p}\right\} \cup\left\{\bar{W}_{m-q}::{\overline{\tau^{\prime \prime}}}_{m-q}\right\} \cup \hat{T}\right) \sigma_{t}^{\prime}\right)$.
3. $\mathcal{P} \vdash_{G O R C}\left(P \square \bar{V}_{m-p} \bar{a}_{p} \asymp \bar{W}_{m-q} \bar{b}_{q}, C\right) \rho_{d} \theta_{d}$.
4. $\theta_{t} \in \operatorname{TSol}\left(S_{t}^{\prime}\right)$ with $\sigma_{t}^{\prime}=\operatorname{mgu}\left(\hat{S}_{t}, \tau^{\prime} \approx{\overline{\lambda^{\prime}}}_{p} \rightarrow \tau_{0}^{\prime}, \tau^{\prime \prime} \approx \overline{\lambda^{\prime \prime}}{ }_{q} \rightarrow \tau_{0}^{\prime \prime}\right)$, where $\tau^{\prime}=T(X), \tau^{\prime \prime}=T(Y),\left(h:: \overline{\tau^{\prime}}{ }_{m-p} \rightarrow \overline{\lambda^{\prime}} p \rightarrow \tau_{0}^{\prime}\right) \in_{\text {var }} \Sigma$ and $\left(h::{\overline{\tau^{\prime \prime}}}_{m-q} \rightarrow{\overline{\lambda^{\prime \prime}}}_{q} \rightarrow \tau_{0}^{\prime \prime}\right) \in_{\text {var }} \Sigma$.
5. $\left(T_{1} \sigma_{t}^{\prime} \theta_{t} \cup R\right) \vdash_{W T} Z \theta_{d}:: T_{1}(Z) \sigma_{t}^{\prime} \theta_{t}$ must hold, for all $Z \in \operatorname{dom}\left(T_{1} \sigma_{t}^{\prime}\right)$, where $T_{1}:=\left\{\bar{V}_{m-p}::{\overline{\tau^{\prime}}}_{m-p}\right\} \cup\left\{\bar{W}_{m-q}::{\overline{\tau^{\prime \prime}}}_{m-q}\right\} \cup \hat{T}$.

Therefore, it holds that:
(D) $\rho_{d} \theta_{d}=\theta_{d}$ by 1 .
(T) $\sigma_{t}^{\prime} \theta_{t}=\theta_{t}$ and $\hat{\sigma}_{t} \sigma_{t}^{\prime}=\sigma_{t}^{\prime}$ by 4 .
(E) Since the variables of $\left\{\bar{V}_{m-p}::{\overline{\tau^{\prime}}}_{m-p}\right\} \cup\left\{\bar{W}_{m-q}:: \overline{\tau^{\prime \prime}}{ }_{m-q}\right\}$ are fresh, $\operatorname{dom}\left(T_{1}\right)=\left\{\bar{V}_{m-p}\right\} \uplus\left\{\bar{W}_{m-q}\right\} \uplus \operatorname{dom}(T)$. Moreover, by $(\mathbf{T}), T_{1} \theta_{t}=$ $\left\{\bar{V}_{m-p}::{\overline{\tau^{\prime}}}_{m-p} \theta_{t}\right\} \uplus\left\{\bar{W}_{m-q}::{\overline{\tau^{\prime \prime}}}_{m-q} \theta_{t}\right\} \uplus T \theta_{t}$ and $\hat{T} \sigma_{t}^{\prime}=T \sigma_{t}^{\prime}$.

We prove that $\left(\left\{\bar{V}_{m-p}::{\overline{\tau^{\prime}}}_{m-p} \theta_{t}\right\} \cup\left\{\bar{W}_{m-q}::{\overline{\tau^{\prime \prime}}}_{m-q} \theta_{t}\right\} \cup R, \theta\right) \in \operatorname{WTSol}(G)$ :

- $\theta_{d} \in \operatorname{Sol}\left(S_{d}\right)$, by 1 and (D).
- $\operatorname{dom}\left(\left\{\bar{V}_{m-p}::{\overline{\tau^{\prime}}}_{m-p} \theta_{t}\right\} \cup\left\{\bar{W}_{m-q}::{\overline{\tau^{\prime \prime}}}_{m-q} \theta_{t}\right\} \cup R\right) \subseteq\left(\operatorname{ran}\left(\theta_{d}\right) \backslash \operatorname{dom}(T)\right)$, by (E) and 2 .
- $\mathcal{P} \vdash_{G O R C}\left(P\right.$ ם $\left.X \bar{a}_{p} \asymp Y \bar{b}_{q}, C\right) \theta_{d}: \mathcal{P} \vdash_{G O R C}\left(h \bar{V}_{m-p} \bar{a}_{p} \asymp h \bar{W}_{m-q} \bar{b}_{q}\right) \theta_{d}$ because of 3 and (D), but $X \theta_{d}=X \rho_{d} \theta_{d}=\left(h \bar{V}_{m-p}\right) \theta_{d}$ and $Y \theta_{d}=$ $Y \rho_{d} \theta_{d}=\left(h \bar{W}_{m-q}\right) \theta_{d}$, therefore $\mathcal{P} \vdash_{G O R C}\left(X \bar{a}_{p} \asymp Y \bar{b}_{q}\right) \theta_{d}$.
- $\theta_{t} \in \operatorname{TSol}\left(S_{t}\right)$, because 4 implies $\operatorname{TSol}\left(S_{t}^{\prime}\right) \subseteq \operatorname{TSol}\left(\hat{S}_{t}\right) \subseteq \operatorname{TSol}\left(S_{t}\right)$.
- Since $\left(T \theta_{t} \cup\left\{\bar{V}_{m-p}::{\overline{\tau^{\prime}}}_{m-p} \theta_{t}\right\} \cup\left\{\bar{W}_{m-q}::{\overline{\tau^{\prime \prime}}}_{m-q} \theta_{t}\right\} \cup R\right)=\left(T_{1} \theta_{t} \cup R\right)$, then $\left(T_{1} \theta_{t} \cup R\right) \vdash_{W T} Z \theta_{d}:: T(Z) \theta_{t}$ for all $Z \in \operatorname{dom}(T) \subseteq \operatorname{dom}(T 1)$, because of (E) and 5 .
(b) Let us assume $p \geq q$; the case $p \leq q$ is symmetrical. To show that $G^{\prime}$ is well-typed, we prove [1], [2], [3] and [4].
[1] $T_{1} \sigma_{t}^{\prime} \vdash_{W T}\left(X \approx h \bar{V}_{m-p}\right)::$ bool: Using $T_{1} \vdash_{W T} h \bar{V}_{m-p}::\left(\overline{\lambda_{p}^{\prime}} \rightarrow \tau_{0}^{\prime}\right)$, $T_{1} \vdash_{W T} X:: \tau^{\prime}$ and Lemma 4, we obtain $T_{1} \sigma_{t}^{\prime} \vdash_{W T} X:: \tau^{\prime} \sigma_{t}^{\prime}$ and $T_{1} \sigma_{t}^{\prime} \vdash_{W T} h \bar{V}_{m-p}::\left(\overline{\lambda_{p}^{\prime}} \rightarrow \tau_{0}^{\prime}\right) \sigma_{t}^{\prime}$. Moreover, $\tau^{\prime} \sigma_{t}^{\prime}=\left(\overline{\lambda_{p}^{\prime}} \rightarrow \tau_{0}^{\prime}\right) \sigma_{t}^{\prime}$ by 4.
[2] $T_{1} \sigma_{t}^{\prime} \vdash_{W T}\left(Y \approx h \bar{W}_{m-q}\right)::$ bool: The proof is similar to [1], using the facts $T_{1} \sigma_{t}^{\prime} \vdash_{W T} Y:: \tau^{\prime \prime} \sigma_{t}^{\prime}$ and $T_{1} \sigma_{t}^{\prime} \vdash_{W T} h \bar{W}_{m-q}::\left({\overline{\lambda^{\prime \prime}}}_{q} \rightarrow \tau_{0}^{\prime \prime}\right) \sigma_{t}^{\prime}$ and $\tau^{\prime \prime} \sigma_{t}^{\prime}=\left(\overline{\lambda^{\prime \prime}}{ }_{q} \rightarrow \tau_{0}^{\prime \prime}\right) \sigma_{t}^{\prime}$.
[3] $T_{1} \sigma_{t}^{\prime} \vdash_{W T}\left(P, C, S_{d}\right) \rho_{d}::$ bool: This follows from $T_{1} \vdash_{W T}\left(P, C, S_{d}\right)::$ bool, by Lemma 3, which can be applied because of [1], [2].
[4] $T_{1} \sigma_{t}^{\prime} \vdash{ }_{W T}\left(\bar{V}_{m-p} \bar{a}_{p} \asymp \bar{W}_{m-q} \bar{b}_{q}\right) \rho_{d}::$ bool: We show this by proving three things:
(a) $T_{1} \sigma_{t}^{\prime} \vdash_{W T}\left(V_{j} \asymp W_{j}\right) \rho_{d}::$ bool, $j \in\{1, \ldots,(m-p)\}$.
(b) $T_{1} \sigma_{t}^{\prime} \vdash_{W T}\left(a_{i} \asymp W_{m-p+i}\right) \rho_{d}::$ bool, $i \in\{1, \ldots,(p-q)\}$.
(c) $T_{1} \sigma_{t}^{\prime} \vdash_{W T}\left(a_{p-q+k} \asymp b_{k}\right) \rho_{d}::$ bool, $k \in\{1, \ldots, q\}$.

Proof of (a), (b), (c): Since $G$ is well-typed, $T_{1} \vdash_{W T}\left(X \bar{a}_{p} \asymp Y \bar{b}_{q}\right)::$ bool. Using Lemma 3 (which is applicable because of [1], [2]) we obtain $T_{1} \sigma_{t}^{\prime} \vdash_{W T}\left(X \bar{a}_{p} \asymp Y \bar{b}_{q}\right) \rho_{d}::$ bool, which can be rewritten as $T_{1} \sigma_{t}^{\prime} \vdash_{W T}$
$\left(h \bar{V}_{m-p} \bar{a}_{p} \asymp h \bar{W}_{m-q} \bar{b}_{q}\right) \rho_{d}::$ bool. Since we are assuming a transparent CLNC step, $h$ must be $m$-transparent. Then, we can apply Lemma 7 to obtain types $\nu_{j}$, for $j \in\{1, \ldots,(m-p)\}$, $\mu_{i}$, for $i \in\{1, \ldots,(p-q)\}$ and $\lambda_{k}$, for $k \in\{1, \ldots, q\}$ such that $T_{1} \sigma_{t}^{\prime} \vdash_{W T} V_{j} \rho_{d}:: \nu_{j}:: W_{j} \rho_{d}$, $T_{1} \sigma_{t}^{\prime} \vdash_{W T} a_{i} \rho_{d}:: \mu_{i}:: W_{m-p+i} \rho_{d}$ and $T_{1} \sigma_{t}^{\prime} \vdash_{W T} a_{p-q+k} \rho_{d}:: \lambda_{k}:: b_{k} \rho_{d}$.
(CF1), (CY) Analogously to [18], it is easy to prove that $\operatorname{Sol}(G)=\emptyset$ whenever these rules are applicable.

## Rules for the Delayed Part

We prove only the correctness of (EL). For the other rules in this part, the proofs of related rules in the solved part can be easily adapted.
(EL) (a) It is clear that $\left(R, \theta^{\prime}\right) \in W T S o l(G)$, where $\theta_{t}^{\prime}=\theta_{t}, X \theta_{d}^{\prime}=\perp$ and $Y \theta_{d}^{\prime}=Y \theta_{d}$ for all variables $Y \neq X$. Note that $X \theta_{d}^{\prime}=\perp$ is allowed because $X$ is a produced variable in $G$. Being produced, $X$ is also existential, and then $\left(R, \theta^{\prime}\right) \in W T S o l(G)$ implies $(R, \theta) \in_{e x} \operatorname{WTSol}(G)$.
(b) If $G$ is well-typed then $G^{\prime}$ is also well-typed.

Proof of Lemma 17: We organize our reasoning in two stages. First, we use the fact that $\mathcal{M}$ is a witness of $(R, \theta) \in \operatorname{TASol}(\hat{G})$ to find a CLNC rule TR which acts as a candidate to transform $G$ into $G^{\prime}$ as required by the lemma. This part of the proof ignores types and is performed by a case analysis. For each candidate rule TR, the second stage of our reasoning uses the type information present in $\mathcal{M}$ to show that TR can be actually applied to $G$ (which may involve dynamic type checking) and to build a smaller type-annotated $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$ witnessing $\left(R^{\prime}, \theta^{\prime}\right) \in \operatorname{TASol}\left(\hat{G}^{\prime}\right)$, for some suitable $\left(R^{\prime}, \theta^{\prime}\right) \approx_{e x}(R, \theta)$. In each case, $\theta^{\prime}$ and $\mathcal{M}^{\prime}$ must be built explicitly, but the construction of $R^{\prime}$ and the reasoning which proves $G^{\prime}$ well-typed can be left implicit. This is because the type annotation within $\mathcal{M}^{\prime}$ implies welltypedness of $G^{\prime}$, and $R^{\prime}$ can be defined as the set of all type assumptions $X:: \tau$ such that $X^{\tau}$ occurs in $\mathcal{M}^{\prime}$, but $X \notin \operatorname{dom}\left(\hat{\mathrm{~T}}^{\prime} \theta_{t}^{\prime} \cup R\right)$.

In what follows, items 1, 2, etc. enumerate the cases in our main case distinction. Subcases are indicated by a similar notation, as 1.2, 1.2.1, etc. When performing the second stages of our reasoning for each particular CLNC rule TR, we will assume that $G$ and $G^{\prime}$ are written with exactly the same notation used in the presentation of CLNC in Subsection 4.2. In several
cases, we will leave out proof details which are easy to complete, or similar to the reasonings already performed for some other cases.

Let us now start our case analysis. By the One-step Soundness Lemma 16, we can ignore the failure rules, because $G$ is solvable. Moreover, we can assume that the $(P \square C)$ part of $G$ is nor empty, because $G$ is not solved.
1 Assume that $G$ satisfies the condition:
There is some $(a \asymp b) \in C$ such that neither $a$ nor $b$ are headed by a produced variable.

Choose one such $a \asymp b$ and continue the case analysis as follows:
1.1 $a, b$ are both rigid and passive expressions. In this case TR is DC1, $a=h \bar{a}_{m}, b=h \bar{b}_{m}$. The principal type annotation of $\hat{G}$ must include $h^{\bar{\tau}_{m} \rightarrow \tau} \bar{a}_{m}^{\bar{\tau}_{m}} \asymp h^{\overline{\tau^{\prime}} m \rightarrow \tau} \bar{b}_{m}^{\overline{\tau_{m}} m}$. The witness $\mathcal{M}$ must include a type-annotated GORC-proof

$$
\begin{aligned}
\Pi_{0}= & \left(\Pi \leadsto h^{\left(\bar{\tau}_{m} \rightarrow \tau\right) \theta_{t}} \bar{a}_{m} \theta_{d}^{\bar{\tau}_{m} \theta_{t}} \rightarrow t^{\tau^{\prime \prime}} \&\right. \\
& \left.\Pi^{\prime} \leadsto h^{\left(\overline{\tau_{m}^{\prime}} \rightarrow \tau\right) \theta_{t}} \bar{b}_{m} \theta_{d}^{\bar{\tau}^{\prime}} \theta_{t} \rightarrow t^{\tau^{\prime \prime}}\right)+(\mathbf{J N})
\end{aligned}
$$

where

- $t^{\tau^{\prime \prime}}=h^{\overline{\tau^{\prime \prime}}{ }_{m} \rightarrow \tau^{\prime \prime}} \overline{t_{m}^{\overline{\prime^{\prime \prime}}}{ }_{m}}$
- ${\overline{\tau^{\prime \prime}}}_{m} \rightarrow \tau^{\prime \prime}=\left(\bar{\tau}_{m} \rightarrow \tau\right) \theta_{t}=\left({\overline{\tau^{\prime}}}_{m} \rightarrow \tau\right) \theta_{t}$
- $\Pi=\left(\ldots \& \Pi_{i} \leadsto a_{i} \theta_{d}^{\tau_{i} \theta_{t}} \rightarrow t_{i}^{\tau_{i}^{\prime \prime}} \& \ldots\right)+(\mathbf{D C})$
- $\Pi^{\prime}=\left(\ldots \& \Pi_{i}^{\prime} \leadsto b_{i} \theta_{d}^{\tau_{i}^{\prime} \theta_{t}} \rightarrow t_{i}^{\tau_{i}^{\prime \prime}} \& \ldots\right)+(\mathbf{D C})$

Clearly, DC1 can be applied to $G$. Moreover, considering the type-annotated GORC-proofs $\Pi_{i}^{\prime \prime}=\left(\Pi_{i} \& \Pi_{i}^{\prime}\right)+(\mathbf{J N}) \leadsto a_{i} \theta_{d}^{\tau_{i}^{\prime \prime}} \asymp b_{i} \theta_{d}^{\tau_{i}^{\prime \prime}}(1 \leq i \leq m)$ and $\mathcal{M}^{\prime}=_{\text {def }}\left(\mathcal{M} \backslash\left\{\left\{\Pi_{0}\right\}\right\}\right) \uplus\left\{\left\{\Pi_{1}^{\prime \prime}, \ldots, \Pi_{m}^{\prime \prime}\right\}\right\}$, we see that $\left(R^{\prime}, \theta\right) \in \operatorname{TASol}\left(\hat{G}^{\prime}\right)$ with type-annotated witness $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$.
$1.2 a$ is a flexible expression, while $b$ is a rigid and passive expression. Due to $\mathbf{I}$, the variable $X$ occurring as the head of $a$ is not produced. Moreover, $X \theta_{d}$ must be a rigid pattern. We distinguish three different subcases:
1.2.1 $a=X \bar{a}_{k}, a \theta_{d}=h \bar{t}_{m} \bar{a}_{k} \theta_{d}$ is rigid and passive, $b=h \bar{s}_{m} \bar{b}_{k}$, and $s=h \bar{s}_{m}$ is a pattern. In this case TR is BD. The principal type annotation
of $\hat{G}$ must include $X^{\bar{\nu}_{k} \rightarrow \nu} \bar{a}_{k}^{\bar{\nu}_{k}} \asymp\left(h^{\overline{\mu^{\prime}}{ }_{m} \rightarrow \bar{\nu}_{k} \rightarrow \nu} \overline{\bar{s}_{m}^{\mu_{m}}}\right)^{\overline{\nu^{\prime}}{ }_{k} \rightarrow \nu} \bar{b}_{k}^{\overline{\nu^{\prime}} k}$. The witness $\mathcal{M}$ must include a type-annotated GORC-proof

$$
\begin{aligned}
\Pi_{0}= & \left(\Pi \leadsto X \theta_{d}^{\left(\bar{\nu}_{k} \rightarrow \nu\right) \theta_{t}} \bar{a}_{k} \theta_{d}^{\bar{\nu}_{k} \theta_{t}} \rightarrow t^{\nu^{\prime \prime}} \& \Pi^{\prime} \leadsto\right. \\
& \left.\left(h^{\left({\overline{\mu^{\prime}}}_{m} \rightarrow \nu^{\prime}{ }_{k} \rightarrow \nu\right) \theta_{t}} \bar{s}_{m} \theta_{d}^{{\overline{\mu^{\prime}}}_{m} \theta_{t}}\right)^{\left(\overline{\nu^{\prime}}{ }_{k} \rightarrow \nu\right) \theta_{t}} \bar{b}_{k} \theta_{d}^{{\overline{\nu^{\prime}}}_{k} \theta_{t}} \rightarrow t^{\nu^{\prime \prime}}\right)+(\mathbf{J N})
\end{aligned}
$$

where

- $t^{\nu^{\prime \prime}}={h \bar{\mu}^{\mu^{\prime}}{ }_{m} \rightarrow \overline{\nu^{\prime \prime}}{ }_{k} \rightarrow \nu^{\prime \prime} \bar{i}_{m}^{\overline{\mu^{\prime \prime}}}{ }_{m} \overline{u_{k}^{\overline{\nu^{\prime}}}} k}_{k}$
- (a) $\overline{\nu^{\prime \prime}}{ }_{k} \rightarrow \nu^{\prime \prime}=\left(\bar{\nu}_{k} \rightarrow \nu\right) \theta_{t}=\left(\overline{\nu^{\prime}}{ }_{k} \rightarrow \nu\right) \theta_{t}$
- $\Pi=\left(\ldots \& \Pi_{j} \leadsto a_{j} \theta_{d}^{\nu_{j}^{\prime \prime}} \rightarrow u_{j}^{\nu_{j}^{\prime \prime}} \& \ldots\right)+(\mathbf{D C})$
- $\Pi^{\prime}=\left(\ldots \& \Pi_{j}^{\prime} \leadsto b_{j} \theta_{d}^{\nu_{j}^{\prime \prime}} \rightarrow u_{j}^{\nu_{j}^{\prime \prime}} \& \ldots\right)+(\mathbf{D C})$

In particular, (a) shows that $\theta_{t}$ unifies the types attached to $X$ and $s$ in the principal type annotation of $\hat{G}$. Since $\theta_{t}$ is also solution of $\hat{S}_{t}$, the dynamic type checking condition of $\mathbf{B D}$ succeeds and $\mathbf{B D}$ can actually be applied to transform $G$ into $G^{\prime}$. Reasoning as in Lemma 16, $\theta_{t}=\sigma_{t}^{\prime} \theta_{t}$ and $\theta_{d}=\rho_{d} \theta_{d}$. Taking these identities into account, it is clear that $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$ built as indicated below is a type-annotated witness of $\left(R^{\prime}, \theta\right) \in \operatorname{TASol}\left(\hat{G}^{\prime}\right): \mathcal{M}^{\prime}={ }_{\operatorname{def}}(\mathcal{M} \backslash$ $\left.\left\{\left\{\Pi_{0}\right\}\right\}\right) \uplus\left\{\left\{\Pi_{1}^{\prime \prime}, \ldots, \Pi_{k}^{\prime \prime}\right\}\right\}$ where $\Pi_{j}^{\prime \prime}=\left(\Pi_{j} \& \Pi_{j}^{\prime}\right)+(\mathbf{J N}) \leadsto a_{j} \theta_{d}^{\nu_{j}^{\prime \prime}} \asymp b_{j} \theta_{d}^{\nu_{j}^{\prime \prime}}$.
1.2.2 $a=X \bar{a}_{k}, a \theta_{d}=h \bar{t}_{m} \bar{a}_{k} \theta_{d}$ is rigid and passive, $b=h \bar{e}_{m} \bar{b}_{k}$, and $h \bar{e}_{m}$ is not a pattern. In this case TR is IM. The principal type annotation of $\hat{G}$ must include $X^{\bar{\nu}_{k} \rightarrow \nu} \bar{a}_{k}^{\bar{\nu}_{k}} \asymp\left(h^{\bar{\mu}_{m} \rightarrow \bar{\nu}^{\prime}{ }_{k} \rightarrow \nu} \overline{e_{m}^{\mu_{m}^{\prime}}}\right)^{\overline{\nu^{\prime}}{ }_{k} \rightarrow \nu} \overline{b_{k}^{\nu_{k}}}$. The witness $\mathcal{M}$ must include a type-annotated GORC-proof

$$
\begin{aligned}
\Pi_{0}= & \left(\Pi \leadsto h^{\overline{\mu^{\prime \prime}}}{ }_{m} \rightarrow\left(\bar{\nu}_{k} \rightarrow \nu\right) \theta_{t} \overline{\underline{t}}_{m}^{\overline{\mu^{\prime \prime}}} \bar{a}_{k}{\overline{\bar{\nu}_{k}} \theta_{t} \rightarrow t^{\nu^{\prime \prime}} \&}^{\Pi^{\prime}} \sim h^{\left.{\overline{\mu^{\prime}}}_{m} \rightarrow \bar{\nu}_{k}^{\prime} \rightarrow \nu\right) \theta_{t}} \bar{e}_{m} \bar{\theta}_{d}^{\bar{\mu}^{\prime} \theta_{t}} \bar{b}_{k} \theta_{d}^{{\overline{\nu^{\prime}}}_{k} \theta_{t}} \rightarrow t^{\nu^{\prime \prime}}\right)+(\mathbf{J N})
\end{aligned}
$$

where


- (a) ${\overline{\mu^{\prime \prime}}}_{m} \rightarrow{\overline{\nu^{\prime \prime}}}_{k} \rightarrow \nu^{\prime \prime}={\overline{\mu^{\prime \prime}}}_{m} \rightarrow\left(\bar{\nu}_{k} \rightarrow \nu\right) \theta_{t}=\left({\overline{\mu^{\prime}}}_{m} \rightarrow{\overline{\nu^{\prime}}}_{k} \rightarrow \nu\right) \theta_{t}$
- $\Pi=\left(\ldots \& \Delta_{i} \leadsto t_{i}^{\mu_{i}^{\prime \prime}} \rightarrow t_{i}^{\mu_{i}^{\prime \prime}} \ldots \& \ldots \Pi_{j} \leadsto a_{j} \theta_{d}^{\nu_{j}^{\prime \prime}} \rightarrow u_{j}^{\nu_{j}^{\prime \prime}} \& \ldots\right)+(\mathbf{D C})$
- $\Pi^{\prime}=\left(\ldots \& \Delta_{i}^{\prime} \leadsto e_{i} \theta_{d}^{\mu_{i}^{\prime \prime}} \rightarrow t_{i}^{\mu_{i}^{\prime \prime}} \ldots \& \ldots \Pi_{j}^{\prime} \leadsto b_{j} \theta_{d}^{\nu_{j}^{\prime \prime}} \rightarrow u_{j}^{\nu_{j}^{\prime \prime}} \&\right.$ $\ldots)+(\mathbf{D C})$

In particular, the existence of these proofs implies the condition $X \notin$ $\operatorname{svar}\left(h \bar{e}_{m}\right)$ needed for the application of IM. Moreover, the type $\overline{\mu^{\prime}}{ }_{m} \rightarrow$ $\overline{\nu^{\prime}}{ }_{k} \rightarrow \nu$ must be an instance of the type $\bar{\tau}_{m} \rightarrow \tau$ taken as a fresh variant of $h$ 's principal type in the formulation of IM. Therefore, we can choose some $\rho_{t} \in T S u b$ such that (b) $\overline{\mu^{\prime}}{ }_{m} \rightarrow \bar{\nu}^{\prime}{ }_{k} \rightarrow \nu=\left(\bar{\tau}_{m} \rightarrow \tau\right) \rho_{t}$. Consider now the substitution $\theta^{\prime}=\left(\theta_{t}^{\prime}, \theta_{d}^{\prime}\right)$ such that

- $\theta_{t}^{\prime}=\rho_{t}\left[\operatorname{tvar}\left(\bar{\tau}_{m} \rightarrow \tau\right)\right]$ and $\theta_{t}^{\prime}=\theta_{t}\left[\backslash \operatorname{tvar}\left(\bar{\tau}_{m} \rightarrow \tau\right)\right]$.
- $\bar{V}_{m} \theta_{d}^{\prime}=\bar{t}_{m}$ and $\theta_{d}^{\prime}=\theta_{d}\left[\backslash \bar{V}_{m}\right]$.

Note that $\theta^{\prime} \approx_{e x} \theta$. Moreover, (a) and (b) imply that $\theta_{t}^{\prime}$ is a unifier of $\bar{\nu}_{k} \rightarrow \nu$ (i.e. the type $\tau^{\prime}$ of $X$ in $\hat{T}$ ) and $\tau$. Moreover, $\theta_{t}^{\prime}$ is a solution of $\hat{S}_{t}$, because $\theta_{t}^{\prime}=\theta_{t}\left[\operatorname{tvar}\left(\hat{S}_{t}\right)\right]$. Therefore, the dynamic type checking condition of IM succeeds and IM can be used to transform $G$ into $G^{\prime}$. Finally, consider $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$ built as $\mathcal{M}^{\prime}={ }_{\text {def }}\left(\mathcal{M} \backslash\left\{\left\{\Pi_{0}\right\}\right\}\right) \uplus\left\{\left\{\Delta_{1}^{\prime \prime}, \ldots, \Delta_{m}^{\prime \prime}, \Pi_{1}^{\prime \prime}, \ldots, \Pi_{k}^{\prime \prime}\right\}\right\}$ where

- $\Delta_{i}^{\prime \prime}=\left(\Delta_{i} \& \Delta_{i}^{\prime}\right)+(\mathbf{J N}) \leadsto V_{i} \theta_{d}^{\mu_{i}^{\prime \prime}} \asymp e_{i} \theta_{d}^{\mu_{i}^{\prime \prime}}$
- $\Pi_{i}^{\prime \prime}=\left(\Pi_{i} \& \Pi_{i}^{\prime}\right)+(\mathbf{J N}) \leadsto a_{j} \theta_{d}^{\nu_{j}^{\prime \prime}} \asymp b_{j} \theta_{d}^{\nu_{j}^{\prime \prime}}$

Taking into account the construction of $\theta^{\prime}$ it is easy to check that $\mathcal{M}^{\prime}$ is a type-annotated witness of $\left(R^{\prime}, \theta^{\prime}\right) \in \operatorname{TASol}\left(\hat{G}^{\prime}\right)$.
1.2.3 $a \theta_{d}$ is rigid and active. In this case $X \theta_{d}=f{\overline{t^{\prime}}}_{p}$ for some $f \in F S^{n}$ with $p<n$. Taking $q=n-p>0$, we can assume $a=X \bar{e}_{q} \bar{a}_{k}$ and $a \theta_{d}=f \overline{t^{\prime}}{ }_{p} \bar{e}_{q} \theta_{d} \bar{a}_{k} \theta_{d}$. Let us choose $\mathbf{G N}$ as TR. The principal type annotation of $\hat{G}$ must include (a) $X^{\bar{\nu}_{q} \rightarrow \bar{\varepsilon}_{k} \rightarrow \varepsilon} \bar{e}_{q}^{\bar{\nu}_{q}} \bar{a}_{k}^{\bar{\varepsilon}_{k}} \asymp b^{\varepsilon}$. In the formulation of GN, we find $\tau^{\prime}=\hat{T}(X)$ and a fresh variant $f:: \bar{\tau}_{p} \rightarrow \bar{\lambda}_{q} \rightarrow \tau$ of $f$ 's principal type. Therefore, $\tau^{\prime}=\bar{\nu}_{q} \rightarrow \bar{\varepsilon}_{k} \rightarrow \varepsilon$. Moreover, the witness $\mathcal{M}$ must include a type-annotated GORC-proof of (a) using some type-annotated instance of some fresh variant ( $f \bar{t}_{p} \bar{s}_{q} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}$ ) of a rule of $\mathcal{P}$. Let $\omega=\left(\omega_{t}, \omega_{d}\right)$ be the substitution which builds the instance of this rule used in the witness. Then, $\mathcal{M}$ will include the following type-annotated GORC-proof

$$
\begin{aligned}
\Pi_{0}= & \left(\Pi \leadsto f^{\bar{\tau}_{p} \omega_{t} \rightarrow\left(\bar{\nu}_{q} \rightarrow \bar{\varepsilon}_{k} \rightarrow \varepsilon\right) \theta_{t}}{\overline{t^{\prime}}{ }_{q}^{\bar{\tau}_{p} \omega_{t}} \bar{e}_{q} \theta_{d}^{\bar{\nu}_{q} \theta_{t}} \bar{a}_{k} \theta_{d}^{\bar{\varepsilon}_{k} \theta_{t}} \rightarrow t^{\varepsilon \theta_{t}} \&} \quad \Pi^{\prime} \leadsto b \theta_{d}^{\varepsilon \theta_{t}} \rightarrow t^{\varepsilon \theta_{t}}\right)+(\mathbf{J N})
\end{aligned}
$$

where $t \neq \perp$ is some pattern, and

$$
\begin{aligned}
\Pi=( & \ldots \& \Delta_{i} \leadsto t_{i}^{\prime \tau_{i} \omega_{t}} \rightarrow t_{i} \omega_{d}^{\tau_{i} \omega_{t}} \ldots \& \ldots \Pi_{j} \leadsto e_{j} \theta_{d}^{\nu_{j} \theta_{t}} \rightarrow s_{j} \omega_{d}^{\lambda_{j} \omega_{t}} \& \\
& \left.\ldots \& \mathcal{M}_{0} \leadsto C^{\prime} \omega_{d}^{\text {bool }} \& \Pi^{\prime \prime} \leadsto r \omega_{d}^{\tau \omega_{t}} \bar{a}_{k} \theta_{d}^{\varepsilon_{k} \theta_{t}} \rightarrow t^{\varepsilon \theta_{t}}\right)+(\mathbf{O R})
\end{aligned}
$$

Since the previous proofs are type-annotated, the following type identities must hold: (b) $\bar{\lambda}_{q} \omega_{t}=\bar{\nu}_{q} \theta_{t}$, (c) $\tau \omega_{t}=\left(\bar{\varepsilon}_{k} \rightarrow \varepsilon\right) \theta_{t}$. Consider now the substitution $\theta^{\prime}=\left(\theta_{t}^{\prime}, \theta_{d}^{\prime}\right)$ such that

- $\theta_{t}^{\prime}=\omega_{t}\left[\operatorname{dom}\left(\omega_{t}\right)\right]$ and $\theta_{t}^{\prime}=\theta_{t}\left[\backslash \operatorname{dom}\left(\omega_{t}\right)\right]$.
- $\theta_{d}^{\prime}=\omega_{d}\left[\operatorname{dom}\left(\omega_{d}\right)\right]$ and $\theta_{d}^{\prime}=\theta_{d}\left[\backslash \operatorname{dom}\left(\omega_{d}\right)\right]$.

By construction, $\theta^{\prime} \approx_{e x} \theta$. Because of (b) and (c) $\theta_{t}^{\prime}$ is a unifier of $\bar{\nu}_{q} \rightarrow$ $\bar{\varepsilon}_{k} \rightarrow \varepsilon$ and $\bar{\lambda}_{q} \rightarrow \tau$. Moreover, $\theta_{t}^{\prime}=\theta_{t}\left[\operatorname{tvar}\left(\hat{S}_{t}\right)\right]$ implies $\theta_{t}^{\prime} \in \operatorname{TSol}\left(\hat{S}_{t}\right)$. Therefore, the dynamic type checking condition of GN succeeds and GN can be used to transform $G$ into $G^{\prime}$. To finish this case, we need a typeannotated $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$ witnessing $\left(R^{\prime}, \theta^{\prime}\right) \in \operatorname{TASol}\left(\hat{G}^{\prime}\right)$. Taking into account the construction of $\theta^{\prime}$, it is easy to check that the following $\mathcal{M}^{\prime}$ does the job: $\mathcal{M}^{\prime}={ }_{\text {def }}\left(\mathcal{M} \backslash\left\{\left\{\Pi_{0}\right\}\right\}\right) \uplus \mathcal{M}_{0} \uplus\left\{\left\{\Pi_{1}, \ldots, \Pi_{q}, \Pi^{\prime \prime \prime}\right\}\right\}$ where $\Pi^{\prime \prime \prime}=\left(\Pi^{\prime \prime} \& \Pi^{\prime}\right)$ $+(\mathbf{J N}) \sim r \omega_{d}^{\tau \omega_{t}} \bar{a}_{k} \theta_{d}^{\bar{\varepsilon}_{k} \theta_{t}} \asymp b \theta_{d}^{\varepsilon \theta_{t}}$.
1.3 Both $a$ and $b$ are flexible expressions. In this case we distinguish four subcases.
1.3.1 $a=X \bar{a}_{p}$ and $b=X \bar{b}_{q}$ where $a \theta_{d}$ (and thus $b \theta_{d}$ ) is a rigid and passive. This case can be handled by taking ID as TR.
1.3.2 $a$ and $b$ are two different variables, say $X$ and $Y$. This case can be handled by choosing TR as BD, with $k=0$ and $s=Y$. In this simple situation, $\mathbf{B D}$ needs no dynamic type checking.
1.3.3 $a=X \bar{a}_{p}$ and $b=Y \bar{b}_{q}$ where $X$ and $Y$ are different variables and $a \theta_{d}$, $b \theta_{d}$ are both rigid and passive. Without loss of generality, we can assume $p \geq q$. The witness must include a GORC proof of $(a \asymp b) \theta_{d}$. This is possible only if $X \theta_{d}$ and $Y \theta_{d}$ are patterns of the forms $h \bar{t}_{m-p}$ and $h \bar{s}_{m-q}$, respectively. Moreover, since $p \geq q$ implies $m-p \leq m-q$, the sequence $\bar{t}_{m-p}$ must coincide with the $m-p$ first patterns in the sequence $\bar{s}_{m-q}$. Moreover, the GORC proof of $(a \asymp b) \theta_{d}$ must end with a $\mathbf{J N}$ inference with two premises of the form $a \theta_{d} \rightarrow h \bar{t}_{m-p} \bar{u}_{p}$ and $b \theta_{d} \rightarrow h \bar{s}_{m-q} \bar{v}_{q}$ (where $h \bar{t}_{m-p} \bar{u}_{p}$ and $h \bar{s}_{m-q} \bar{v}_{q}$ are identical patterns), each of them proved by a DC inference. Taking all
these ideas into account, this case can be completed by choosing GD as TR and exploiting the type information included in $\mathcal{M}$. We omit the detailed reasoning, which would be somewhat similar to that of case 1.2.2
1.3.4 $a \theta_{d}$ is rigid and active. Let $X$ be the variable occurring as the head of $a$. As in case 1.2.3, $X \theta_{d}$ must be a pattern $f{\overline{t^{\prime}}}_{p}$ for some $f \in F S^{n}$ with $p \leq n$. Taking $q=n-p>0$, we can assume $a=X \bar{e}_{q} \bar{a}_{k}$ and $a \theta_{d}=f \bar{t}_{p}{ }_{p} \bar{e}_{q} \theta_{d} \bar{a}_{k} \theta_{d}$. Note that the assumption " $b$ rigid and passive" in case 1.2.3 has been actually not used in our proof for this case. Therefore, the same proof can be reused to complete the present case, choosing GN as TR.
$1.4 a$ is rigid and active expression. In this case, we can assume $a=f \bar{e}_{n} \bar{a}_{k}$ for some $f \in F S^{n}$ with $k \geq 0$. The GORC proof of $(a \asymp b) \theta_{d}$ included in $\mathcal{M}$ must involved an OR-inference using some type-annotated instance of a freshly renamed program rule $R l:\left(f \bar{t}_{n} \rightarrow r \Leftarrow C^{\prime} \square T^{\prime}\right) \in_{\text {var }} \mathcal{P}$, build with a well-typed substitution $\omega=\left(\omega_{t}, \omega_{d}\right)$. More precisely, the principal type annotation of $\hat{G}$ must include $f^{\bar{\nu}_{n} \rightarrow \bar{\varepsilon}_{k} \rightarrow \varepsilon} \bar{e}_{n}^{\bar{\nu}_{n}} \bar{a}_{k}^{\bar{\varepsilon}_{k}} \asymp b^{\varepsilon}$ while $\mathcal{M}$ must include a type-annotated GORC-proof

$$
\begin{aligned}
\Pi_{0}= & \left(\Pi \leadsto f^{\left(\bar{\nu}_{n} \rightarrow \bar{\varepsilon}_{k} \rightarrow \varepsilon\right) \theta_{t}} \bar{e}_{n} \theta_{d}^{\bar{\nu}_{n} \theta_{t}} \bar{a}_{k} \theta_{d}^{\bar{\varepsilon}_{k} \theta_{t}} \rightarrow t^{\varepsilon \theta_{t}} \& \Pi^{\prime} \leadsto b \theta_{d}^{\theta_{t}} \rightarrow t^{\varepsilon \theta_{t}}\right) \\
& +(\mathbf{J N})
\end{aligned}
$$

where $t \neq \perp$ is some pattern, and

$$
\begin{aligned}
& \Pi=\left(\ldots \& \Pi_{i} \leadsto e_{i} \theta_{d}^{\nu_{i} \theta_{t}} \rightarrow t_{i} \omega_{d}^{\tau_{i} \omega_{t}} \& \ldots \& \mathcal{M}_{0} \leadsto C^{\prime} \omega_{d}^{\text {bool }} \&\right. \\
&\left.\Pi^{\prime \prime} \leadsto r \omega_{d}^{\tau \omega_{t}} \bar{a}_{k} \theta_{d}^{\varepsilon_{k} \theta_{t}} \rightarrow t^{\varepsilon \theta_{t}}\right)+(\mathbf{O R})
\end{aligned}
$$

Note that $\Pi$ must be built using the $\omega$ instance of the principal type annotation of $R l$, which we assume to be $\left(f^{\bar{\tau}_{n} \rightarrow \tau} \bar{t}_{n}^{\bar{\tau}_{n}} \rightarrow r^{\tau} \Leftarrow C^{\prime \text { bool }}\right)$. Since $\Pi_{0}$ is a type-annotated proof, the type identity $\left(\bar{\tau}_{n} \rightarrow \tau\right) \omega_{t}=\left(\bar{\nu}_{n} \rightarrow \bar{\varepsilon}_{k} \rightarrow \varepsilon\right) \theta_{t}$ must hold. The rest of this case can be completed by choosing NR1 as TR. The proof details are similar to those of case 1.2.3, but easier. In particular, no dynamic type checking is needed.
2 Now we assume that $G$ satisfies the condition $\neg \mathbf{I} \wedge \mathbf{I I}$, where
There is some $(e \rightarrow t) \in P$ such that $t \notin D V a r$.
Note that $\neg \mathbf{I}$ can be rewritten as:
For all $(a \asymp b) \in C$, either $a$ or $b$ is headed by a produced variable.

Choose any $(e \rightarrow t) \in P$ such that $t$ is not a variable, and continue the case analysis as follows:
$2.1 e$ is a rigid and passive expression. Note that $e$ and $t$ must have the forms $h \bar{e}_{n}$ and $h \bar{t}_{n}$, respectively. Otherwise, $(e \rightarrow t) \theta_{d}$ could have no GORC proof. The rest of this case can be completed by taking DC2 as TR, by a reasoning similar to that of case 1.1.
$2.2 e$ is a rigid and active expression. This case can be proved using NR2 as TR. Note that NR2 can be applied because $t$ is not a variable. The proof details are similar to those of case 1.4.
$2.3 e$ is flexible, but $e \theta_{d}$ is rigid and passive. In this case we can assume $(e \rightarrow t)=\left(X \bar{e}_{k} \rightarrow h \bar{t}_{m} \bar{s}_{k}\right)$ and $X \theta_{d}=h \bar{t}_{m}$. Since $\theta_{d}$ is a solution of $(e \rightarrow t)$, we can also assume $h \bar{t}^{\prime}{ }_{m} \sqsupseteq h \bar{t}_{m} \theta_{d}$. To continue our reasoning, we choose OB as TR. The principal type annotation of $\hat{G}$ must include

$$
X^{\bar{\nu}_{k} \rightarrow \nu} \bar{e}_{k}^{\bar{\nu}_{k}} \rightarrow h^{\bar{\mu}_{m} \rightarrow \bar{\nu}_{k} \rightarrow \nu} \bar{t}_{m}^{\bar{\mu}_{m}}{\overline{\bar{s}_{k}^{\nu^{\prime}} k}}^{\text {m}}
$$

and $\mathcal{M}$ must include a type-annotated GORC-proof

$$
\begin{aligned}
& \Pi_{0}=\left(\ldots \& \Delta_{i} \leadsto t_{i}^{\prime \mu_{i}^{\prime}} \rightarrow t_{i} \theta_{d}^{\mu_{i} \theta_{t}} \ldots \& \ldots \Pi_{j} \leadsto e_{j} \theta_{d}^{\nu_{j} \theta_{t}} \rightarrow s_{j} \theta_{d}^{\nu_{j}^{\prime} \theta_{t}} \& \ldots\right) \\
& +(\mathbf{D C}) \leadsto\left(h^{\bar{\mu}_{m}^{\prime}} \rightarrow\left(\bar{\nu}_{k} \rightarrow \nu\right) \theta_{t}\right. \\
& \left.\bar{t}_{m}^{\mu^{\prime}}{ }_{m} \bar{e}_{k} \theta_{d}^{\bar{\nu}_{k} \theta_{t}} \rightarrow h^{\left(\bar{\mu}_{m} \rightarrow \bar{\nu}^{\prime}{ }_{k} \rightarrow \nu\right) \theta_{t}} \bar{t}_{m} \theta_{d}^{\bar{\mu}_{m} \theta_{t}} \bar{s}_{k} \theta_{d}^{\overline{\nu_{k}^{\prime}} \theta_{t}}\right)
\end{aligned}
$$

In the formulation of OB we find $\tau^{\prime}=\hat{T}(X)$ and $h:: \bar{\tau}_{m} \rightarrow \tau$ as fresh variant of $h$ 's principal type. Since the type annotations in $\Pi_{0}$ must be consistent, the following type identities must hold for some $\rho_{t} \in T S u b$ :
(a) $\overline{\mu^{\prime}}{ }_{m} \rightarrow\left(\bar{\nu}_{k} \rightarrow \nu\right) \theta_{t}=\left(\bar{\mu}_{m} \rightarrow{\overline{\nu^{\prime}}}_{k} \rightarrow \nu\right) \theta_{t}$.
(b) $\bar{\mu}_{m} \rightarrow{\overline{\nu^{\prime}}}_{k} \rightarrow \nu=\left(\bar{\tau}_{m} \rightarrow \tau\right) \rho_{t}$.

Consider $\theta_{t}^{\prime} \in T S u b$ defined so that $\theta_{t}^{\prime}=\rho_{t}\left[\operatorname{tvar}\left(\bar{\tau}_{m} \rightarrow \tau\right)\right]$ and $\theta_{t}^{\prime}=$ $\theta_{t}\left[\backslash \operatorname{tvar}\left(\bar{\tau}_{m} \rightarrow \tau\right)\right]$. Because of (a) and (b), $\theta_{t}^{\prime}$ is a unifier of $\tau^{\prime}=\hat{T}(X)=$ $\bar{\nu}_{k} \rightarrow \nu$ and $\tau$. Moreover, $\theta_{t}^{\prime} \in \operatorname{Sol}\left(\hat{S}_{t}\right)$, because $\theta_{t}^{\prime}=\theta_{t}\left[\operatorname{tvar}\left(\hat{S}_{t}\right)\right]$. Hence, $\theta_{t}^{\prime}$ is a solution of ( $\hat{S}_{t}, \tau \approx \tau^{\prime}$ ), the dynamic type checking condition of OB succeeds, and OB can be applied to transform $G$ into $G^{\prime}$.

We still have to build $\theta^{\prime} \approx_{e x} \theta$ such that $\left(R^{\prime}, \theta^{\prime}\right) \in \operatorname{TASol}\left(\hat{G}^{\prime}\right)$ with some type-annotated witness $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$. In particular, for $\theta_{d}^{\prime}$ to be a solution of $X \approx h \bar{t}_{m}$, the identity $X \theta_{d}^{\prime}=h \bar{t}_{m} \theta_{d}^{\prime}$ should hold. For $\theta_{d}$, however, we
only know $X \theta_{d}=h \bar{t}^{\prime}{ }_{m} \sqsupseteq h \bar{t}_{m} \theta_{d}$. Therefore, we are going to define $\theta_{d}^{\prime}$ as a modification of $\theta_{d}$ acting differently over $\operatorname{var}\left(h \bar{t}_{m}\right)$. Thanks to the condition EX of admissible goals, $\operatorname{var}\left(h \bar{t}_{m}\right)$ consists of existential variables, which ensures $\theta_{d}^{\prime} \approx_{e x} \theta_{d}$.

To build $\theta_{d}^{\prime}$, assume $\operatorname{var}\left(h \bar{t}_{m}\right)=\left\{Y_{1}, \ldots, Y_{p}\right\}$. Since $h \bar{t}_{m}$ is linear, each $Y_{j}$ has exactly one occurrence at one position in $h \bar{t}_{m}$. Let $u_{j}$ be the subpattern which occurs at the same position in $h \bar{t}_{m} \theta_{d}^{\prime}$ and let $u_{j}^{\prime}$ be the subpattern which occurs at the same position in $h \overline{t^{\prime}}{ }_{m}$. Note that $h \overline{t^{\prime}}{ }_{m} \sqsupseteq h \bar{t}_{m} \theta_{d}$ implies $u_{j}^{\prime} \sqsupseteq u_{j}$ for all $1 \leq j \leq p$. Define $\theta_{d}^{\prime} \in D S u b_{\perp}$ such that $Y_{j} \theta_{d}^{\prime}=u_{j}^{\prime}$, $1 \leq j \leq p$ and $\theta_{d}^{\prime}=\theta_{d}\left[\backslash\left\{Y_{1}, \ldots, Y_{p}\right\}\right]$. In particular, $X \theta_{d}^{\prime}=X \theta_{d}=h \bar{t}^{\prime}{ }_{m}$, because $X \notin \operatorname{var}\left(h \bar{t}_{m}\right)$ due to the NC condition of admissible goals. Hence, $X \theta_{d}^{\prime}=h \bar{t}^{\prime}{ }_{m}=h \bar{t}_{m} \theta_{d}^{\prime}$.

Finally, regarding the witness $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$ of $\left(R, \theta^{\prime}\right) \in \operatorname{TASol}\left(\hat{G}^{\prime}\right)$, let us consider $\mathcal{M}^{\prime}{ }_{0}={ }_{\text {def }}\left(\mathcal{M} \backslash\left\{\left\{\Pi_{0}\right\}\right\}\right) \uplus\left\{\left\{\Pi_{1}, \ldots, \Pi_{k}\right\}\right\}$ which is easily seen to serve as a type-annotated witness for the principal type annotation of $\hat{G}^{\prime}$ affected by $\left(\theta_{t}^{\prime}, \theta_{d}\right)$. By applying Lemma 8 (item 3 ), $\mathcal{M}_{0}^{\prime}$ can be transformed into another witness $\mathcal{M}^{\prime}$ with the same structure for the principal type annotation of $\hat{G}^{\prime}$ affected by $\left(\theta_{t}^{\prime}, \theta_{d}^{\prime}\right)$. Note that Lemma 8 says nothing about type annotations, but this is not a problem, because $\mathcal{M}^{\prime}$ and $\mathcal{M}_{0}^{\prime}$ are the same, except that certain occurrences of $u_{j}$ in $\mathcal{M}_{0}^{\prime}$ are replaced by occurrences of $u_{j}^{\prime}$ in $\mathcal{M}^{\prime}$, which can inherit the type annotations of $u_{j}^{\prime}$ as a subpattern of $h \bar{t}^{\prime}{ }_{m}$.
$2.4 e$ is flexible, but $e \theta_{d}$ is rigid and active. This case can be proved by using OGN as TR. Note that OGN can be applied because $t$ is not a variable. The proof details are similar to those of case 1.2.3.

3 Now we assume that $G$ satisfies the condition $\neg \mathbf{I} \wedge \neg \mathbf{I I} \wedge \mathbf{I I I}$, where $\neg \mathbf{I I}$ can be rewritten as:

$$
P \text { includes only statements }(e \rightarrow X) \text { with } X \in D \operatorname{Var}
$$

and
There is some $(t \rightarrow X) \in P$, such that $t$ is a pattern.
This case is easy to prove taking IB as TR.
4 Assume now that $G$ satisfies the condition $\neg \mathbf{I} \wedge \neg \mathbf{I I} \wedge \neg \mathbf{I I I} \wedge \mathbf{I V}$, where

$$
C \neq \emptyset .
$$

Because of $\mathbf{I V}$ and $\neg \mathbf{I}$, we can choose some $(a \asymp b) \in C$ such that $a$ is headed by a produced variable $Y$. Since $Y$ is produced and $\neg \mathbf{I I} \wedge \neg \mathbf{I I I}$ hold, $(e \rightarrow Y) \in P$ for some expression $e$ which is not a pattern. Moreover, $Y$ is demanded because it occurs as the head of $a$ in $(a \asymp b) \in C$. We distinguish four subcases according to the form of $e$ and $e \theta_{d}$.
$4.1 e$ is rigid and passive. This case can be proved by taking IIM as TR. The reasoning is similar to that of case $\mathbf{1 . 2 . 2}$ (with $k=0$ ), but simpler. In particular, no dynamic type checking is needed.
$4.2 e$ is rigid and active. In this case we can choose NR2 as TR. Note that NR2 can be applied because $Y$ is demanded. The proof details are similar to case 1.4.
$4.3 e$ is flexible, but $e \theta_{d}$ is rigid and passive. Since $e$ is not a pattern, we can assume $e=X \bar{e}_{q}$ with $q>0$. Since $\theta_{d}$ is solution of $e \theta_{d}, X \theta_{d}$ and $Y \theta_{d}$ must be patterns of the form $h{\overline{t^{\prime}}}_{p}$ and $h{\overline{t^{\prime}}}_{p} \bar{s}_{q}$, respectively, and $\mathcal{M}$ must include a GORC proof of $h \overline{t^{\prime}}{ }_{p} \bar{e}_{q} \theta_{d} \rightarrow h \overline{t^{\prime}} \bar{p}_{q}$ ending with a DC step. The rest of this case can be completed by taking OGD as TR.
$4.4 e$ is flexible, but $e \theta_{d}$ is rigid and active. This case quite similar to case 2.4. It can be proved by using OGN as TR. Note that OGN can be applied because $Y$ is a demanded variable.
$\mathbf{5}$ Finally, assume that $G$ satisfies the condition $\neg \mathbf{I} \wedge \neg \mathbf{I I} \wedge \neg \mathbf{I I I} \wedge \neg \mathbf{I V}$. Since $G$ is not solved and IV is false, $C=\emptyset$ and $P \neq \emptyset$. Due to the acyclicity condition NC of admissible goals, $P$ must contain some statement $(e \rightarrow t)$ such that $\operatorname{var}(t) \cap \operatorname{var}\left(e^{\prime}\right)=\emptyset$ for all $\left(e^{\prime} \rightarrow t^{\prime}\right) \in P$. Due to $\neg \mathbf{I I}, t$ must be a single variable $X$. Because of $C=\emptyset$ and the linearity condition $\mathbf{L N}$ of admissible goals, $X$ has exactly one occurrence in $G$. Then $\mathbf{E L}$ can be applied to transform $G$ into $G^{\prime}$, and a type-annotated witness $\mathcal{M}^{\prime} \triangleleft \mathcal{M}$ for $\left(R, \theta^{\prime}\right) \in \operatorname{TASol}\left(\hat{G^{\prime}}\right)$ can be obtained from $\mathcal{M}$ by removing the typeannotated proof of $(e \rightarrow X) \theta_{d}$.


[^0]:    *This research has been partially supported by the Spanish National Project TIC98-0445-C03-02 "TREND" and the Esprit BRA Working Group EP-22457 "CCLII". A preliminary version of the paper, much shorter and including no proofs, was published as [20].

